



# Improved collision operator for full-f HAGIS simulations

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- **TSVV1 sub project D2.3, D2.7:**

**Use HAGIS as a full-f code with non-linear collision model  
for calculating the bootstrap current in the pedestal**

- **D2.3: First version of full-f HAGIS code available, due: 12/2022**

Full-f code with linearized collision operator - ready in 2021

Full-f code with improved (non-linear) collision operator - this talk

- **M2.11: Extend delta-f neoclassical studies with HAGIS to full-f, due: 12/2022**

- **D2.7: Neoclassical bootstrap current studies with full-f HAGIS code**

in support of GK studies, due: 6/2024

- HAGIS: integration of equations of motion in Boozer coordinates, variable time steps
- **Full-f: all particle have the same fixed weight**

Number of particles in real space grid cell is proportional to the volume

- **Full-f: particles are created with a Maxwellian velocity distribution**  
(with a finite flow velocity for shortening the transient phase)
- Separate simulations for ions and electrons as before
- Linearized Coulomb collision operator
  - Each particle collides with a Maxwellian distribution with the same flow velocity and temperature as the actual distribution function (in moving frame)**
- Full-f code requires for low noise much more num. particles than delta-f code, particularly for electrons (flow velocity  $\ll$  ion thermal velocity)

**Collisions of particles of species  $a$  by particles of species  $b$ :**

$$C_{ab}(f_a, f_b) = -\nu_{ab0} \frac{v_{T_a}^3}{n_b} \nabla \mathbf{v} \cdot \left[ \left(1 + \frac{m_a}{m_b}\right) f_a(\mathbf{v}) \nabla \mathbf{v} H_b(\mathbf{v}) - \frac{1}{2} \nabla \mathbf{v} \cdot (f_a(\mathbf{v}) \nabla \mathbf{v} \nabla \mathbf{v} G_b(\mathbf{v})) \right]$$

Rosenbluth potentials:

$$G_b(\mathbf{v}) = \int f_b(\mathbf{w}) |\mathbf{v} - \mathbf{w}| d^3 w \quad H_b(\mathbf{v}) = \int \frac{f_b(\mathbf{w})}{|\mathbf{v} - \mathbf{w}|} d^3 w \quad \nu_{ab0} = \frac{Z_a^2 Z_b^2 e^4 n_b \ln \Lambda_{ab}}{4\pi \varepsilon_0^2 m_a^2 v_{T_a}^3}$$
$$\Delta H_b(\mathbf{v}) = -4\pi f_b(\mathbf{v}) \quad \Delta G_b(\mathbf{v}) = 2H_b(\mathbf{v})$$

For collisions within a species,  $C_{aa}$  is a nonlinear operator for  $f_a$

**Calculating the Rosenbluth potentials numerically is time-consuming**

**For avoiding this,  $f_b(v)$  is approximated by an analytic expression [Donnel et al. PPCF63]**

# Approximation of the distribution function

For calculation of the Rosenbluth potentials,  $f(v)$  is approximated by

$$\tilde{f} = f_M(v^2) \left( 1 + \frac{m\mathbf{v} \cdot \mathbf{V}}{T} - \frac{m\mathbf{v} \cdot \mathbf{q}}{nT^2} \left( 1 - \frac{mv^2}{5T} \right) - \frac{mV^2}{2T} \left( 1 - \frac{mv^2}{3T} \right) \right) \quad (5.1)$$

(first 4 terms of polynomial expansion of  $f/f_M$ )

- Due to strong anisotropy in the plasma, we can assume  $\mathbf{V} = V_{\parallel}\mathbf{b}$ ,  $\mathbf{q} = q_{\parallel}\mathbf{b}$ :

$$\tilde{f} = \frac{n \exp\left(-\frac{mv^2}{2T}\right)}{(2\pi T/m)^{3/2}} \left( 1 + \frac{mv_{\parallel}V_{\parallel}}{T} - \frac{mv_{\parallel}q_{\parallel}}{T nT} \left( 1 - \frac{mv^2}{5T} \right) - \frac{mV_{\parallel}^2}{2T} \left( 1 - \frac{mv^2}{3T} \right) \right) \quad (5.2)$$

- This approximative distribution function has the properties:

$$\int \tilde{f} d^3v = n \quad \int v_{\parallel} \tilde{f} d^3v = nV_{\parallel} \quad \int v_{\parallel} \left( \frac{mv^2}{2} - \frac{5}{2}T \right) \tilde{f} d^3v = q_{\parallel} \quad (5.3)$$

$$\int mv^2 \tilde{f} d^3v = n(3T + mV_{\parallel}^2) \quad \text{but: } \int mv_{\parallel}^2 \tilde{f} d^3v = n(T + \frac{1}{3}mV_{\parallel}^2) \quad (5.4)$$

- The scattering is done in the frame moving with the field particles
- In the frame with  $V_{\parallel b} = 0$  the distribution function (5.2) becomes

$$f_b \approx f_{bt} = f_M(v^2) \left( 1 - \frac{m_b v_{\parallel}}{T_b} \frac{q_{\parallel b}}{n_b T_b} \left( 1 - \frac{m_b v^2}{5T_b} \right) \right) \quad (6.1)$$

- This corresponds to a modified shifted Maxwellian in the lab frame

$$f_{bt} = \hat{f}_M \exp \left( -\frac{m_b(\mathbf{v} - \mathbf{b}V_{\parallel b})^2}{2T_b} \right) \left[ 1 - \frac{m_b(v_{\parallel} - V_{\parallel b})}{T_b} \frac{q_{\parallel b}}{n_b T_b} \left( 1 - \frac{m_b(\mathbf{v} - \mathbf{b}V_{\parallel b})^2}{5T_b} \right) \right] \quad (6.2)$$

- **Advantage of calculating the collisions in the moving frame:**  
Expressions for friction and diffusion coefficients are reduced  
 $V_{\parallel b}$  does not have to be small

# Scattering in moving frame: friction

- Coordinate system with  $\mathbf{v} = v\mathbf{e}_z$  (before collisions)
- $\mathbf{b} = \mathbf{B}/B = (v_{\parallel}/v)\mathbf{e}_z - (v_{\perp}/v)\mathbf{e}_y, \quad \mathbf{e}_x = \mathbf{e}_y \times \mathbf{e}_z, \quad v_{\parallel} = \mathbf{v} \cdot \mathbf{b}, \quad v_{\perp} = |\mathbf{v} \times \mathbf{b}|$

$$\Gamma_{ab} = \nu_{ab0} \left(1 + \frac{m_a}{m_b}\right) (\Gamma_{ab}^y \mathbf{e}_y + \Gamma_{ab}^z \mathbf{e}_z) \quad \nu_{ab0} = \frac{Z_a^2 Z_b^2 e^4 n_b \ln \Lambda_{ab}}{4\pi \epsilon_0^2 m_a^2 v_{T_a}^3} \quad (7.1)$$

$$\Gamma_{ab}^z = -v \frac{F(s_b)}{s_a^3} + u_{\parallel b} \frac{v_{\parallel}}{v} (2s_b^2 - 1) \frac{v_{T_a}^3}{v_{T_b}^3} \frac{2}{\sqrt{\pi}} e^{-s_b^2} \quad u_{\parallel b} = \frac{2q_{\parallel b}}{5n_b T_b} \quad (7.2)$$

$$\Gamma_{ab}^y = u_{\parallel b} \frac{v_{\perp}}{v} \frac{v_{T_a}^3}{v_{T_b}^3} \frac{2}{\sqrt{\pi}} e^{-s_b^2} \quad s_b = \frac{v}{v_{T_b}} \quad s_a = \frac{v}{v_{T_a}} \quad (7.3)$$

[Donnel et al., NF63]

$$F(s_b) = \operatorname{erf}(s_b) - s_b \operatorname{erf}'(s_b) = \operatorname{erf}(s_b) - \frac{2s_b}{\sqrt{\pi}} e^{-s_b^2} \quad (7.4)$$

# Scattering in moving frame: diffusion

$$2\mathbf{D}_{ab} = \nu_{ab0} \begin{pmatrix} D_{ab}^{xx} & 0 & 0 \\ 0 & D_{ab}^{yy} & D_{ab}^{yz} \\ 0 & D_{ab}^{yz} & D_{ab}^{zz} \end{pmatrix} \quad \nu_{ab0} = \frac{Z_a^2 Z_b^2 e^4 n_b \ln \Lambda_{ab}}{4\pi \varepsilon_0^2 m_a^2 v_{T_a}^3} \quad (8.1)$$

$$D_{ab}^{yy} = v^2 \frac{G(s_b)}{s_a^3} - u_{\parallel b} v_{\parallel} \frac{H(s_b) - G(s_b) + F(s_b)}{s_a^3} = D_{ab}^{xx} \quad u_{\parallel b} = \frac{2q_{\parallel b}}{5n_b T_b} \quad (8.2)$$

$$D_{ab}^{yz} = u_{\parallel b} v_{\perp} \frac{H(s_b) - G(s_b) + F(s_b)}{s_a^3} \quad s_a = \frac{v}{v_{T_a}} \quad (8.3)$$

$$D_{ab}^{zz} = v^2 \frac{H(s_b)}{s_a^3} + 2u_{\parallel b} v_{\parallel} \left( \frac{H(s_b) - G(s_b) + F(s_b)}{s_a^3} - \frac{v_{T_a}^3}{v_{T_b}^3} \frac{2}{\sqrt{\pi}} e^{-s_b^2} \right) \quad s_b = \frac{v}{v_{T_b}} \quad (8.4)$$

[Donnel et al., NF63]

$$G(s_b) = \operatorname{erf}(s_b) \left( 1 - \frac{1}{2s_b^2} \right) + \frac{1}{s_b \sqrt{\pi}} e^{-s_b^2} \quad H(s_b) = \frac{\operatorname{erf}(s_b)}{s_b^2} - \frac{2}{s_b \sqrt{\pi}} e^{-s_b^2} \quad (8.5)$$

$$H(s_b) - G(s_b) + F(s_b) = \frac{3 \operatorname{erf}(s_b)}{2s_b^2} - \frac{3 + 2s_b^2}{s_b \sqrt{\pi}} e^{-s_b^2} \quad F(s_b) = \operatorname{erf}(s_b) - \frac{2s_b}{\sqrt{\pi}} e^{-s_b^2} \quad (8.6)$$

# Equation for $(\Delta v)_{\text{coll}}$

$$\left. \frac{\partial f_a}{\partial t} \right|_{\text{coll}} = \sum_b C_{ab}(f_a, f_b) = - \sum_b \nabla \mathbf{v} \cdot \left( \Gamma_{ab} f_a - \nabla \mathbf{v} \cdot (\mathbf{ID}_{ab} f_a) \right) \quad (9.1)$$

$$\Gamma_{ab} = \nu_{ab0} \frac{v_{T_a}^3}{n_b} \left( 1 + \frac{m_a}{m_b} \right) \nabla \mathbf{v} H_b(\mathbf{v}) \quad 2\mathbf{ID}_{ab} = \nu_{ab0} \frac{v_{T_a}^3}{n_b} \nabla \mathbf{v} \nabla \mathbf{v} G_b(\mathbf{v}) \quad (9.2)$$

**In a PIC code: particle velocities  $v_{\parallel i}$  and  $v_{\perp i}^2$  have to be changed**

Use corresponding stochastic differential equation:

$$\left. \frac{d\mathbf{v}}{dt} \right|_{ab} = \Gamma_{ab} + \mathbf{IK}_{ab} d\mathbf{W} \quad \mathbf{W}: \text{stochastic Wiener process}, \quad 2\mathbf{ID}_{ab} = \mathbf{IK}_{ab} \mathbf{IK}_{ab}^T$$

$$\Delta \mathbf{v} = \Gamma_{ab} \Delta t + \mathbf{IK}_{ab} \sqrt{\Delta t} \mathbf{R} \quad \mathbf{R}: \text{vector of random numbers}, \quad \langle R_i \rangle = 0, \quad \langle R_i^2 \rangle = 1$$

$$\Delta v_i = (\Gamma_{ab})_i \Delta t + \sqrt{(2\mathbf{ID}_{ab})_{ii} \Delta t} R_i \quad \text{if } \mathbf{ID}_{ab} \text{ is diagonal}$$

1. Friction:  $v_z = v + \Gamma_z \Delta t, \quad v_y = \Gamma_y \Delta t, \quad v_x = 0$

2. Diffusion:

$$x : \quad v_x = \sqrt{D_{ab}^{yy} \Delta t} R_1 \quad R_1 : \text{random number}$$

$y, z :$

1. transform  $(v_y, v_z)$  to  $(v_2, v_3)$  so that  $2\mathbf{ID}$  becomes diagonal,  $2\mathbf{ID} = \begin{pmatrix} \lambda_2 & 0 \\ 0 & \lambda_3 \end{pmatrix}$

$$2. \quad v_2 \rightarrow v_2 + \sqrt{\lambda_2 \Delta t} R_2, \quad v_3 \rightarrow v_3 + \sqrt{\lambda_3 \Delta t} R_3$$

3. transfrom back to  $(v_y, v_z)$

4. retrieve  $v_{\parallel}, v_{\perp}^2 : \quad v^2 = (v_x^2 + v_y^2 + v_z^2), \quad v_{\parallel} = \mathbf{v} \cdot \mathbf{b} = b_z v_z + b_y v_y, \quad v_{\perp}^2 = v^2 - v_{\parallel}^2$

# Collisions: scattering part and correction part

In a delta-f code with linearized collision operator we have

$$C(f_a, f_b) = \underbrace{C(\delta f_a, f_{Mb})}_{\text{scattering part}} + \underbrace{C(f_{Ma}, \delta f_b) + C(\delta f_a, \delta f_b)}_{\text{replaced by correction part}} + C(f_{Ma}, f_{Mb}) \quad (11.1)$$

In the full-f code with the approximation  $f_{bt}$  for  $f_b$  we have

$$C(f_a, f_b) = \underbrace{C(f_a, f_{bt})}_{\text{scattering part}} + \underbrace{C(f_a, (f_b - f_{bt}))}_{\text{replaced by correction part}} \quad (11.2)$$

The correction part is needed for momentum/energy conservation and for correct momentum/energy loss/gain

Full-f:  $C(f_a, f_{bt})$  is closer to  $C(f_a, f_b)$  than  $C(\delta f_a, f_{Mb})$ , because  $f_{bt}$  is closer to  $f_b$  than  $f_{Mb}$  and the particles scattered represent the full distribution function  $f_a$

## Velocity dependent correction for momentum and energy conservation:

Before and after scattering:  $(V_{\parallel 1}, E_1)$  and  $(V_{\parallel 2}, E_2)$ ,  $V_{\parallel} = \frac{1}{N} \sum_j v_{\parallel j}$ ,  $E = \frac{1}{N} \sum_j v_j^2$

Corrections for  $v_{\parallel}$  and  $v_{\perp}^2$ :

$$\Delta v_{\parallel j} = -\frac{v_{\parallel j} \delta v_{\parallel j} \Delta V_{\parallel}}{\frac{1}{N} \sum_j v_{\parallel j} \delta v_{\parallel j}}, \quad \frac{1}{N} \sum_j \Delta v_{\parallel j} = -\Delta V_{\parallel}, \quad \Delta V_{\parallel} = V_{\parallel 2} - V_{\parallel 1} \quad (12.1)$$

$$\Delta v_j^2 = -\frac{v_j^2 \delta v_j^2 \Delta E}{\frac{1}{N} \sum_j v_j^2 \delta v_j^2}, \quad \frac{1}{N} \sum_j \Delta v_j^2 = -\Delta E, \quad \Delta E = \frac{3T_2}{m} + V_{\parallel 2}^2 - \left( \frac{3T_1}{m} + V_{\parallel 1}^2 \right) \quad (12.2)$$

$$\Delta v_{\perp j}^2 = \Delta v_j^2 - 2v_{\parallel j} \Delta v_{\parallel j} - (\Delta v_{\parallel j})^2 \quad (12.3)$$

Theoretical changes of momentum and energy (next slides)

$$\delta v_{\parallel j} = (\Delta v_{\parallel})_j^{\text{th}}, \quad \delta v_j^2 = (\Delta v^2)_j^{\text{th}} \quad (12.4)$$

# Average momentum/energy loss per particle

In the frame with  $V_{\parallel b} = 0$  (**obtained with**  $\langle R_i \rangle = 0, \langle R_i^2 \rangle = 1$ ):

$$(\Delta v_{\parallel})_{ab}^{\text{th}} = \nu_{ab0} \Delta t \left( 1 + \frac{m_a}{m_b} \right) \left[ -v_{\parallel} \frac{F(s_b)}{s_a^3} + \frac{2q_{\parallel b}}{5n_b T_b} \left( 2 \frac{v_{\parallel}^2}{v_{T_b}^2} - 1 \right) \frac{2}{\sqrt{\pi}} \frac{v_{T_a}^3}{v_{T_b}^3} e^{-s_b^2} \right] \quad (13.1)$$

$$\begin{aligned} (\Delta v^2)_{ab}^{\text{th}} = & -\nu_{ab0} \Delta t \left[ v^2 \left( 2 \left( 1 + \frac{m_a}{m_b} \right) \frac{F(s_b)}{s_a^3} - \frac{2E_b}{s_a^3} \right) \right. \\ & \left. - \frac{2q_{\parallel b} v_{\parallel}}{5n_b T_b} \left( \left( 1 + \frac{m_a}{m_b} \right) (2s_b^2 - 1) - 1 \right) \frac{v_{T_a}^3}{v_{T_b}^3} \frac{4}{\sqrt{\pi}} e^{-s_b^2} \right] \end{aligned} \quad (13.2)$$

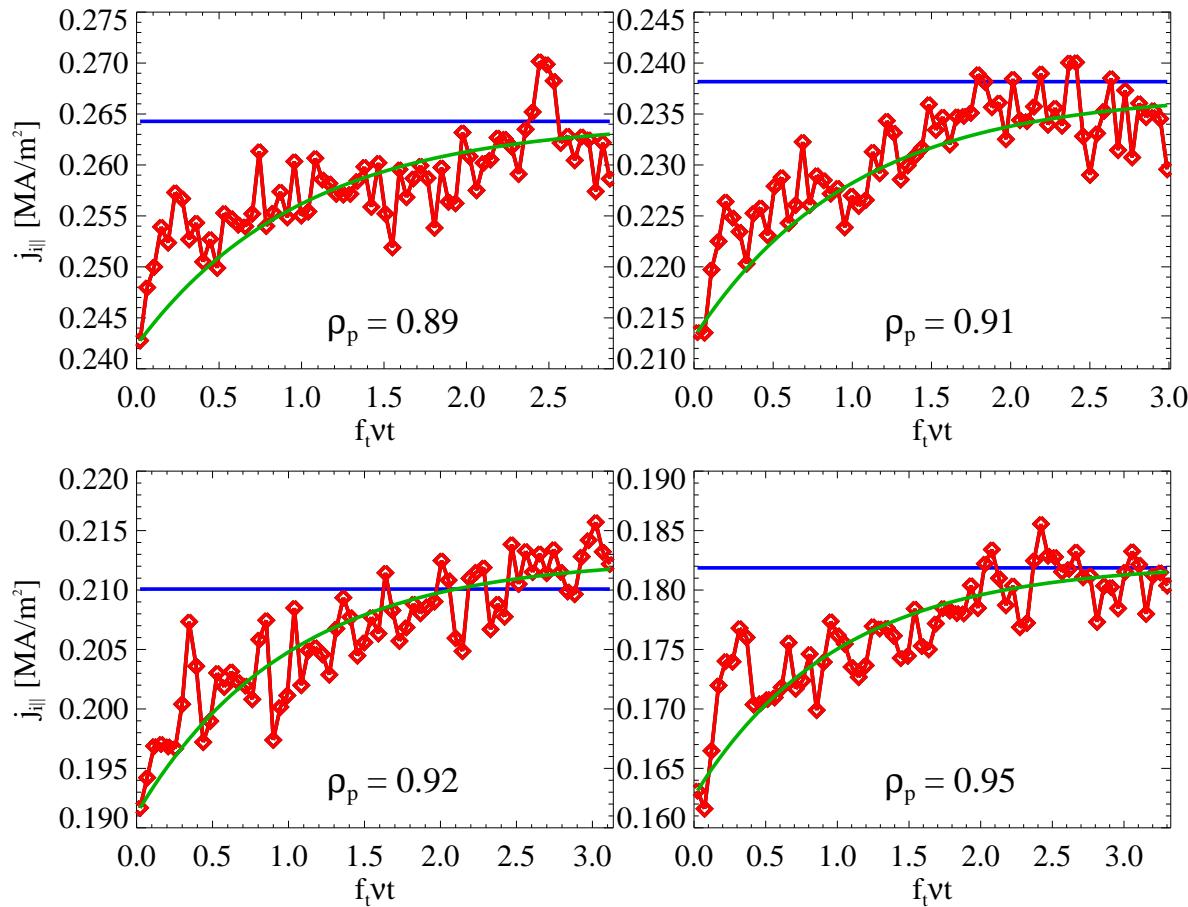
Neglecting  $q_b$ :

$$(\Delta v_{\parallel})_{ab}^{\text{th}} = -v_{\parallel} \nu_{ab0} \Delta t \left( 1 + \frac{m_a}{m_b} \right) \frac{F(s_b)}{s_a^3} \quad (13.3)$$

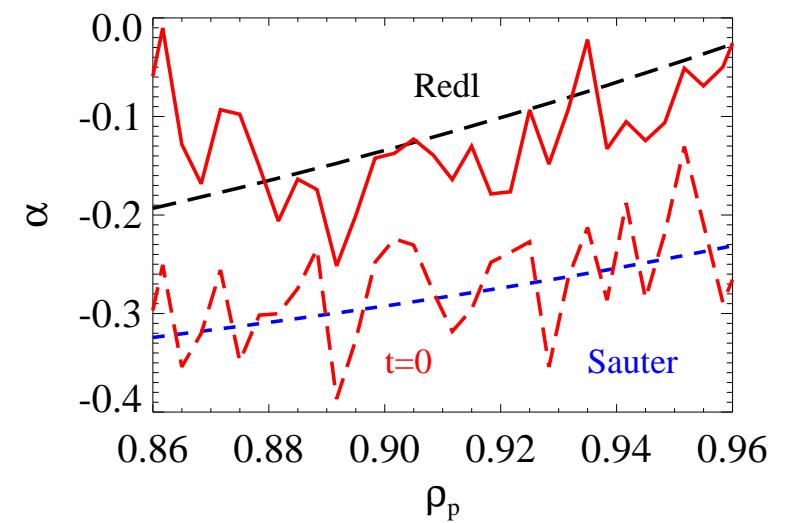
$$(\Delta v^2)_{ab}^{\text{th}} = -v^2 \nu_{ab0} \Delta t \left( 2 \left( 1 + \frac{m_a}{m_b} \right) \frac{F(s_b)}{s_a^3} - \frac{2E_b}{s_a^3} \right) \quad (13.4)$$

# Ion simulation with weak gradients

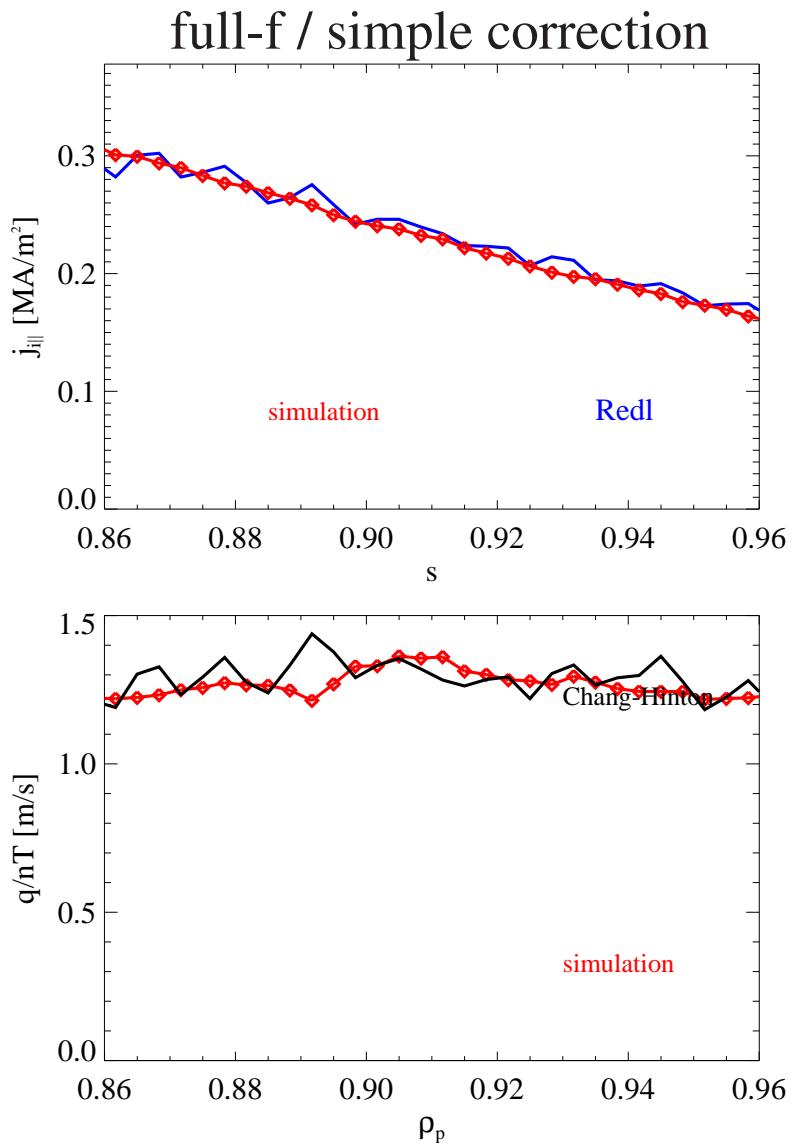
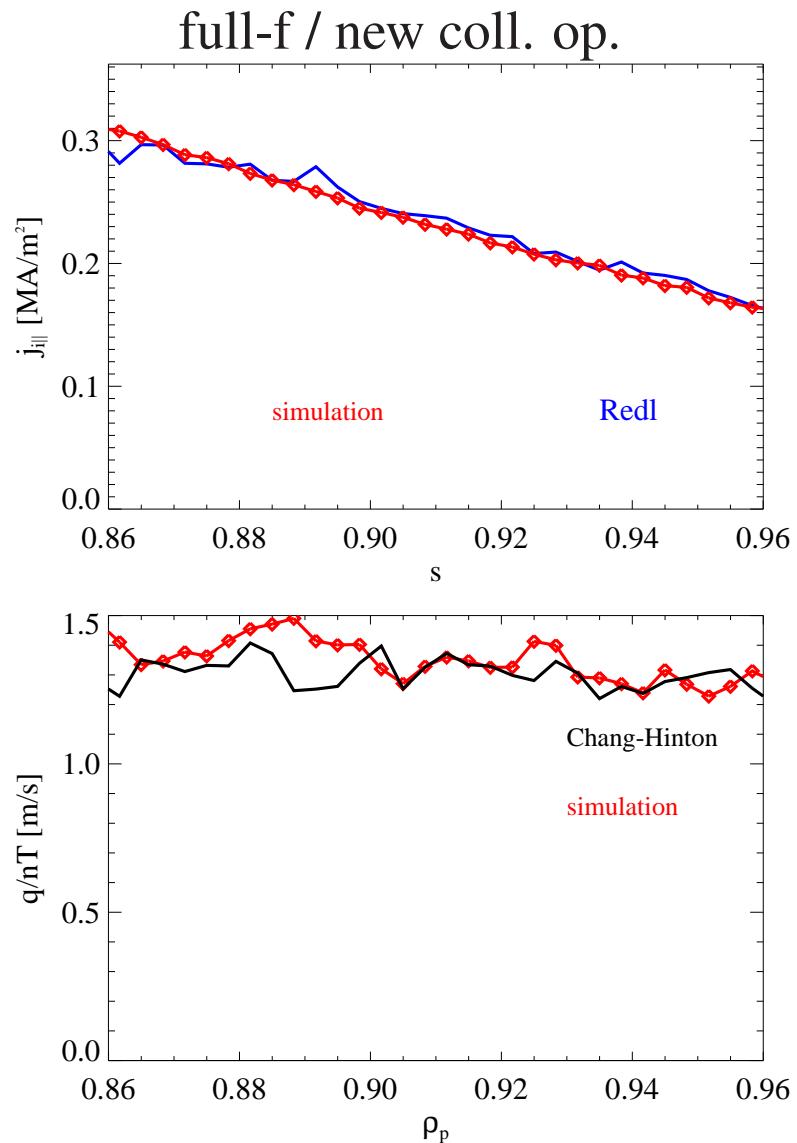
Characteristic time for ion current:  $\tau_{\text{coll}}/f_t$  [ $dj_i/dt = (\nu_{ii}/f_t^2)j_{i\text{tr}} - f_t \nu_{ii} j_i$ ]



Coefficient for poloidal flow



# Ion simulation with weak gradients



## Simple version: correction for momentum/energy conservation/transfer:

- Intra-species collisions: momentum and energy conservation

$$v_{\parallel} \rightarrow V_{\parallel 1} + (v_{\parallel} - V_{\parallel 2}) \sqrt{\frac{T_1}{T_2}} \quad v_{\perp}^2 \rightarrow v_{\perp}^2 \frac{T_1}{T_2} \quad [1, 2 : \text{before/after scatt.}] \quad (16.1)$$

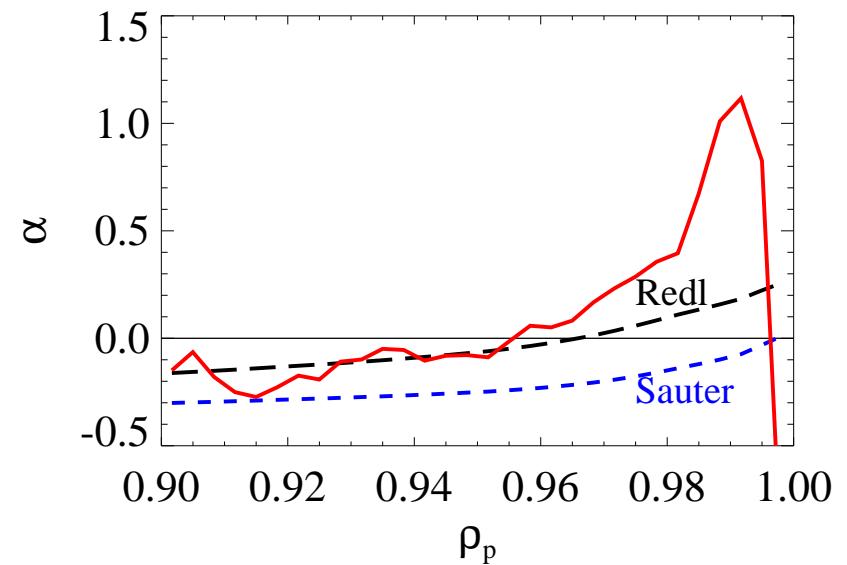
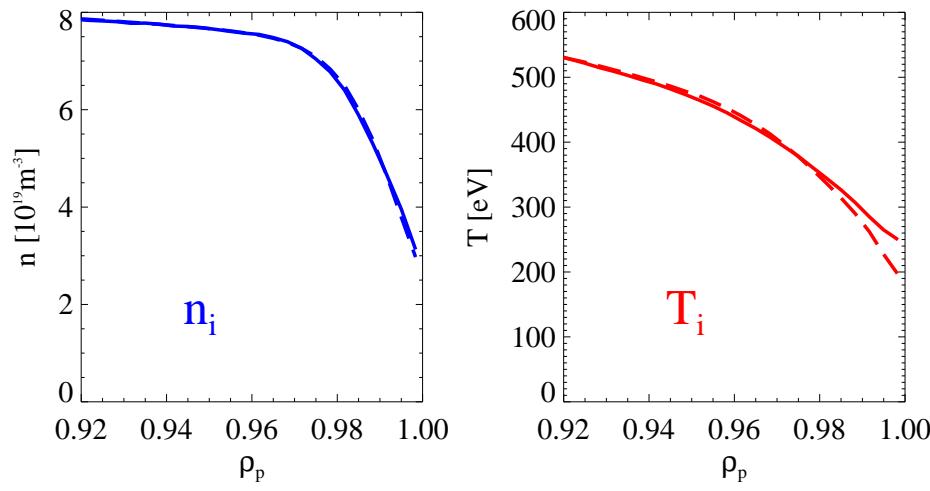
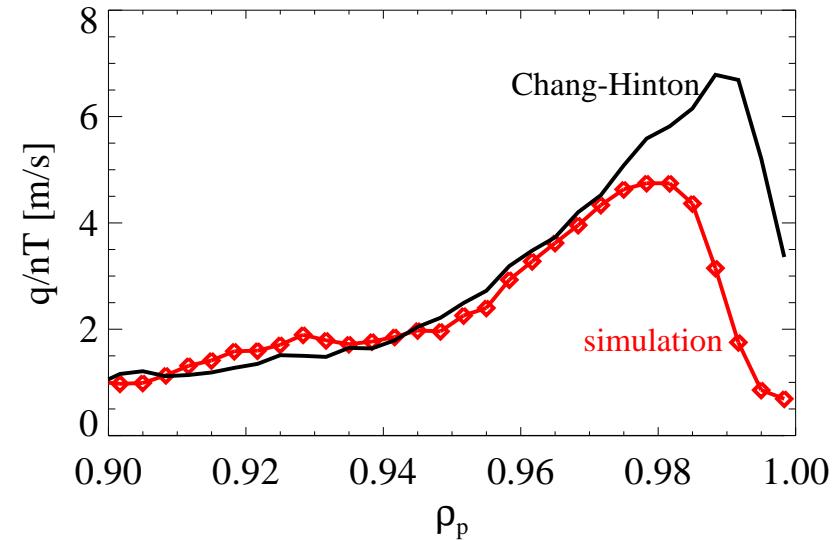
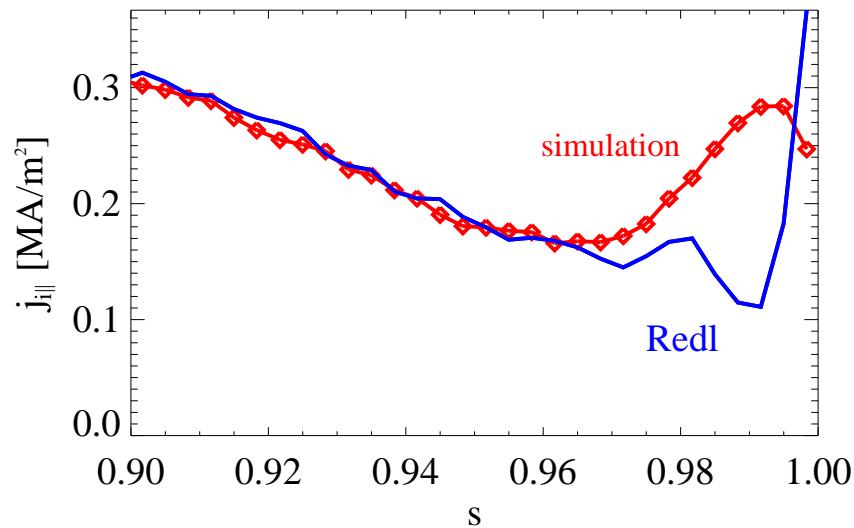
- electron - ion collisions: momentum and energy loss/gain

$$T_{e1n} = T_{e1} + 2(T_i - T_{e1}) \frac{m_e}{m_i} 0.752 \nu_{ei0} \Delta t \quad v_{\perp e}^2 \rightarrow v_{\perp e}^2 \frac{T_{e1n}}{T_{e2}} \quad (16.2)$$

$$v_{\parallel e} \rightarrow V_{\parallel e1} + (v_{\parallel e} - V_{\parallel e2}) \sqrt{\frac{T_{e1n}}{T_{e2}}} + (V_{\parallel i} - V_{\parallel e1} + \frac{3q_{\parallel e}}{5n_e T_e}) 0.752 \nu_{ei0} \Delta t \quad (16.3)$$

- This procedure works, but was shown for the linearized operator to be inaccurate

# Ion simulation for pedestal



## Energy dependent correction for momentum and energy:

Before and after scattering:  $(V_{\parallel 1}, T_1)$  and  $(V_{\parallel 2}, T_2)$

After correction:  $V_{\parallel 1} + (\Delta V_{\parallel})_{ab}, T_1 + (\Delta T)_{ab}$

Theoretical losses of momentum and energy

$$(\Delta V_{\parallel})_{ab}, \quad (\Delta T)_{ab} \quad (18.1)$$

Corrections for  $v_{\parallel}$  and  $v_{\perp}^2$ :

$$\Delta v_{\parallel j} = -\Delta V_{\parallel} \frac{v_{\parallel j} \delta v_{\parallel j}}{\frac{1}{N} \sum_j v_{\parallel j} \delta v_{\parallel j}}, \quad \Delta V_{\parallel} = V_{\parallel 2} - (V_{\parallel 1} + (\Delta V_{\parallel})_{ab}) \quad (18.2)$$

$$\Delta v_j^2 = -\frac{v_j^2 \delta v_j^2 \Delta E}{\frac{1}{N} \sum_j v_j^2 \delta v_j^2}, \quad \Delta E = \frac{3T_2}{m} + V_{\parallel 2}^2 - \left( \frac{3(T_1 + (\Delta T)_{ab})}{m} + (V_{\parallel 1} + (\Delta V_{\parallel})_{ab})^2 \right) \quad (18.3)$$

$$\Delta v_{\perp j}^2 = \Delta v_j^2 - 2v_{\parallel j} \Delta v_{\parallel j} - \Delta v_{\parallel j}^2 \quad (18.4)$$

# Different species: change of average velocity

In the frame with  $V_{\parallel b} = 0$ ,  $V_{\parallel a} = \Delta V_{\parallel}$  (4-term approximation (6.1) also used for  $f_a$ ):

$$(\Delta V_{\parallel})_{ab} = \nu_{ab} \Delta t \left[ -\Delta V_{\parallel} + \frac{3q_{\parallel a}}{5n_a T_a} \frac{T_a m_b}{T_a m_b + T_b m_a} - \frac{3q_{\parallel b}}{5n_b T_b} \frac{T_b m_a}{T_a m_b + T_b m_a} \right] + \dots \quad (19.1)$$

In the frame with  $V_{\parallel a} = 0$ ,  $V_{\parallel b} = -\Delta V_{\parallel}$

$$(\Delta V_{\parallel})_{ba} = \nu_{ba} \Delta t \left[ \Delta V_{\parallel} - \frac{3q_{\parallel a}}{5n_a T_a} \frac{T_a m_b}{T_a m_b + T_b m_a} + \frac{3q_{\parallel b}}{5n_b T_b} \frac{T_b m_a}{T_a m_b + T_b m_a} \right] + \dots \quad (19.2)$$

Two terms in the expressions from [Donnel et al., NF63] are omitted for obtaining

$$(\Delta V_{\parallel})_{ba} \Big|_{V_{\parallel a}=0} = - (\Delta V_{\parallel})_{ab} \Big|_{V_{\parallel b}=0}$$

For  $m_a \ll m_b$  terms with  $q_{\parallel b}$  are very small:

$$(\Delta V_{\parallel})_{ei} = \nu_{ei} \Delta t \left[ V_{\parallel i} - V_{\parallel e} + \frac{3q_{\parallel e}}{5n_e T_e} \right] = \nu_{ei} \Delta t \left[ \frac{J_{\parallel}}{en_e} + \frac{3q_{\parallel e}}{5n_e T_e} \right] \quad (19.3)$$

In the frame with  $V_{\parallel b} = 0$ ,  $V_{\parallel a} = \Delta V_{\parallel}$  ( $f_a$  approx. by  $f_{at}$ ):

$$(\Delta E)_{ab} = \frac{m_a}{m_a + m_b} \nu_{ab} \Delta t \left\{ 3(T_b - T_a) - \frac{(\Delta V_{\parallel})^2}{v_{T_a}^2 + v_{T_b}^2} \left[ \left( 2 \frac{m_a}{m_b} + 3 \right) T_b - T_a \right] \right. \\ \left. - 3 \frac{2q_{\parallel b} \Delta V_{\parallel}}{5n_b T_b} \frac{X_{ba}^2}{(v_{T_a}^2 + v_{T_b}^2)} \left[ \left( \frac{m_a}{m_b} + 2 \right) T_b - \left( 3 \frac{m_b}{m_a} + 4 \right) T_a \right] \right. \\ \left. + \frac{15}{2} \frac{2q_{\parallel a}}{5n_a T_a} \frac{2q_{\parallel b}}{5n_b T_b} \frac{X_{ab}^2 X_{ba}^2}{(v_{T_a}^2 + v_{T_b}^2)} \left[ 3 \left( \frac{m_a}{m_b} + 4 \right) T_b - \left( 3 \frac{m_b}{m_a} + 4 \right) T_a \right] \right\} \quad (20.1)$$

$$X_{ab}^2 = \frac{T_a m_b}{T_a m_b + T_b m_a}, \quad X_{ba}^2 = \frac{T_b m_a}{T_a m_b + T_b m_a} \quad (20.2)$$

## Electron - ion collisions:

$$X_{ei}^2 \approx 1, \quad X_{ie}^2 \approx m_e/m_i, \quad (\Delta V_{\parallel})^2 \ll v_{T_e}^2 \quad (20.3)$$

$$(\Delta E)_{ei} = \frac{m_e}{m_i} \nu_{ei} \Delta t 3(T_i - T_e), \quad (\Delta T)_{ei} = \frac{m_e}{m_i} \nu_{ei} \Delta t 2(T_i - T_e) \quad (20.4)$$

From neoclassical theory:

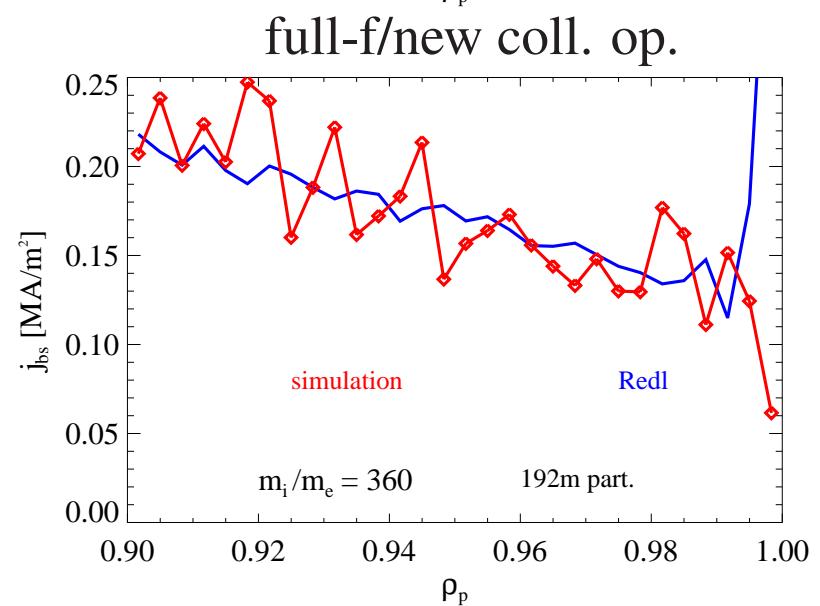
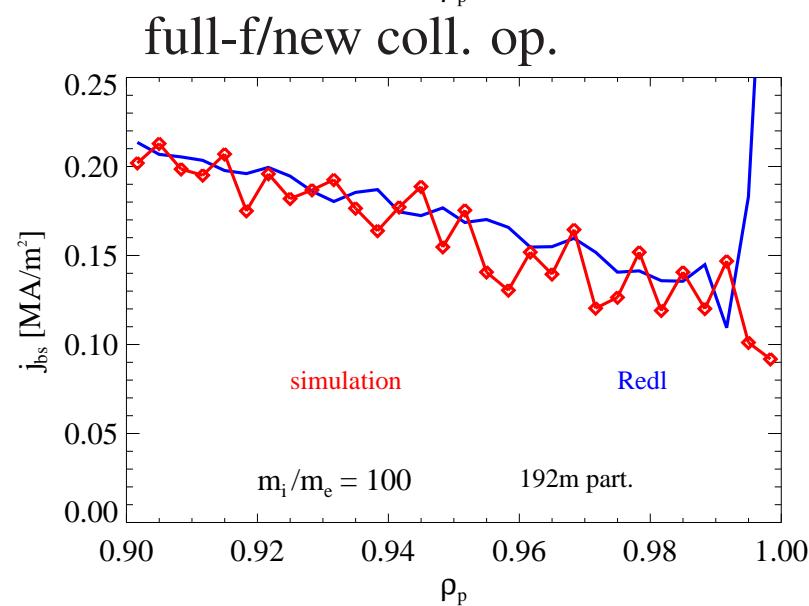
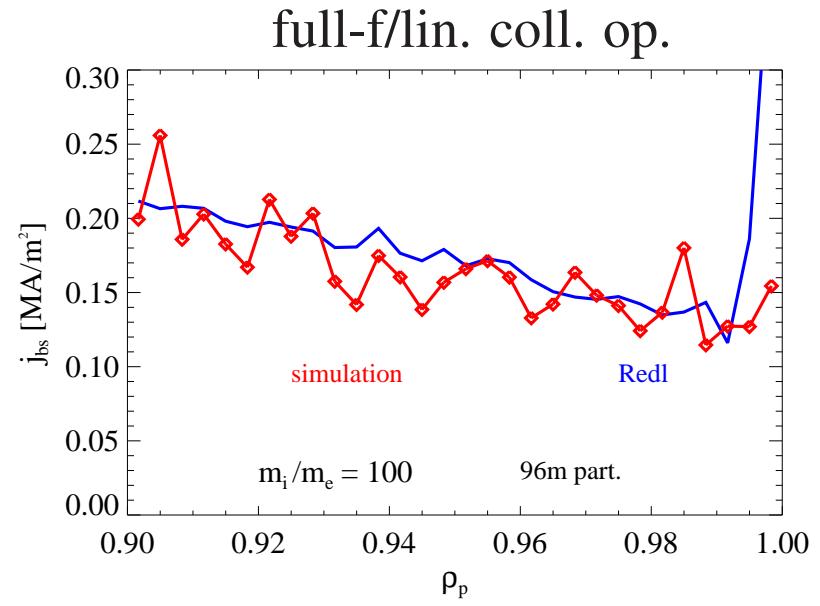
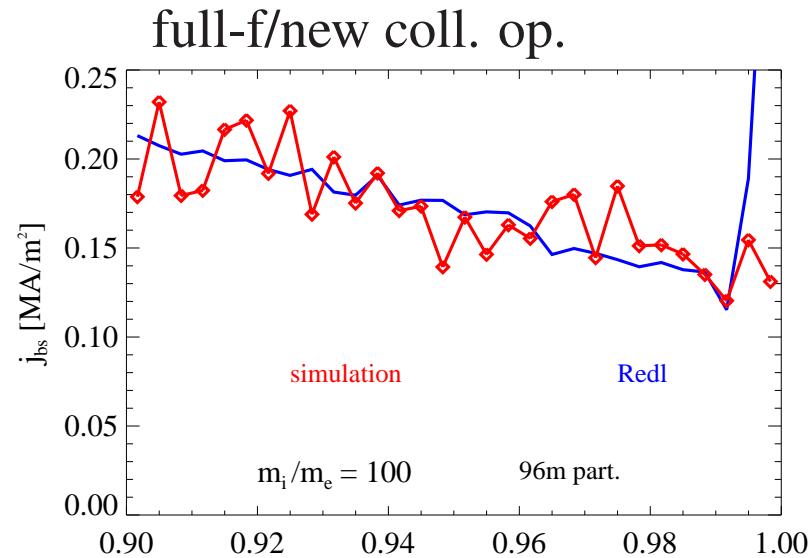
$$j_{\parallel} = -\frac{RB_t}{B} \left\{ \left( \frac{dp_e}{d\psi} + \frac{dp_i}{d\psi} \right) + \frac{B^2}{\langle B^2 \rangle} \left[ (L_{31} - 1) \left( \frac{dp_e}{d\psi} + \frac{dp_i}{d\psi} \right) + L_{32} n_e \frac{dT_e}{d\psi} + \alpha L_{34} n_i \frac{dT_i}{d\psi} \right] \right\}$$

$$\frac{\langle j_{\parallel} B \rangle}{B_0} = -R_0 \left\{ L_{31} \left( \frac{dp_e}{d\psi} + \frac{dp_i}{d\psi} \right) + L_{32} n_e \frac{dT_e}{d\psi} + \alpha L_{34} n_i \frac{dT_i}{d\psi} \right\}$$

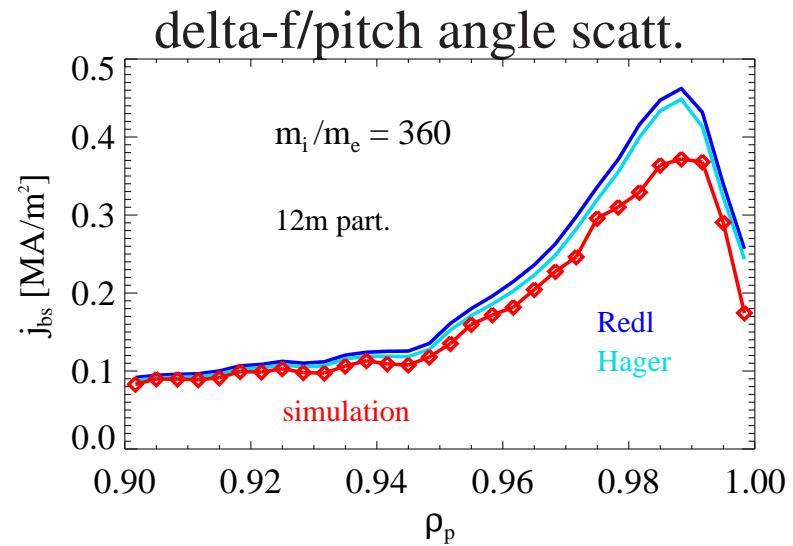
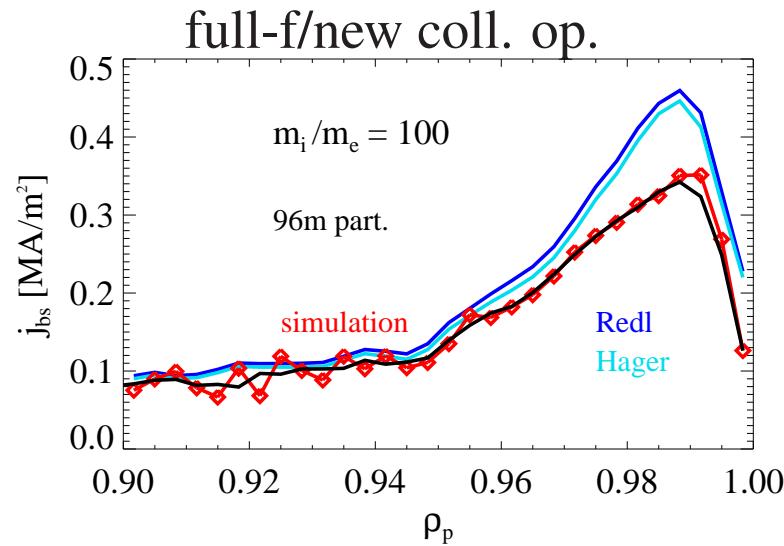
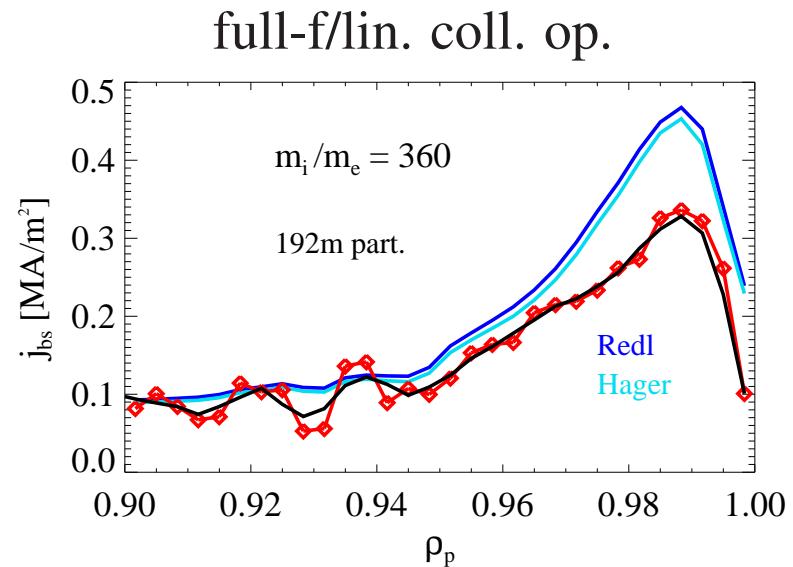
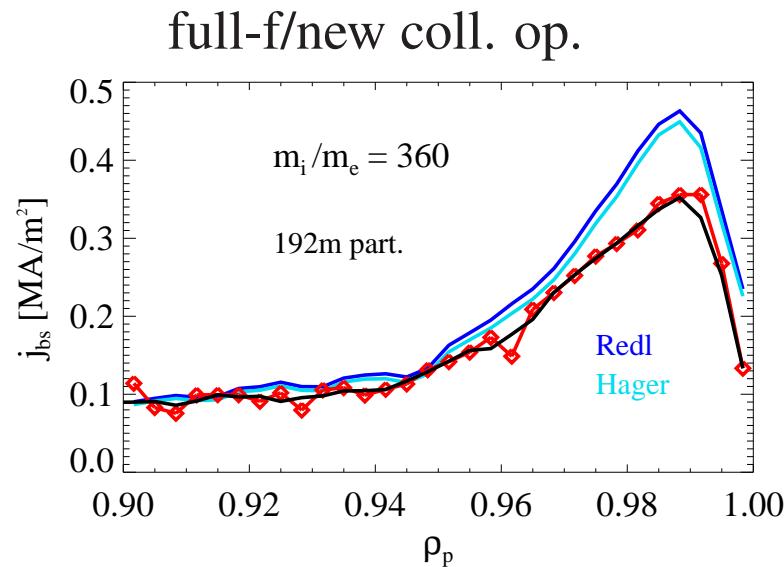
$$L_{3x} = L_{3x}(\nu_*, f_t)$$

- No explicit dependence on the mass ratio  $m_i/m_e$ .
- Possible effect of finite electron orbit width, if electron mass is large.
- We can use smaller mass ratio if  $\rho_{pe} \ll L$  still holds.

# Bootstrap current - simulation with weak gradients



# Bootstrap current in pedestal



- Improved collision operator for full-f HAGIS simulations was implemented
- Collisions are calculated in the frame moving with the field particles
- New versus linear collision operator: additional terms due to the heat flux
- Corrections for momentum/energy conservation/exchange proportional to theoretical rates are smaller than for linearized operator
- For bootstrap current a large number of marker particles is necessary
- Currently without noise reduction procedure, but
- smaller mass ratio (360, 100) can be used in bootstrap current calculation for reducing the numerical noise