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Status update Implementation of 3 fields edge plasma model in the EBC HDG code

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Motivation

- Why HDG-approach?
 - Allows detailed geometrical description of the wall
 - Grid flexibility
 - High order, p-adaptivity
 - Highly parallelizable
 - Cheaper than standard implicit FEM
- Drawbacks HDG-approach?
 - $_{\circ}$ High order \Rightarrow badly conditioned matrices





The 3-field mean-field model

• Continuity, plasma

$$\partial_t n + \nabla \cdot \left(\left(\frac{\Gamma_{||}}{n} \boldsymbol{b} \right) n - D \nabla_{\perp} n \right) = S_n$$

- Parallel momentum, plasma $\partial_{t}(\Gamma_{||}) + \nabla \cdot \left(\left(\frac{\Gamma_{||}}{n} \boldsymbol{b} - \frac{D}{n} \nabla_{\perp} n \right) \Gamma_{||} + (\boldsymbol{b}) n c_{s}^{2} - \frac{1}{mn} \mu_{||} \boldsymbol{b} \nabla_{||}(\Gamma_{||}) - \frac{1}{mn} \mu_{\perp} \nabla_{\perp}(\Gamma_{||}) + \frac{\Gamma_{||}}{mn^{2}} \mu_{||} \boldsymbol{b} \nabla_{||}(n) + \frac{\Gamma_{||}}{mn^{2}} \mu_{\perp} \nabla_{\perp}(n) \right)$ $= \frac{1}{m} S_{u_{||}} + \frac{1}{m} p \nabla \cdot \boldsymbol{b}$
- Continuity, neutrals (AFN) $\partial_t n_n + \nabla \cdot \left(\left(\frac{n_{n,eq} \Gamma_{||}}{n n_n} \boldsymbol{b} \right) n_n - D_n^p T \nabla(n_n) - D_n^p n_n \nabla(T) \right) = -S_n$ $n_{n,eq} = \frac{n^2 K_r + n_n n K_{cx,m}}{n K_i + n K_{cx,m}}$ $D_n^p = \frac{1}{m(n K_i + n K_{cx,m})}$
- Sources: ionization, recombination, charge-exchange

The 3-field mean-field model, normalized

$$\begin{aligned} \partial_t n + \nabla \cdot \left(\left(\frac{\Gamma_{||}}{n} \boldsymbol{b} \right) n - D \nabla_{\perp} n \right) &= S_n \\ \partial_t (\Gamma_{||}) + \nabla \cdot \left(\left(\frac{\Gamma_{||}}{n} \boldsymbol{b} - \frac{D}{n} \nabla_{\perp} n \right) \Gamma_{||} + M_0(\boldsymbol{b}) n(T_i + T_e) - \frac{1}{n} \mu_{||} \boldsymbol{b} \nabla_{||} (\Gamma_{||}) - \frac{1}{n} \mu_{\perp} \nabla_{\perp} (\Gamma_{||}) + \frac{\Gamma_{||}}{n^2} \mu_{||} \boldsymbol{b} \nabla_{||}(n) + \frac{\Gamma_{||}}{n^2} \mu_{\perp} \nabla_{\perp}(n) \right) \\ &= S_{u_{||}} + M_0 n(T_i + T_e) \nabla \cdot \boldsymbol{b} \\ \partial_t n_n + \nabla \cdot \left(\left(\frac{n_{n,eq} \Gamma_{||}}{n n_n} \boldsymbol{b} \right) n_n - D_n^p T \nabla(n_n) - D_n^p n_n \nabla(T) \right) = -S_n \end{aligned}$$

 \Rightarrow coupled advection-diffusion-reaction equations for $U = \{U_1, U_2, U_3\}^T = \{n, \Gamma_{||}, n_n\}^T$

$$\partial_t \boldsymbol{U} + \boldsymbol{\nabla} \cdot (\boldsymbol{C}(\boldsymbol{U}) + \boldsymbol{C}_p(\boldsymbol{U}) + \boldsymbol{K}(\boldsymbol{U})\boldsymbol{q}) = \boldsymbol{S}(\boldsymbol{U}), \qquad \boldsymbol{q} + \nabla_{\perp} \boldsymbol{U} = 0$$

Solution with HDG approach

- Implementation: models & operators
 - Model: build matrix contributions at the element level
 - Operator: construct contributions from individual terms in the model
 - Flexibility to implement different models and discretization options

$$\begin{bmatrix} A_{uu} & A_{uq} & A_{ul} \\ A_{qu} & A_{qq} & A_{ql} \\ A_{lu} & A_{lq} & A_{ll} \end{bmatrix} \begin{bmatrix} u \\ q \\ \lambda \end{bmatrix} = \begin{bmatrix} B_u \\ B_q \\ B_l \end{bmatrix} \quad \begin{array}{c} \text{model eq.} \\ q + \nabla u = 0 \\ \text{trace eq.} \end{array}$$





Breakdown into operators

• Advection operator: explicit, upwind

$$oldsymbol{C}(oldsymbol{U}) = egin{bmatrix} oldsymbol{U}_1 \mathbf{v}_1 \ \ldots \ oldsymbol{U}_{\mathrm{nEq}} \mathbf{v}_{\mathrm{nEq}} \end{bmatrix}$$

• Diffusion operator: implicit

• Time lagging for the advection velocities & diffusion matrix: evaluate with solution at time step *n*

Breakdown into operators

• Reaction (implicit, time-lagging) and source (explicit) operators

$$\boldsymbol{S}(\boldsymbol{U}) = \begin{bmatrix} R_{1,1}(\boldsymbol{U}) & R_{1,2}(\boldsymbol{U}) & \dots & R_{1,\mathrm{nEq}}(\boldsymbol{U}) \\ \dots & \dots & \dots & \dots \\ R_{\mathrm{nEq},1}(\boldsymbol{U}) & R_{\mathrm{nEq},2}(\boldsymbol{U}) & \dots & R_{\mathrm{nEq},\mathrm{nEq}}(\boldsymbol{U}) \end{bmatrix} \begin{bmatrix} \boldsymbol{U}_1 \\ \dots \\ \boldsymbol{U}_{\mathrm{nEq}} \end{bmatrix}$$
$$\boldsymbol{S}(\boldsymbol{U}) = \begin{bmatrix} f_1(\boldsymbol{U}) \\ \dots \\ f_{\mathrm{nEq}}(\boldsymbol{U}) \end{bmatrix}$$

Simple advection-diffusion-reaction model

• Single advection-diffusion-reaction equation with linear analytical solution $\bar{u} = 0.1x + 0.2y + 0.3$

$$\partial_t u + \nabla \cdot (u \boldsymbol{v} - D \nabla u) = S - R u \quad \text{on} \quad \Omega$$

 $u = \bar{u}|_{\partial \Omega} \quad \text{on} \quad \partial \Omega$

Solenoidal velocity field $\boldsymbol{v} = \{-0.2, 0.1\}^T$; constant, isotropic diffusion tensor DSource chosen to have constant R and $S = R\bar{u}$

• *N* coupled equations, linear analytical solutions $\bar{u}_i = i\bar{u}$

$$\begin{array}{ll} \partial_t u_i + \boldsymbol{\nabla} \cdot \left(u_i \boldsymbol{v} - \sum_{j=1,N} D_{i,j} \nabla u_j \right) = S_i - \sum_{j=1,N} R_{i,j} u_j \quad \text{on} \quad \Omega \\ u_i = \bar{u}_i |_{\partial \Omega} & \begin{array}{c} \text{on} \quad \partial \Omega \\ \text{Same velocity field; isotropic diffusion tensor with } D_{i,j} = \frac{i}{jN} D \end{array}; \text{ source rate } R_{i,j} = \frac{i}{jN} R \end{array}$$

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Simple advection-diffusion-reaction model

Solution (-)



Error (-)







Diffusion equation, arbitrary element order



Toy interchange model

• 2-field model

$$\partial_t n + \nabla \cdot (n \boldsymbol{u}_E - D_\perp \nabla_\perp n) = 0$$
$$n - \nabla \cdot \left(\frac{\nabla_\perp \phi}{B}\right) = 0$$

- Introduced option to add/remove time dependent term per equation
- MMS tested (Dirichlet BCs)



Preliminary results 3-field model, sheath BCs



Parallel flux

Preliminary results 3-field model, sheath BCs

1.00 1.00 0.6 0.6 0.98 0.98 0.4 0.4 0.2 0.2 0.96 0.96 0.0 0.0 - 0.94 - 0.94 -0.2 -0.2 -0.4-0.40.92 0.92 -0.6 -0.60.90 0.90 2.0 2.2 2.4 2.6 2.8 2.0 2.2 2.4 2.6 3.0 2.8 3.0

After a few iterations

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Ion density

Initial state

Preliminary results 3-field model, sheath BCs



Neutral density