

Technical overview of the GENE-X code



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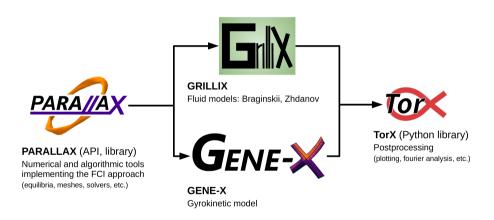




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The PARALLAX Code Family



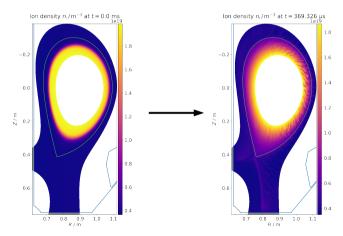




GENE-X is a gyrokinetic code to simulate plasma turbulence in X-point geometries.

Features:

- global
- non-linear
- full-f
- · electromagnetic
- collisional



Equations solved by the code I



$$\frac{\partial f_{\alpha}}{\partial t} + v_{||} \frac{\mathbf{B}^{*}}{B_{||}^{*}} \cdot \nabla f_{\alpha} + \frac{c}{q_{\alpha} B_{||}^{*}} \mathbf{b} \times (\mu \nabla B + q_{\alpha} \nabla \phi_{1}) \cdot \nabla f_{\alpha}$$

$$- \frac{\mathbf{B}^{*}}{m_{\alpha} B_{||}^{*}} \cdot (\mu \nabla B + q_{\alpha} \nabla \phi_{1}) \frac{\partial f_{\alpha}}{\partial v_{||}} - \frac{q_{\alpha}}{m_{\alpha} c} \frac{\partial A_{1,||}}{\partial t} \frac{\partial f_{\alpha}}{\partial v_{||}} = C_{\alpha}(f_{\alpha}).$$

timestep

operators/op_rhs_vlasov_static
operators/op_rhs_vlasov_dynamic
operators/collisions

- $\alpha \dots$ particle species. (electrons + ions)
- $v_{||}\dots$ parallel velocity
- $\mu \dots$ magnetic moment

Equations solved by the code II



$$\begin{split} -\nabla \cdot \left(\sum_{\alpha} \frac{m_{\alpha} c^2 n_{0,\alpha}}{B^2} \nabla_{\perp} \phi_1 \right) &= \sum_{\alpha} q_{\alpha} \int f_{\alpha} \, \mathrm{d}W, \\ -\Delta_{\perp} A_{1,||} &= 4\pi \sum_{\alpha} \frac{q_{\alpha}}{c} \int v_{||} f_{\alpha} \, \mathrm{d}W, \\ -\left(\Delta_{\perp} + 4\pi \sum_{\alpha} \frac{q_{\alpha}^2}{m_{\alpha} c^2} \int v_{||} \frac{\partial f_{\alpha}}{\partial v_{||}} \, \mathrm{d}W \right) \frac{\partial A_{1,||}}{\partial t} &= 4\pi \sum_{\alpha} \frac{q_{\alpha}}{c} \int v_{||} \left(\frac{\partial f_{\alpha}}{\partial t} \right)^{\star} \, \mathrm{d}W. \end{split}$$

operators/field_solve_operators/op_solve_qn_eq
operators/op_mom_maxwells_eq
operators/field_solve_operators/op_solve_amps_law
operators/field_solve_operators/op_solve_ohms_law
operators/op_mom_ohms_law

Data structure



- The distribution function f_{α} is stored on a 5D+species grid $(RZ, \varphi, v_{\parallel}, \mu, \alpha)$
- The electrostatic potential ϕ_1 , parallel electromagnetic vector potential $A_{1,||}$ and parallel electric field $E_{1,||} = \partial A_{1,||}/\partial t$ are stored on a 3D grid (RZ,φ)
- Also moments (results of $\mathrm{d}W$ integrals) are 3D
- We have implemented types that contain this data + handle the pack/unpack to/from 1D for MPI exchange: datastructures/data_storage_5d datastructures/data_storage_2d
- All relevant data of the simulation is stored in state_vector
- All operations done on data are implemented in operators
- The state vector keeps its data encapsulated to prevent global access. Operators are applied via e.g. state_vector%apply(op_rhs_vlasov_static)

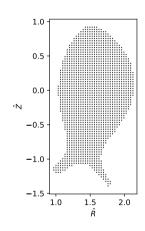
Dimensions



- RZ Cartesian but unstructured 2D grid (see figure right)
- φ angle dimension uniform
- $v_{||}, \mu$ velocity space uniform 2D Cartesian
- α species parameter

Conventions in the code:

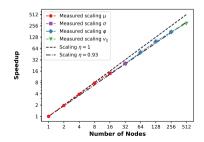
- Loop indices i, k, 1, m, n for $RZ, \varphi, v_{||}, \mu, \alpha$
- 1b and ub 5D arrays with lower and upper bound with MPI ghosts
- 1b_stripped and ub_stripped 5D arrays with lower and upper bound - no MPI ghosts

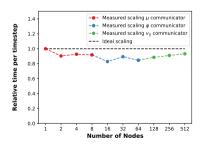


Parallelization



- Hybrid MPI+OMP. MPI in $\varphi, v_{||}, \mu, \alpha$. OMP in RZ
- Typical problem size approx. $(RZ, \varphi, v_{||}, \mu, \alpha) = (200000, 32, 80, 20, 2)$
- Latest production runs on Raven supercomputer (MPCDF) 320 nodes 72 cores. 640 MPI procs, 36 cores for OMP. MPI decomposition e.g. $(RZ, \varphi, v_{||}, \mu, \alpha) = (1, 16, 2, 10, 2)$.
- · Good strong (left) + weak (right) scaling

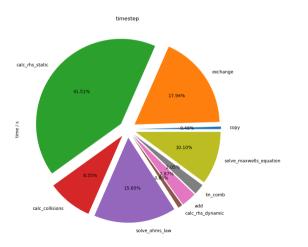




Performance



Example for recent production run with $(RZ, \varphi, v_{||}, \mu, \alpha) = (200000, 32, 80, 20, 2)$



Wall-clock time: approx 2.6 s (configuration given on last slide)

Intensity ranking:

- op_rhs_vlasov_static
- 2. field_solve_operators
- 3. MPI exchange
- 4. collisions

Interface to PARALLAX



- mesh/mesh_5d contains all calls to PARALLAX library routines
- Important tasks: create equilibrium (magnetic field), create 2D $\it RZ$ mesh (with multigrid), create elliptic solver (mGMRES)
- PARALLAX has 3 types of points: inner + boundary + ghost
- Currently GENE-X has 2 types: inner + ghost (contains PARALLAX boundary)
- Currently **no** MPI decomposition in RZ

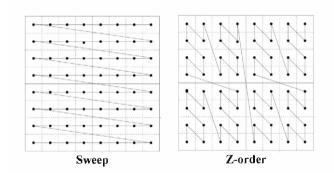
Re-ordering of the unstructured mesh

- Implemented in PARALLAX
 call this%multigrid_3d(k)%init(..., reorder_size=X)
- However, we use X=0 no reordering so far
- Reordering would change the order of inner + boundary + ghost points

What is reorder?



https://en.wikipedia.org/wiki/Z-order_curve



May increase performance for stencil heavy operations.

Why reorder?



- Performance limited by memory access bottleneck op_rhs_vlasov_static
- Finite difference stencils in $R\mathbb{Z}$ because dimension is unstructured, neighbor search is needed
- Finite difference stencils in φ require CSR matrix-vector dot product involves stencil in RZ due to interpolation
- Effect of reordering on PARALLAX elliptic solvers expected (may dig out details)
- Question: do all code parts profit from reordering?

Code Infrastructure



- Program for code benchmarks of individual operators is available benchmarks/benchmark_operators (field solvers not included so far)
- Workflow: protected master on Gitlab branch out for new feature, merge request ASAP when ready to avoid conflicts (CI/CD)
- Unit tests are performed automatically when pushing to Gitlab. These may take a
 while due to the slurm queue. Best run tests manually before pushing to identify
 errors earlier
- New functions, subroutines require new tests if not covered by existing tests or if isolated feature
- Code review before merge to double check bugs
- PARALLAX coding standards available

Open questions: Code access? Runners for unit tests?

Summary



Current Status

- Bottleneck is memory access
- op_rhs_vlasov_static is most intense part of the code
- RZ dimension is unstructured
- Morton Z-reordering implemented in PARALLAX for RZ dimension
- Benchmark program for individual code parts available

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Todos

- Main goal: performance optimization of op_rhs_vlasov_static
- Enable reordering by fixing handling of boundary/ghost cells
- Identify other changes needed to enable reorder
- Benchmark effect on op_rhs_vlasov_static and other code parts (maybe add field solver benchmark?)