# DMP Implementation Status of IPP

2023-06-02

# IMAS installation (previously reported)

On the TOK cluster (i.e. linux systems hosted by MPCDF)

- IMAS/3.24.0-4.2.0
- IMAS/3.25.0-4.4.0
- IMAS/3.30.0-4.8.4
- IMAS/3.32.1-4.9.1
- IMAS/3.34.0-4.10.1
- IMAS/3.35.0-4.10.0
- IMAS/3.36.0-4.10.0
- idstools/1.2.3
- idstools/1.5.1
- UDA/2.5.1

Would like to get a recommendation of which version to install, and which tools

# IMAS installation (new installation)

On the IPP-IT Citrix nodes (linux system hosted by IPP-IT running "Ubuntu 20.04.6 LTS")

- IMAS/3.38.1-4.11.4
- fundamental-constants/0.1.1
- IDSTOOLS/1.14.0
- AMNS/1.4.0-gfortran

Notes

- This is in my private area still waiting for the IMAS volume to be made available
- Used **spack** to install the dependencies
- Only gnu compilers available at the moment Gnu and intel now supported

## Data mappings

Two distinct branches:

- 1. Mapping data that already exists ("diagnostics")
  - a. Can build on what has already been done
  - b. Perhaps few direct users at the moment
  - c. But could be used as new IDS based tools come online (IDA-IMAS)
  - d. Needs UDA with plugins
- 2. Mapping data that doesn't yet exist ("trview", augped, IMASgo, or similar)
  - a. This is perhaps the data that users need now
    - i. But I might be wrong
  - b. Currently the tools are based at the experiments
    - i. Which is where the expertise is
  - c. Future tools might use lower level data and then back to mapping 1
  - d. Good benefit from UDA, but no mappings needed

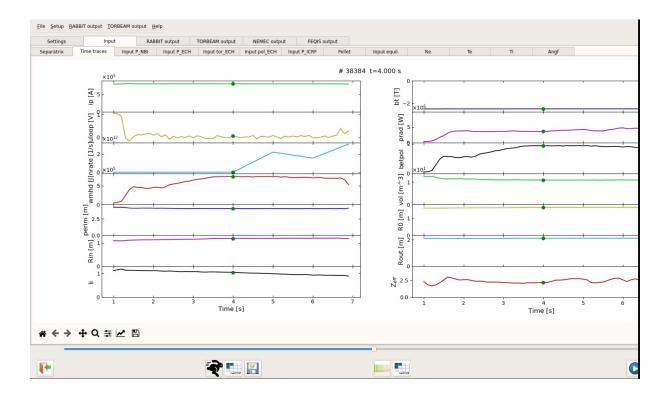
### trview

- Reads AUG shotfiles
- Merges data from multiple diagnostics (various options)
- Writes wall, tf, nbi, ic\_antennas, ec\_launchers, dataset\_descripti on, summary, pulse\_schedule, master, equilibrium, core\_profiles IDS's

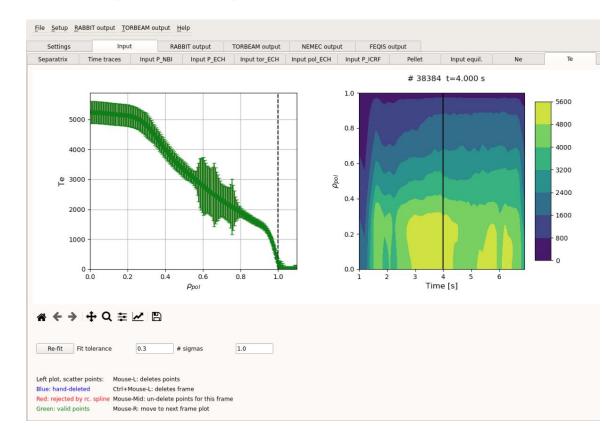
Settings	Input	RABBIT output	TORBEAM output	NEMEC output	FEQIS output
Exp settings	TRANSP settings	RABBIT settings	TORBEAM settings	NEMEC settings	FEOIS settings

Exp/fit options		Ne	Те
Discard frames close to ELMs		Rec. spline      Gaussian fit     Fit 2D	Rec. spline      Gaussian fit     Fit 2D
Shot number	38384		
Initial time for input and simulation	1.0	VTA:Ne_c VTA:Ne_e VTA:Ne VTN:Ne DLP:ne	CEC:Trad-A RMD:Trad-A ✔ IDA:Te IDZ:Te PED:TeFit
Final time for input and simulation	7.0	DPR:ne DCR:profile LIN:ne YAG:ne YAP:ne	VTA:Te c VTA:Te e VTA:Te VTN:Te YPR:Te
Time step for input and simulation	0.1	☐ YPR:Ne	
Equ shotfile exp	AUGD	AUGD:IDA:ne:0	AUGD:IDA:Te:0
Equ shotfile diag	EQH		
Equ shotfile edition	0		
#radial points for input profiles	51		
#poloidal points for Fourier sep. fit	91		
#Fourier moments for DESCUR fit	6	Ті	Angf
PID:C5o ELM-trigger threshold	0.25		
Fit tolerance/smoothness	0.3	Rec. spline      Gaussian fit      Fit 2D	Rec. spline      Gaussian fit     Fit 2D
Fit tolerance/smoothness Throw-away threshold for outliers	0.3		
		<ul> <li>● Rec. spline Gaussian fit</li> <li>Fit 2D</li> <li>CAZ:Ti_c ✓ CEZ:Ti_c CFZ:Ti_c CHZ:Ti_c ✓ CMZ:Ti_c</li> <li>COZ:Ti c CPZ:Ti c CHZ:Ti CCZ:Ti</li> </ul>	Rec. spline     Gaussian fit     Fit 2D     CAZ:vr_c     CEZ:vr_c     CEZ:vr_c     CAZ:vr_c     CUZ:vr c     CAZ:vrot     CEZ:vrot     CEZ:vrot     CEZ:vrot
Throw-away threshold for outliers	1.0	CAZ:TI_C ♥ CEZ:TI_C CFZ:TI_C CHZ:TI_C ♥ CMZ:TI_C	CAZ:vr_c CEZ:vr_c CFZ:vr_c CHZ:vr_c CMZ:vr_c
Throw-away threshold for outliers	1.0	CAZ:TI_C ♥ CEZ:TI_C CFZ:TI_C CHZ:TI_C ♥ CMZ:TI_C COZ:TI_C CFZ:TI_C CUZ:TI_C CAZ:TI CEZ:TI	CAZ:vr_c         CEZ:vr_c         CFZ:vr_c         CHZ:vr_c         CMZ:vr_c           COZ:vr_c         CUZ:vr_c         CAZ:vrot         CEZ:vrot         CFZ:vrot

### Trview: time traces



### Trview: profiles (here Te)



0 0

0 0 0

0 0 0 0 0 0 0 0 0

0 0 0 0 0 0

0 0 0 0 0 0

0 0 0



0 0 0 0 0 0 0

#### SWG Integrated Data Analysis and Validation

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**EURO**fusion

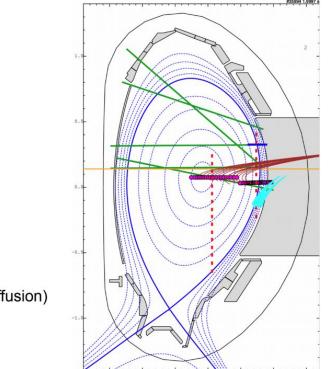


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### IDA

#### IDA at ASDEX Upgrade





multi-diagnostic profile reconstruction:  $n_{e}$ ,  $T_{e}$ Lithium beam impact excitation spectroscopy (LIB) collisional radiative model  $\rightarrow n_e(T_e)$ Interferometry measurements (DCN)  $\rightarrow n_{e}$ Electron cyclotron emission (ECE) *ECRad*: Electron cyclotron radiation transport  $\rightarrow T_e (n_e)$ Thomson scattering (TS)  $\rightarrow n_e, T_e$ Reflectometry  $\rightarrow n_e$  $\rightarrow n_{e} (Z_{eff})$ Beam emission spectroscopy Thermal Helium beam spectroscopy  $\rightarrow n_{e}, T_{e}$ 

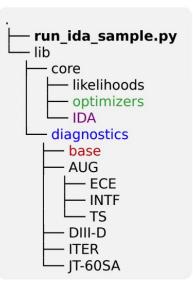
Equilibrium reconstructions for diagnostics mapping (*IDE*: kinetic Grad-Shafranov solution coupled with current diffusion)

<u>A lot of dependencies and uncertainties:</u> <u>We need a probabilistic approach!</u>

#### IDA Basic Implementation for ITER, JT-60SA, ...

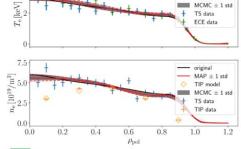
Basic implementation in python being completely modular

- to be compatible with any fusion device (ITER, DIII-D, JT-60SA, ...)
- diagnostics: Thomson scattering, ECE and interferometry, ...
- likelihoods (data uncertainty): Gaussian, Cauchy (outlier robust), ...
- multi-fidelity forward models / synthetic diagnostics
  - > ECE:  $T_{rad} = T_{e}$  vs radiation transport modeling  $T_{rad}(T_{e}, n_{e})$
  - real-time vs offline analysis
- flexible parameterisation of, e.g., profiles: splines, GPR, ...
- priors: smoothness, positivity, physical modeling, ...
- results and their uncertainties:
  - MAP solution (probability maximum and width)
  - MCMC sampling methods (explore full probability space)



#### IDA: ITER workflow

- artificial diagnostics: Thomson scattering, ECE
  - $\rightarrow$  synthetic data set with 10% noise
- 1<sup>st</sup> ITER diagnostic: Toroidal Interferometer Polarimeter (TIP)
  - $\rightarrow$  synthetic data set with 5% noise
  - $\rightarrow$  IMAS synthetic diag.



- original  $MAP \pm 1$  std

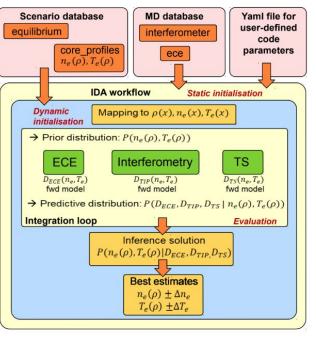
 $MCMC \pm 1$  std TS data

- MAP ±1std
- MCMC (50±34)% percentile

IMAS Interface Data Structures (IDS):

- read: TIP geometry (interferometer md), equilibrium
- write: results ...





M. Schneider

### EX2GK from gitlab.com

For first time users, it is STRONGLY RECOMMENDED to use the GUI developed for the corresponding machine to be analyzed. Note that these GUIs are developed to be executed on the local computing clusters of the machine in question.

Machine-specific GUIs are found in EX2GK/guis/<machine>/

Due to implementation of computing clusters and machine-specific options, each machine requires its own unique GUI

Aaron > EX2GK > Repository

Cosmetic! Modified labels for coordinate systems in JET GUI Aaron Ho authored 2 months ago					
master ~ EX2GK	<pre>X / EX2GK / guis</pre>	History Find file			
Name	Last commit	Last update			
12					
🗅 aug	Hotfix! Continued fixes for pages script in Cl	8 months ago			
🗅 general	Hotfix! Continued fixes for pages script in Cl	8 months ago			
🗅 jet	Cosmetic! Modified labels for coordinate systems in JET GUI	2 months ago			