

# Experience from the EIRENE OpenMP parallelization and refactoring *and some general thoughts*

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# Objectives of EIRENE 'core segregation'

- **Ring-fence parts of the code (as small as possible) which needs to be optimized, increasing readability & maintainability, clarity in order to:**
  - ❑ Help improve the efficiency per core (identify and reduce main hotspots, allow better optimization by the compiler by e.g. reducing branching, improving structure, possibly changing tally structure ....)
  - ❑ Enable large grids by domain decomposition (possibly on a reduced set of geometries)

Note : keep in mind that some aspect of pre-processing (Collisional Radiative model in each cell may become substantial in terms of computing time)

# First attempt to define a 'core'

- **The part which performs particle tracing and tally scoring**
- Located into `eirmod_mcarlo.f`, ~ 50 lines with 5 `gotos` (see next slide, would benefit from a - very careful - rewrite)

On the left – follow a particle, on the right follow any secondary particle (sputtered atoms, ...)

```

C.....
C NEXT MONTE CARLO HISTORY
C
c LAUNCH A NEW PARTICLE NOW
C.....
      XMCP(ISTRA)=XMCP(ISTRA)+1.
      NPANU=NPANU+1

      IPANU=IPANU+1
      ITRJ = NCHORI + MOD(IPANU,NTRJ) + 1
      NLEVEL=0
      CALL EIRENE_LOCAT1(IPANU)

C IS BIRTH PROCESS SURVIVED?
      IF (.NOT.LGPART) GOTO 110
C
102  CONTINUE
C FOLLOW NEUTRAL PARTICLE
      IF (ITYP.EQ.0.OR.ITYP.EQ.1.OR.ITYP.EQ.2) THEN
        CALL EIRENE_FOLNEUT
C FOLLOW TEST ION
      ELSEIF (ITYP.EQ.3) THEN
        CALL EIRENE_FOLION
      ENDIF
C NEXT GENERATION ?
      IF (LGPART) GOTO 102
C
110  CONTINUE

      IF (NLRAY(ISTRA)) THEN
        CALL EIRENE_CLEAR_TRAJECTORY (ITRJ)
      END IF

```

```

C NUMBER OF REMAINING NODES AND NUMBER OF LEVELS AT NEXT
NODE
      IF (NLEVEL.GT.0) THEN
104  INODES=NODES(NLEVEL)-1
        NODES(NLEVEL)=INODES
        IF(INODES.LE.0) GOTO 103
C RESTORE VARIABLES AND START NEW TRACK
      DO 105 J=1,NPARTC
        RPST(J)=RSPLST(J,NLEVEL)
105  CONTINUE
      DO 106 J=1,MPARTC
        IPST(J)=ISPLST(J,NLEVEL)
106  CONTINUE
        ITYP=ISPEZI(ISPZ,-1)
        IPHOT=ISPEZI(ISPZ,0)
        IATM=ISPEZI(ISPZ,1)
        IMOL=ISPEZI(ISPZ,2)
        IION=ISPEZI(ISPZ,3)
        IPLS=ISPEZI(ISPZ,4)
        CALL EIRENE_NCELLN(NCELL,NRCELL,NPCELL,NTCELL,NACELL,
          NBLOCK,NR1ST,NP2ND,NT3RD,NBMLT,NLRAD,NLPOL,NLTOR)
        NBLCKA=NSTRD*(NBLOCK-1)+NACELL
NLSRFX=MRSURF.GT.0
        NLSRFY=MPSURF.GT.0
        NLSRFZ=MTSURF.GT.0
        NLSRFA=MASURF.GT.0
        IF (NLTRC) CALL EIRENE_CHCTRC(X0,Y0,Z0,0,12)

! PARTICLE TYPE AND SPECIES MAY HAVE CHANGED
! PREPARE POINTER FOR UNIFIED SUBROUTINES FPATH, UPDATE,
ETC.
        CALL EIRENE_SWITCH_PARTINFO

        IC_NEUT=0
        IC_ION=0
        GOTO 102
C RETURN TO PREVIOUS LEVEL
103  CONTINUE
        NLEVEL=NLEVEL-1
        IF(NLEVEL.GT.0) GOTO 104
      ENDIF
C HISTORY HAS ENDED

```

# First attempts to define a 'core'

- However these 50 lines have calls to routines in [particle-tracing/](#),
- ❑ which then call routines in [surface-processes/](#), [volume\\_processes/](#), [scoring/](#) folders; with several associated modules in [modules/](#)
- ❑ In the 4 folders above :  $18594+12718+12718 + 4339 = 48369$  lines ~ 33%  
(Total lines in the code (develop\_openmp) = 136996 lines)
- ❑ order of magnitude estimate but shows the current complexity/size of the routines performing the core functions ...

**How to reduce the amount of code to deal with ?**

Limit strictly to moving particles within the grid : fol\*.f, eirmod\_time\*.f ??

# Possible ways towards simplification

- In *fol\**, *time\** routines, several (5-10) *select case* or *if/elseif* or *gotos* structures on the geometry option (LEV GEO)

LEV GEO=1-5 ; 10 (7 options, 2 used in coupled cases 4 = triangles and 10 for EMC3)

- **find an intelligent way to disentangle this (+ focus on the most relevant options for optimizing ?)**  
(NB : the code is specific to each options)

**use an OOP approach as nicely illustrated by Jorge ?**

- in *fpath.f*, lots of branching on MODCOL array (defining how various rates are calculated to obtain mean free paths) – **same thing, can we cleverly disetangle this ? OOP ?**
- *update.f* : lots of 'if' to check if tallies active or not at every call
- 'Streamlining' these routines
  - should make the code more readable
  - may also help enable further compiler optimization of the code

(is this really true with OOP ? (Strongly dependant on array of structures vs structures of array performances for instance ?)

# Experience from OpenMP parallelization

- Use the routines where `#!OMP pragmas` are used as an alternative indication of how many routines may actually be called during particle tracing – depends of course on input parameters
  - > `55 routines` (mostly in the folders discussed previously + some others scattered around, some re-ordering might be in line)
- Most of the time is spent in routine `update.f`, to score tallies.
  - Scoring after trajectories may improve things substantially (for OpenMP but also more more generally)
  - Area where optimization could play a large role on single core performance also

# Some general thoughts in conclusion

- Given the time frame and resources of the project an **incremental approach** is the only way to reach deliverables – this rules out
  - changing coding language (C++)
  - full rewriting of the ‘core’ – the later, based on particle tracing + scoring, is still laaaarge (in spite of the fact that a full rewrite *could* bring large benefits on the long term).
- **OOP fortran features** (modules, derived types & interfaces) already there in bits and pieces, build gradually on these good programming practices. Jorge’s work nicely shows how this can be used in practice.
- ‘User routines’ are where users will first be exposed to fortran and inner workings to implement specific features (standalone or coupled)  
**no straightforward way this can be easily replaced by scripts.**  
The **preprocessor is already written in fortran**, doing it again with scripts will take a lot of resources.