



EUROfusion



Investigation of edge velocity shear generation with NBI for QH-mode in DEMO

E. Fable

MPG-IPP Garching

*Acknowledgments: P. Vincenzi (CNR, RFX Padova,
IT) for NBI input data*

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- DEMO parameters (scenario 2017):

$$\mathbf{R = 8.94\ m}$$

$$\mathbf{a = 2.94\ m}$$

$$\mathbf{B_T = 4.89\ T}$$

$$\mathbf{I_p = 19.07\ MA}$$

$$\mathbf{n_{avg} \sim 8 * 10^{19}\ m^{-3}}$$

$$\mathbf{k = 1.7}$$

$$\mathbf{triang = 0.33}$$

$$\text{- } P_{aux} \sim \text{to be calculated MW}$$

$$\text{- } P_{fus} \sim 2\ \text{GW}$$

$$\text{- } P_{rad,core} \sim 300\ \text{MW}$$

$$\text{- } P_{sep}/P_{LH} \sim 1.5$$

- QH mode requires a certain velocity shear to be triggered
[A. M. Garofalo et al., NF 2011]
- Basically, ExB shear > (value), linked to edge MHD (i.e. Alfvén speed)
- The dimensionless criterion chosen here is (0.16 is arbitrary):

$$- \quad \frac{a}{V_A} a \frac{d\Omega}{dr} \approx 0.16;$$

$$V_A = \frac{B}{\sqrt{(\mu_0 n M)}}; \quad E_r = B_\varphi (V_{dia} - V_\theta) + B_\theta V_\varphi$$

$$\Omega = \frac{E_r}{R B_\theta} = \frac{B_\varphi}{R B_\theta} (V_{dia} - V_\theta) + \frac{V_\varphi}{R} = \frac{q}{r} (V_{dia} - V_\theta) + \frac{V_\varphi}{R};$$

- where a is the minor radius, r is the local minor radius

- Note that V_{dia} is large and negative, i.e. it is much more convenient to inject counter-current toroidal rotation rather than co-current

- Applying the criterion for DEMO we get ($w_{ped} = 15$ cm):

$$- \quad \frac{a}{V_A} a \frac{d\Omega}{dr} \approx 0.16; \quad \frac{d\Omega}{dr} \approx \frac{\Omega}{w_{ped}}$$
$$\rightarrow \Omega \approx 2.55 \cdot 10^4 [rad/s] \rightarrow V_E \approx -19 km/s$$

- First estimate of “natural” (i.e. without rotation) edge shear is

$$V_E \sim -8 km/s$$

- Missing ~ -10 km/s of perpendicular rotation, that is ~ -120 km/s of toroidal rotation which have to come from NBI counter-current injection (or $\sim +360$ km/s from co-current torque)

- So... how much torque is required to drive ~ -120 km/s of pedestal top rotation?

- Assuming that the angular momentum confinement time in the edge is the same as the energy confinement time, this would mean a torque of:

Torque for DEMO



- So... how much torque is required to drive ~ -100 km/s of pedestal top rotation?

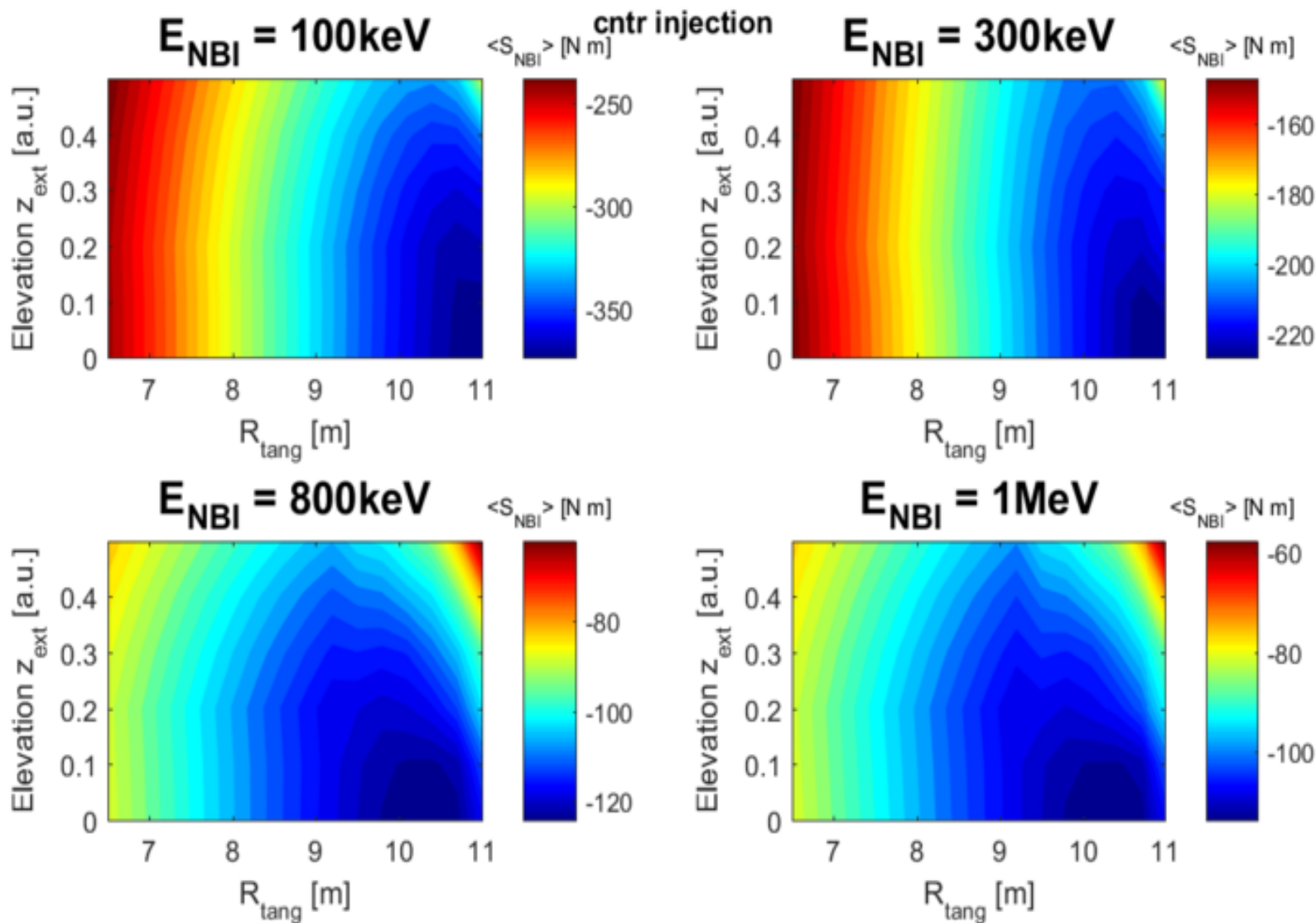
- Assuming that the angular momentum confinement time in the edge is the same as the energy confinement time, this would mean a torque of:

$$S \chi_{\varphi} n R M \frac{V_{\varphi}}{w_{ped}} = T_{\varphi}$$

$$S = 1320 [m^2]; \quad \chi_{\varphi} \approx 0.25; \quad n = 4.2$$
$$T_{\varphi} [Nm] \approx 400 [Nm]$$

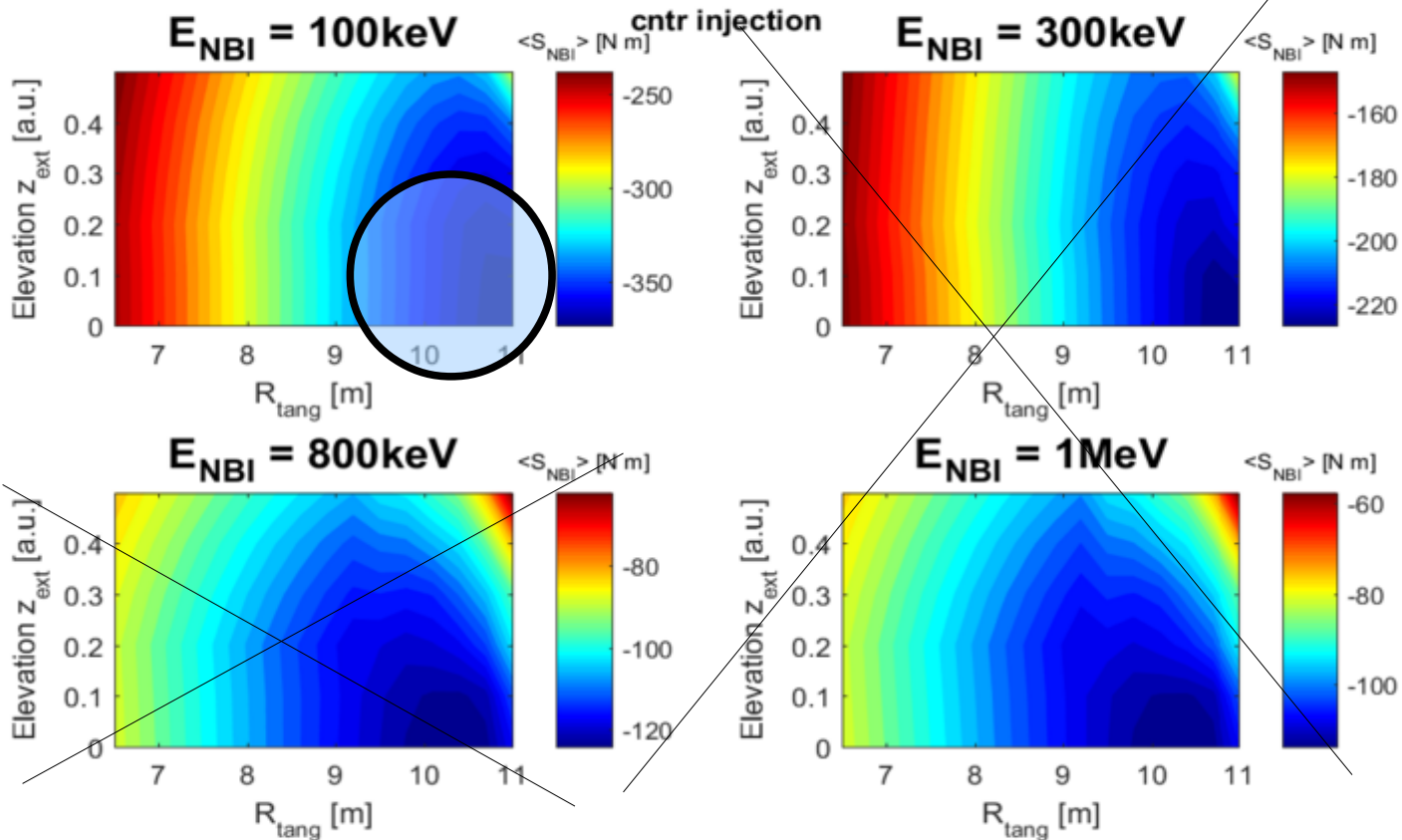
- very rough calculation, to be done with ASTRA properly.
- Result: confirmed by ASTRA

Results from P. Vincenzi @ 76 MW



Operational space @ 76 MW

- very narrow operational space
- expect linearity in power, which would make e.g. 300 keV available @ 140 MW



- If a dimensionless parameter for the QH mode entrance is assumed, for DEMO this leads to a certain requirements in edge radial electric field shearing
 - as already mentioned by Pietro, needs large torque
- Since DEMO naturally has already a rather large counter-current $E \times B$ rotation, to reach the desired value it is better to inject counter-current torque to add the remaining rotation on top of the natural rotation
- This remaining counter-current rotation/torque is estimated and is the ultimate result of the study. The relation by torque and power is provided by the work done by P. Vincenzi
- Regarding pedestal rotation vs torque, the model assumes a pedestal confinement time which is the same in angular momentum as well as in ion energy, and given by the local transport coefficients
 - to check against experimental evidence

- The chosen criterion is just the DIII-D one times a machine size to make it dimensionless → absolutely no first principles here
- It could be that the reality is more favourable (more unfavourable means no QH-mode)
- Present results show that with the assumptions used here the required torque is at the limit of the lowest energy, highest tangency radius cases done by Pietro.
- Main things to improve:
 - QH criterion
 - pedestal transport model for toroidal rotation