Reimagining the flux tube for the tokamak edge



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Outline

J. Ball and S. Brunner. PPCF (2021).

- 1. The non-twisting flux tube
- 2. Further generalizations beyond the non-twisting flux tube
- 3. Including non-uniform magnetic shear in a flux tube

The non-twisting flux tube





Summarizing the non-twisting flux tube

J. Ball and S. Brunner. PPCF (2021).

- The non-twisting flux tube is created by laying down a rectangular grid $K_x = k_x + k_y \frac{\nabla x \cdot \nabla y}{|\nabla x|^2}$, instead k_x
- Prioritizes including Fourier modes with minimal FLR damping, instead of prioritizing following linear modes
- Nothing physical has changed





Non-twisting flux tube is a different set of gridpoints J. Ball and S. Brunner. PPCF (2021).

- Boundary conditions determine an infinite lattice of allowed Fourier modes according to either $k_x = \frac{2\pi}{L_x}m$ or $K_x = \frac{2\pi}{L_x}m + k_y \frac{\nabla x \cdot \nabla y}{|\nabla x|^2}$ where $m \in \mathbb{Z}$
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Conventional

Non-twisting







Takeaways from runtime tests

Parisi et al. In prep. (2021).

- Most helpful for multiple regions of turbulent drive, e.g. tokamaks with $N_{pol} > 1$, <u>H-mode pedestals</u>, stellarators
- Prioritizes including Fourier modes with minimal FLR damping
- Not harmful



Generalizations of the non-twisting flux tube



Boundary conditions define allowed Fourier modes





Can choose points freely with different transformations





EPFL



Can choose points freely with different transformations







Can choose points freely with different transformations

Completely control twist with *z*







Limitations on generalization of the flux tube

Ball et al. *PPCF* (2021).

- Practical limitations due to terms that cause mode coupling:
 - Nonlinear term need evenly-spaced grid for efficient calculation in real space
- Potential to greatly benefit multi-scale simulations or pedestal simulations with weird turbulence?

Flux tubes with non-uniform magnetic shear



Consistency with gyrokinetic orderings

- Turbulence-scale variation (~10 ρ_i) in the \hat{s} profile can be created by:
 - 1. ECCD can provide a localized current source and the q profile evolves on the very slow resistive diffusion timescale
 - 2. The bootstrap current in the pedestal
- Order this source $\tilde{S}_{Ip} \sim \nu \rho_* \omega F_s$ such that it appears in the GK equation, but then perform a subsidiary expansion in $\nu \ll 1$ to make the resistive diffusion timescale of the source asymptotically slow
- Thus, \hat{s} within the flux tube can be considered fixed in the GK calc.





How to include non-uniform magnetic shear

• Instead of just the standard linear dependence $\hat{s}x$, we want to add

$$\tilde{s}(x) = \sum_{j=1}^{j_m} \tilde{s}_{Cj} \cos\left(2\pi j x/L_x\right) + \tilde{s}_{Sj} \sin\left(2\pi j x/L_x\right)$$

- 1. In the non-twisting derivation, magnetic shear only appears in the parallel streaming term, so simply replace $\hat{s}x \rightarrow \hat{s}x + \tilde{s}(x)$
- 2. Include a steady, external $A_{||}^{ext}(x, z)$ perturbation arising from the resistive diffusion timescale equations
- 3. Use standard coordinate $y|_{\tilde{s}(x)=0}$ without new shear variation, causing the $\hat{b} \cdot \nabla y|_{\tilde{s}(x)=0}$ term to persist in parallel streaming





Implementation in GENE

• Surprisingly simple form in Fourier-space

$$\frac{\partial h_s}{\partial z} \bigg|_{k_x, k_y} \to \frac{\partial h_s}{\partial z} \bigg|_{k_x, k_y} + \frac{k_y}{2} \sum_{j=1}^{j_m} \frac{L_x}{2\pi j} \left[\left(\tilde{s}_{Cj} + i \tilde{s}_{Sj} \right) h_s \left(K_x + \frac{2\pi}{L_x} j, k_y, z \right) - \left(\tilde{s}_{Cj} - i \tilde{s}_{Sj} \right) h_s \left(K_x - \frac{2\pi}{L_x} j, k_y, z \right) \right] + \dots$$

• Straightforward to implement, likely at little computational cost





First proof-of-principle simulations



18



Moves integer surfaces of flux tube as expected



19





Temperature profile modified, but not as expected



All done.

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Motivation for the flux tube

Beer et al. Phys. Plasmas (1995).

- Crucial to minimize computational cost as much as possible
- Flux tube simulation domain exploits the scale separation assumed by gyrokinetics, $\rho_i/a \ll 1$
- Field-aligned coordinates minimize the volume of the simulation domain by reflecting the shape of turbulence
- Boundary conditions are elegant (i.e. periodicity)







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 Field-aligned coord
 What's the volume of the sime by reflecting ++ Flux tube simulation domain

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 ${\mathcal X}$





Motivation for the flux tube

Beer et al. Phys. Plasmas (1995).

 $\hat{s} \rightarrow 2\hat{s}$

 $q(x) \approx q_0 \left(\begin{array}{c} 1 + \hat{s} \frac{x - x_0}{x_0} \end{array} \right)$

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Motivation for a non-twisting flux tube



- When $2\pi N_{pol}\hat{s} \gg 1$, the conventional flux tube becomes so twisted that it only supports modes that are strongly damped by FLR effects
- "Shifted metric" approach has been developed, but could not be applied to the standard flux tube domain (i.e. periodic radial boundary condition and with a Fourier representation)
- In this talk, we will show how it can be done





Coordinate system transformation

Scott et al. Phys. Plasmas (2001).



• Define a new coordinate *Y* such that $\nabla x \cdot \nabla Y = 0$, so use

$$Y(x, y, z) \equiv y - \frac{\nabla x \cdot \nabla y}{|\nabla x|^2} x$$





Coordinate system transformation

Ball et al. PPCF (2021).

 Key new insight is to transform the boundary conditions consistently and then use them to find the allowed modes in Fourier-space

• Instead of the typical
$$k_x = \frac{2\pi}{L_x}m$$
, we find

$$K_{x} = \frac{2\pi}{L_{x}}m + k_{y}\frac{\nabla x \cdot \nabla y}{|\nabla x|^{2}} \text{ where } m \in \mathbb{Z}$$

• To make non-twisting flux tube in Fourier-space, **construct a** rectangular grid in K_x instead of k_x





Physical meanings of k_x and K_x



If you trace the perturbation back along field lines to z = 0, has no variation in ∇x

Has no variation in ∇x at all *z* locations





Transforming the Fourier-analyzed gyrokinetic eq.

$$\frac{\partial h_s}{\partial t} + w_{||} \hat{b} \cdot \nabla z \frac{\partial h_s}{\partial z} \bigg|_{K_x - k_y \frac{\nabla x \cdot \nabla y}{|\nabla x|^2}} + i \overrightarrow{v}_{ds} \cdot \left(K_x \nabla x + k_y \nabla Y\right) h_s + a_{s||} \frac{\partial h_s}{\partial w_{||}} + \left\{h'_s, \phi'' J_0\left(K''_{\perp} \rho_s\right)\right\} = \frac{Z_s e F_{Ms}}{T_s} \frac{\partial \phi}{\partial t} J_0\left(K_{\perp} \rho_s\right) - i \frac{k_y}{JB} \phi J_0\left(K_{\perp} \rho_s\right) \frac{dF_{Ms}}{dx}$$

1. The parallel derivative must still be taken at constant $k_x = K_x - k_y \frac{\nabla x \cdot \nabla y}{|\nabla x|^2}$

2. The geometric coefficients lose their secular dependence along the field line:

$$k_{\perp} = \sqrt{k_x^2 |\nabla x|^2 + 2k_x k_y \nabla x \cdot \nabla y + k_y^2 |\nabla y|^2} \rightarrow K_{\perp} = \sqrt{K_x^2 |\nabla x|^2 + k_y^2 |\nabla Y|^2}$$

$$\propto \hat{s}z \qquad \propto (\hat{s}z)^2$$

Conventional grid prioritizes following linear modes, while non-twisting grid minimizes FLR damping





CBC with adiabatic electrons and $\hat{s} = 0.8$

Dimits et al. Phys. Plasmas (2000).



Similar convergence and run time





CBC with adiabatic electrons, $\hat{s} = 0.8$, $N_{\text{pol}} = 3$



• Time step is much larger due to elimination of small radial scales



New choice of gridpoints can better fit turbulence

Dimits et al. Phys. Plasmas (2000).

Cyclone base case in a domain that is three poloidal turns long







CBC with adiabatic electrons, $\hat{s} = 0.8$, $N_{\text{pol}} = 3$



• Non-twisting $N_x = 128$ sim. is **7x** faster than conventional $N_x = 256$





Shaped DEMO with kinetic elec., $\hat{s} = 2.4$, $N_{\text{pol}} = 1$



Inboard is better resolved by non-twisting flux tube, but little flux there





CBC with adiabatic electrons, $\hat{s} = 4.0$, $N_{\text{pol}} = 3$



Non-twisting flux tube is >30x faster than conventional





Transforming real space boundary conditions

Beer et al. Phys. Plasmas (1995).

• Using $Y(x, y, z) = y + \hat{s}zx$, the binormal boundary condition stays boring

 $\phi(x, Y(x, y + L_y, z), z) = \phi(x, Y(x, y, z), z) \implies \phi(x, Y + L_y, z) = \phi(x, Y, z)$

The radial boundary condition becomes interesting

 $\phi(x + L_x, Y(x + L_x, y, z), z) = \phi(x, Y(x, y, z), z) \quad \Rightarrow \quad \phi(x + L_x, Y + \hat{s}zL_x, z) = \phi(x, Y, z)$

• Using $Y(x, \zeta, z) = C_y \zeta - C_y q_0 z$, the parallel "twist-and-shift" boundary condition **becomes boring**

$$\begin{aligned} \phi(x, Y(x, \zeta, z + 2\pi N_{pol}), z + 2\pi N_{pol}) &= \phi(x, Y(x, \zeta, z), z) \\ \Rightarrow \quad \phi(x, Y, z + 2\pi N_{pol}) &= \phi(x, Y, z) \end{aligned}$$





Transforming radial Fourier-space boundary cond.

• Substituting $\overline{\phi}(x, Y, z) = \sum_{k_y} \hat{\phi}(x, k_y, z) e^{ik_y Y}$ from the binormal boundary condition,

$$\overline{\phi}(x+L_x,Y+\hat{s}zL_x,z) = \overline{\phi}(x,Y,z) \quad \Rightarrow \quad \hat{\phi}(x+L_x,k_y,z)e^{ik_y\hat{s}zL_x} = \hat{\phi}(x,k_y,z)$$

• By Floquet's theorem, substitute $\hat{\phi}(x, k_y, z) = P(x, k_y, z)e^{-ik_y\hat{s}zx}$ to find

$$P(x + L_x, k_y, z) = P(x, k_y, z)$$

• Thus, $P(x, k_y, z)$ has a standard Fourier form/discretization in x, implying that

$$K_x = \frac{2\pi}{L_x}m - k_y \hat{s}z \quad \text{where} \quad m \in \mathbb{Z} \quad \text{and} \quad \overline{\phi}(x, Y, z) = \sum_{K_x, k_y} \phi(K_x, k_y, z)e^{iK_x x + ik_y Y}$$





Transforming the gyrokinetic equation

• Fourier analyzing using $\overline{h}_s(x, Y, z) = \sum h_s(K_x, k_y, z)e^{iK_x x + ik_y Y}$ gives

$$\frac{\partial h_s}{\partial t} + \frac{w_{||}\hat{b} \cdot \nabla z}{L_x L_y} \oint \oint dx dY e^{-iK_x x - ik_y Y} \frac{\partial}{\partial z} \bigg|_{x,y} \bigg(\sum_{K'_x, k'_y} h_s(K'_x, k'_y, z) e^{iK'_x x + ik'_y Y} \bigg) + i \vec{K}_\perp \cdot \vec{v}_{ds} h_s + \dots$$

 K_x, k_v

• Substituting $Y = y + \hat{s}zx$ allows you to Fourier analyze in y,

$$\frac{\partial h_s}{\partial t} + \frac{w_{||}\hat{b} \cdot \nabla z}{L_x} \oint dx e^{-i(K_x + k_y \hat{s}z)x} \frac{\partial}{\partial z} \bigg|_{x,k_y} \left(\sum_{K'_x} h_s(K'_x, k_y, z) e^{i(K'_x + k_y \hat{s}z)x} \right) + i \vec{K}_\perp \cdot \vec{v}_{ds} h_s + \dots$$

• Calculate parallel deriv. in (x, k_y) or by holding $k_x = K_x + k_y \hat{s}z$ constant





Shaped DEMO with kinetic elec., $\hat{s} = 2.4$, $N_{\text{pol}} = 1$



• Time step is now limited by shear Alfvén wave, even when $\beta \neq 0$





CBC with adiabatic electrons and $\hat{s} = 4.0$



Significant, direct computational speed-up





CBC with adiabatic electrons and $\hat{s} = 4.0$



Inboard is better resolved by non-twisting flux tube, but little flux there





Alternative twisting flux tubes

Watanabe et al. Phys. Plasmas (2015).

It is straightforward to completely control the flux tube twist using

$$Y(x, y, z) = y + f_{tw}(z)x$$
 and $K_x \equiv k_x - k_y f_{tw}(z)$

whereConventional: $f_{tw}(z) = 0$ Globally non-twisting: $f_{tw}(z) = \hat{s}z$ Non-twisting: $f_{tw}(z) = -\nabla x \cdot \nabla y / |\nabla x|^2$ Flux tube train: $f_{tw}(z) = 2\pi \hat{s} \text{Round}[z/(2\pi)]$



Alternative twisting flux tubes

- Potential applications
 - Coarsen grid at intermediate scales in multiscale simulations
 - Better adapt grids to local conditions in z
 - Prevent linear modes from being clustered around zero ballooning angle in conventional flux tube
 - Better optimize the twist of the flux tube cross-section