



A projection-based approach to handle polar singularities with tensor-product splines

TSVV 10 meeting

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Outline

Motivation

“logical” vs “physical” field spaces

Projection-based approach: a different perspective

Characterizing the pre-polar spline spaces

Computing the conforming projections

Numerical validation in Psydac

Summary



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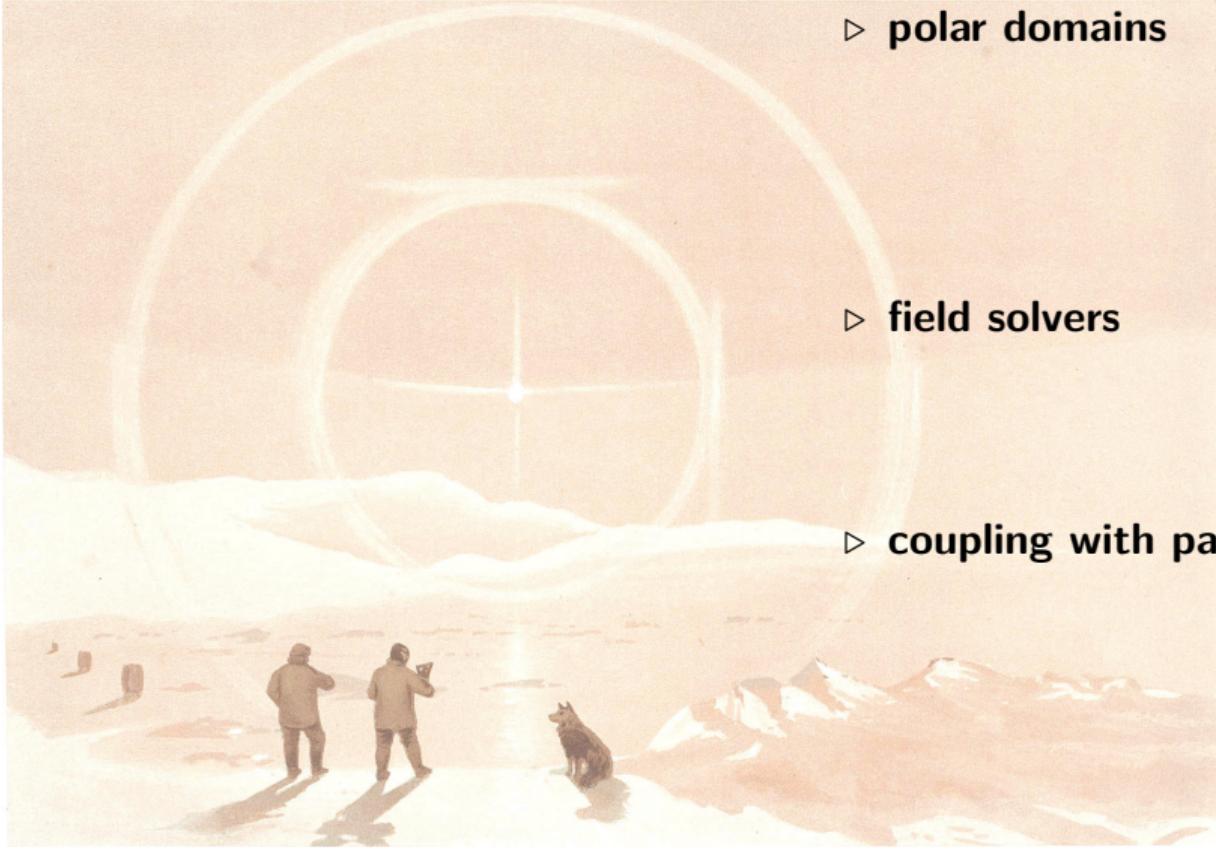
Motivation



Edward L. Moss "Shores of the Polar Sea. A Narrative of the Arctic Expedition of 1875-6"



Motivation



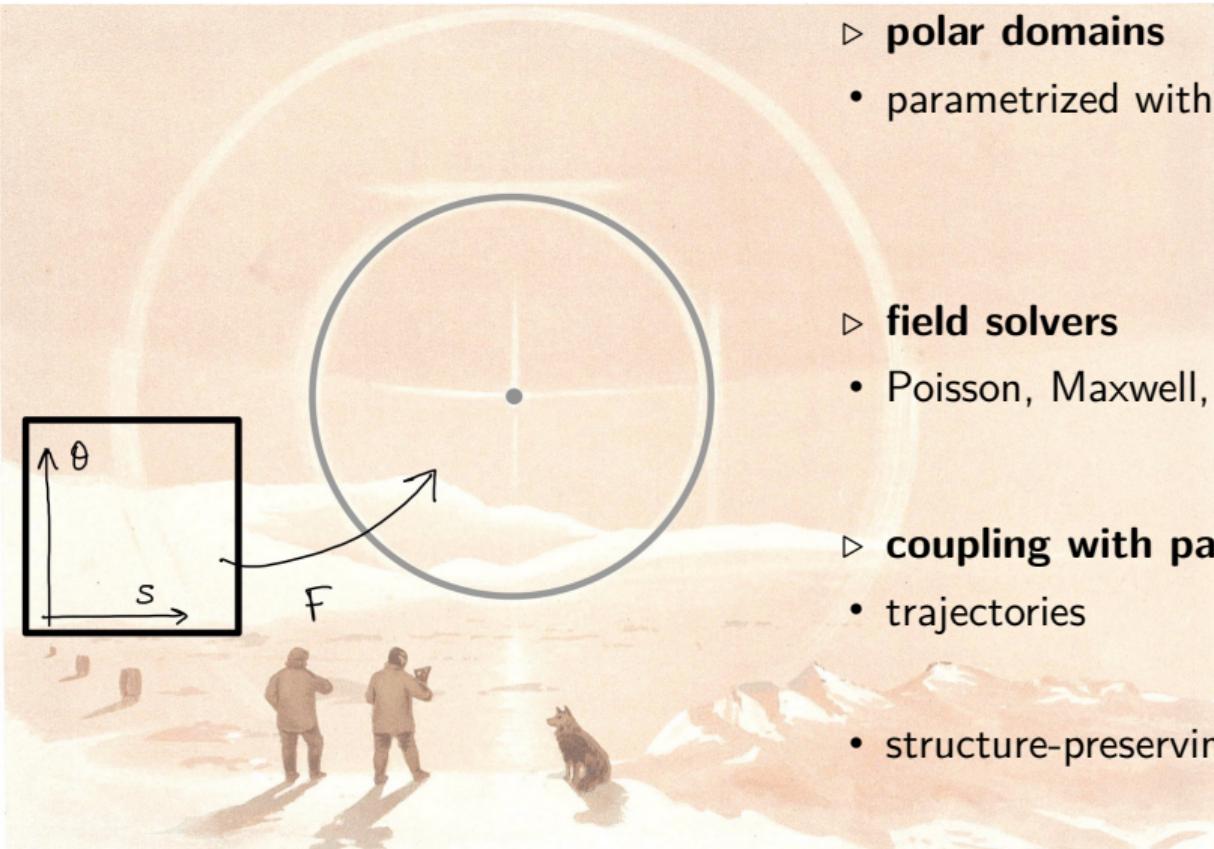
▷ **polar domains**

▷ **field solvers**

▷ **coupling with particles**



Motivation



- ▷ **polar domains**

- parametrized with tensor-product splines

- ▷ **field solvers**

- Poisson, Maxwell, curl-curl ...

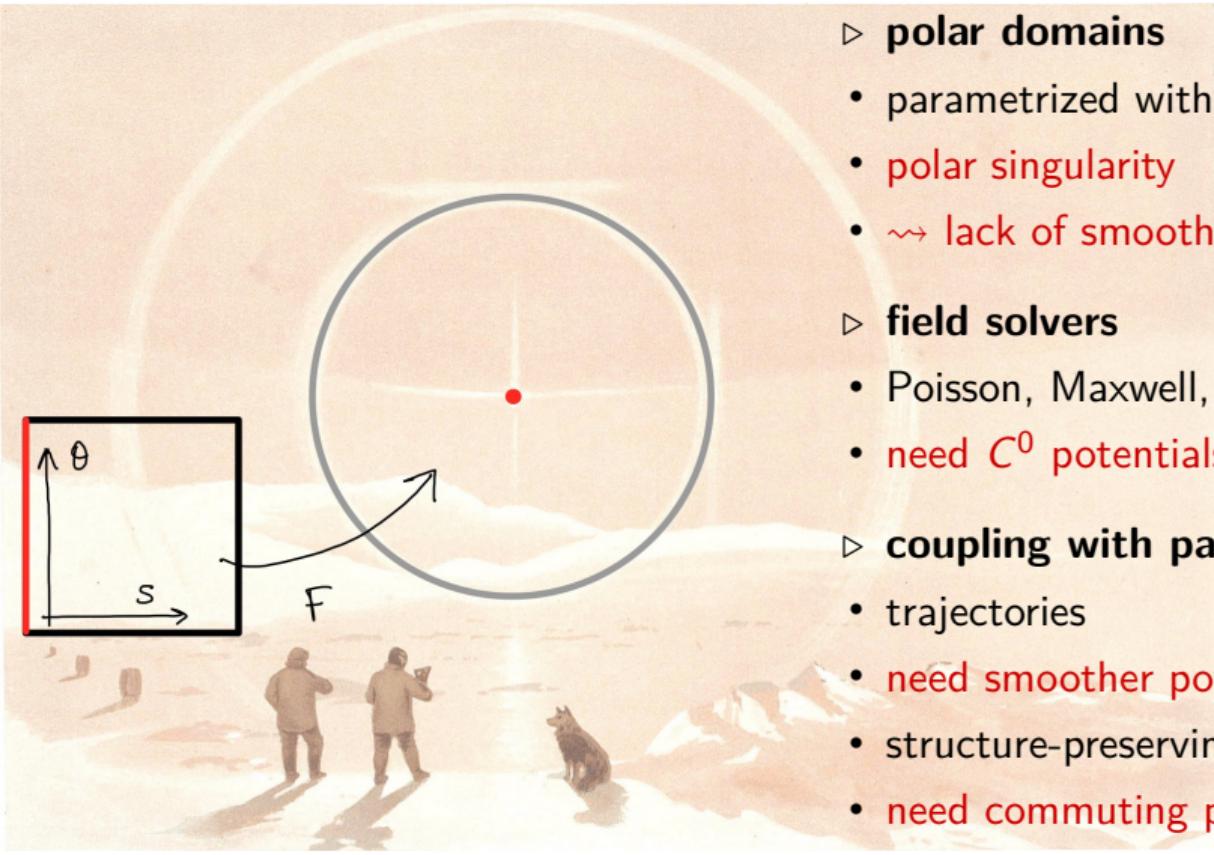
- ▷ **coupling with particles**

- trajectories

- structure-preserving coupling



Motivation



▷ polar domains

- parametrized with tensor-product splines
- polar singularity
- \rightsquigarrow lack of smoothness (and integrability!)

▷ field solvers

- Poisson, Maxwell, curl-curl ...
- need C^0 potentials, $H(\text{curl})$ fields

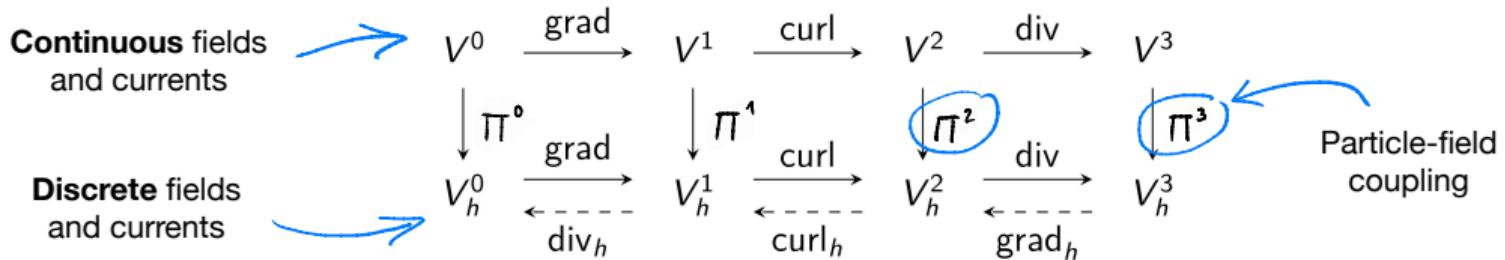
▷ coupling with particles

- trajectories
- need smoother potentials and fields
- structure-preserving coupling
- need commuting projections



A word about particles

- Variational particle-field discretization in generic commuting de Rham complexes



- Action Principle with **discrete Lagrangian** $\mathcal{L}_h(\mathbf{X}_N, \mathbf{X}'_N, \mathbf{V}_N, \mathbf{A}_h, \mathbf{A}'_h, \phi_h)$
- gauge-free FEM-PIC** scheme with

$$\begin{cases} \mathbf{E}_h = -\text{grad}_h \phi_h - \partial_t \mathbf{A}_h & (\text{in } V_h^2) \\ \mathbf{B}_h = \text{curl}_h \mathbf{A}_h & (\text{in } V_h^1) \end{cases}$$

- Hamiltonian** structure¹: energy stability, discrete Casimirs (Gauss laws ...)

¹Kraus-Kormann-Morrison-Sonnendrücker ('17), CP-Kormann-Sonnendrücker ('21)



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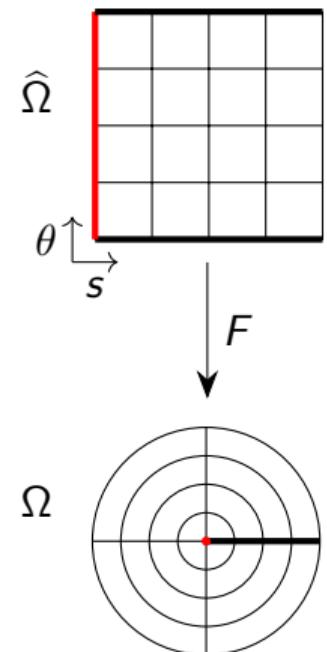


IL
BUONO
IL
BRUTTO
IL
CATTIVO

Sergio Leone, “Il buono, il brutto, il cattivo” (1966)



“logical” vs “physical” field spaces: the Good, the Bad and the Ugly



$$\begin{array}{ccccc}
 \widehat{W}_h^0 \ (\subset H^1(\hat{\Omega})) & \xrightarrow{\text{grad}} & \widehat{W}_h^1 \ (\subset H(\text{curl}; \hat{\Omega})) & \xrightarrow{\text{curl}} & \widehat{W}_h^2 \ (\subset L^2(\hat{\Omega})) \\
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- Push-forward operators:

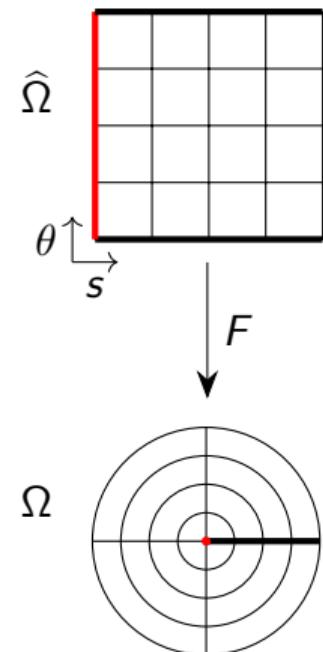
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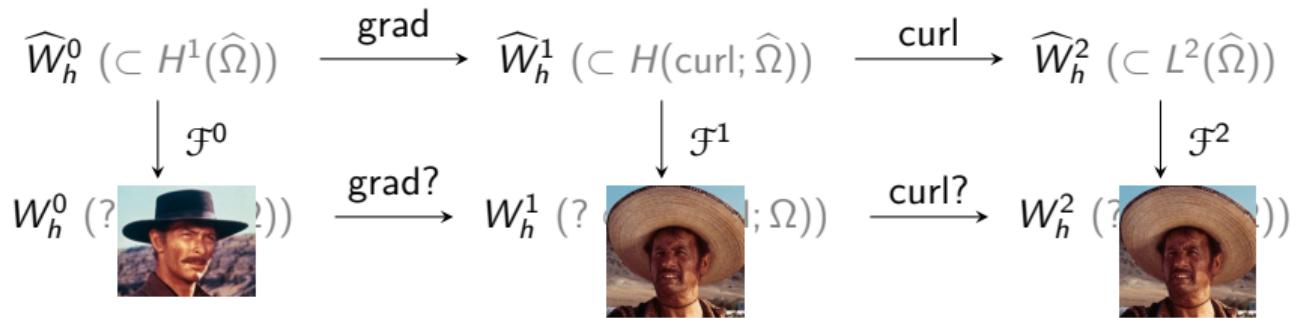
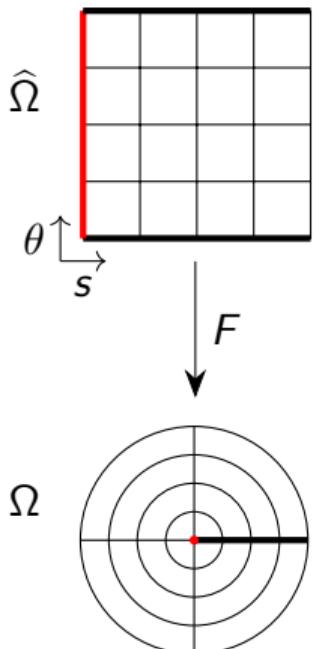
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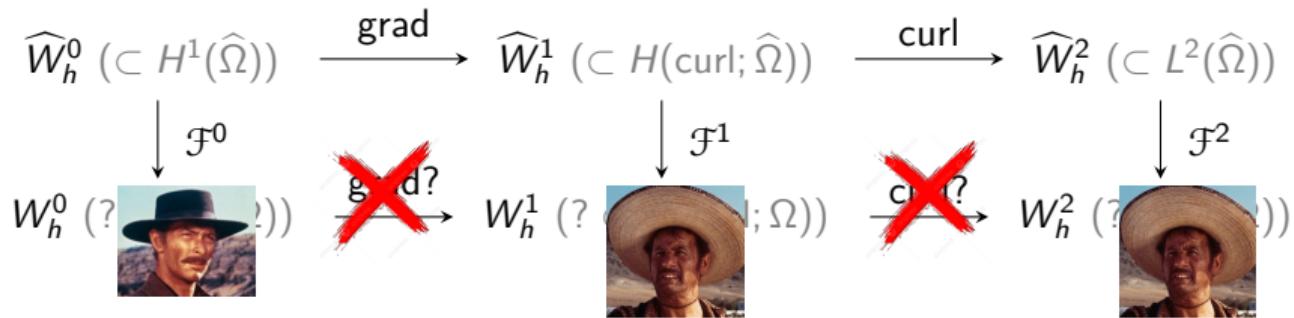
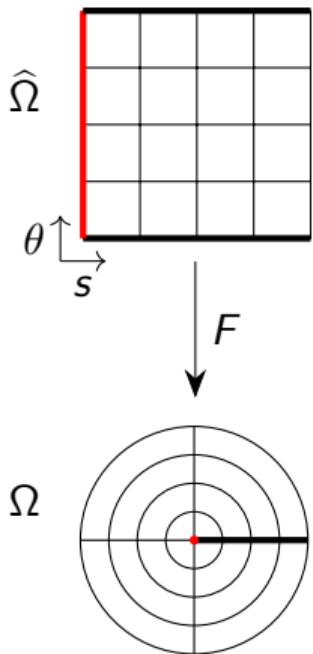
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- with polar map: $DF^{-T} = \begin{pmatrix} \cos \theta & -\frac{1}{s} \sin \theta \\ \sin \theta & \frac{1}{s} \cos \theta \end{pmatrix} \implies \mathbf{E}, \beta \notin L^2(\Omega)!$



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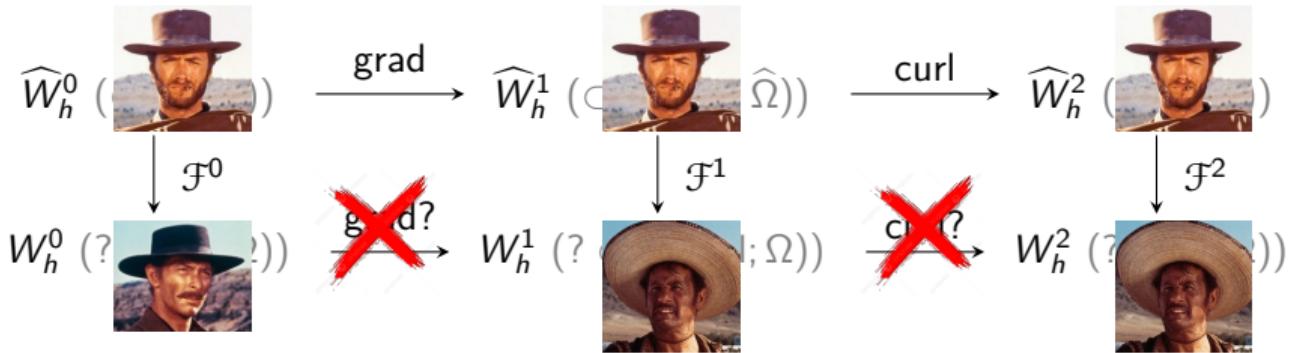
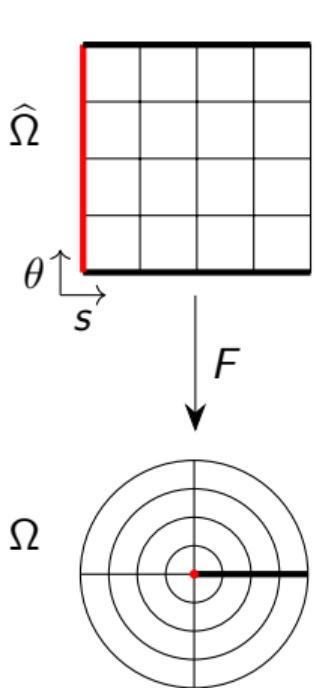
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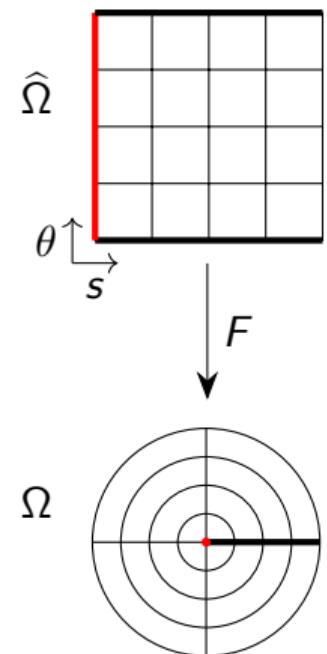
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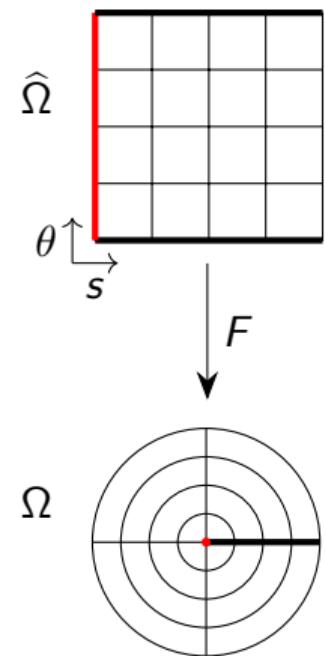
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- Existing solution: use smooth **polar splines** (**non tensor-product**) $V^\ell \subset W^\ell$
- Here: use **tensor-product splines** and project to $\hat{V}^\ell \subset \hat{W}^\ell$ s.t. $\mathcal{F}^\ell \hat{V}^\ell = V^\ell$



Bibliography on polar splines

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-  E. Zoni & Y. Güclü *Solving hyperbolic-elliptic problems on singular mapped disk-like domains with the method of characteristics and spline finite elements*, Journal of Computational Physics 398 (2019): 10889.
-  D. Toshniwal & T. J. Hughes *Isogeometric discrete differential forms: Non-uniform degrees, Bézier extraction, polar splines and flows on surfaces*, Computer Methods in Applied Mechanics and Engineering 376 (2021): 113576.
-  F. Patrizi *Isogeometric de Rham complex discretization in solid toroidal domains*, arXiv:2106.10470 [math.NA] (2021).
-  F. Holderied & S. Possanner *Magneto-hydrodynamic eigenvalue solver for axisymmetric equilibria based on smooth polar splines*, Journal of Computational Physics 464 (2022): 111329.
-  A. Bhole, B. Nkonga, S. Pamela, G. Huijsmans, M. Hoelzl & JOREK team *Treatment of polar grid singularities in the bi-cubic Hermite*, Journal of Computational Physics 471 (2022): 111611.



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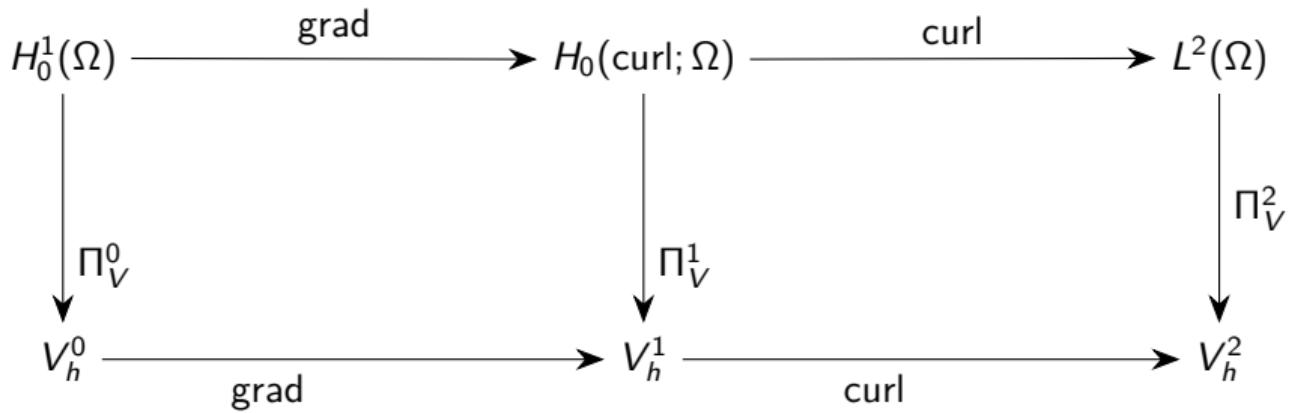
Projection-based approach: a different perspective



Paolo Uccello, "Battaglia di San Romano" (1438)



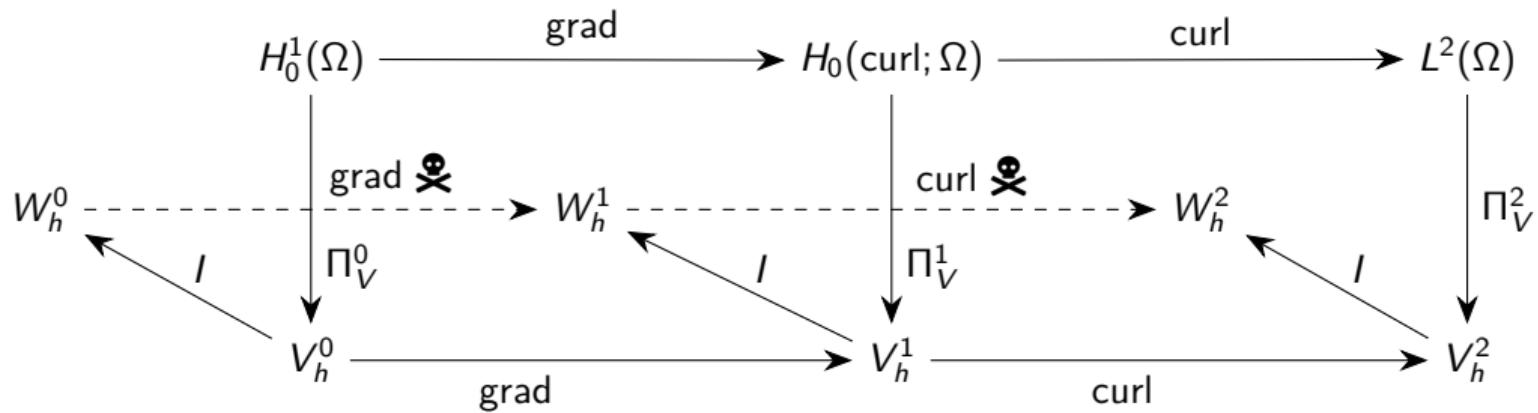
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- Objective #1: commuting de Rham diagram of polar splines



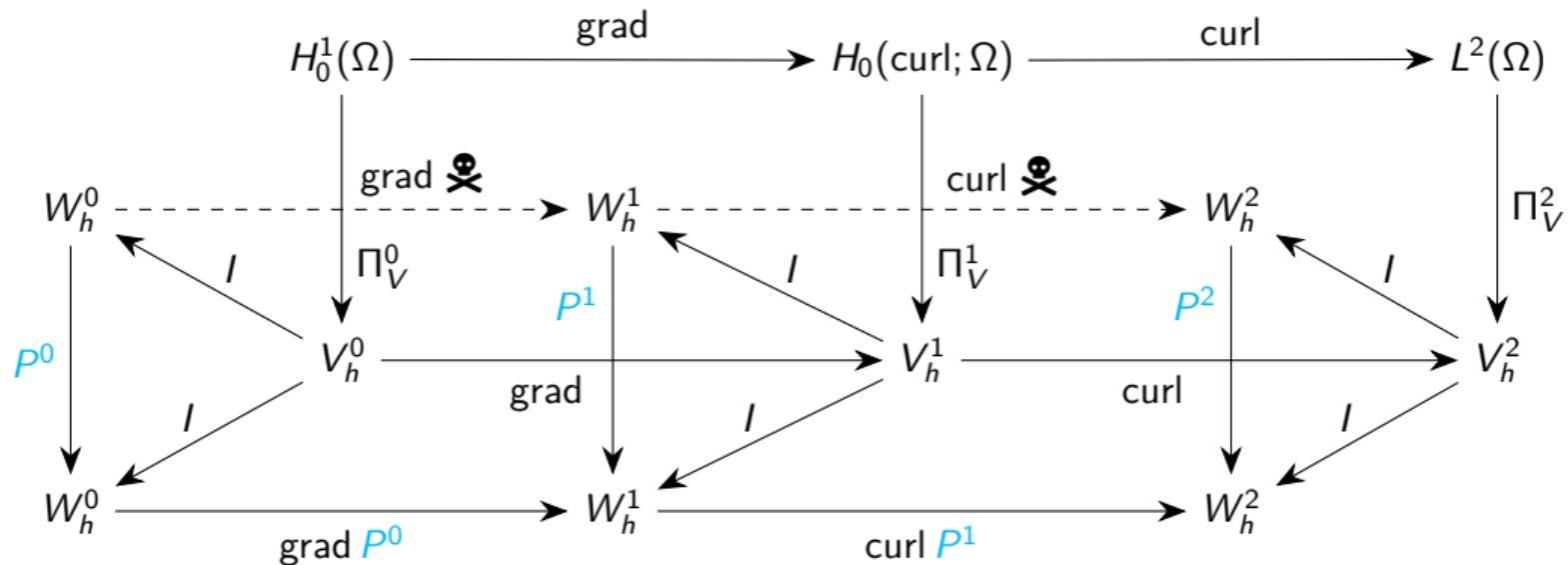
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- Objective #1: commuting de Rham diagram of polar splines
- Objective #2: work with tensor-product splines



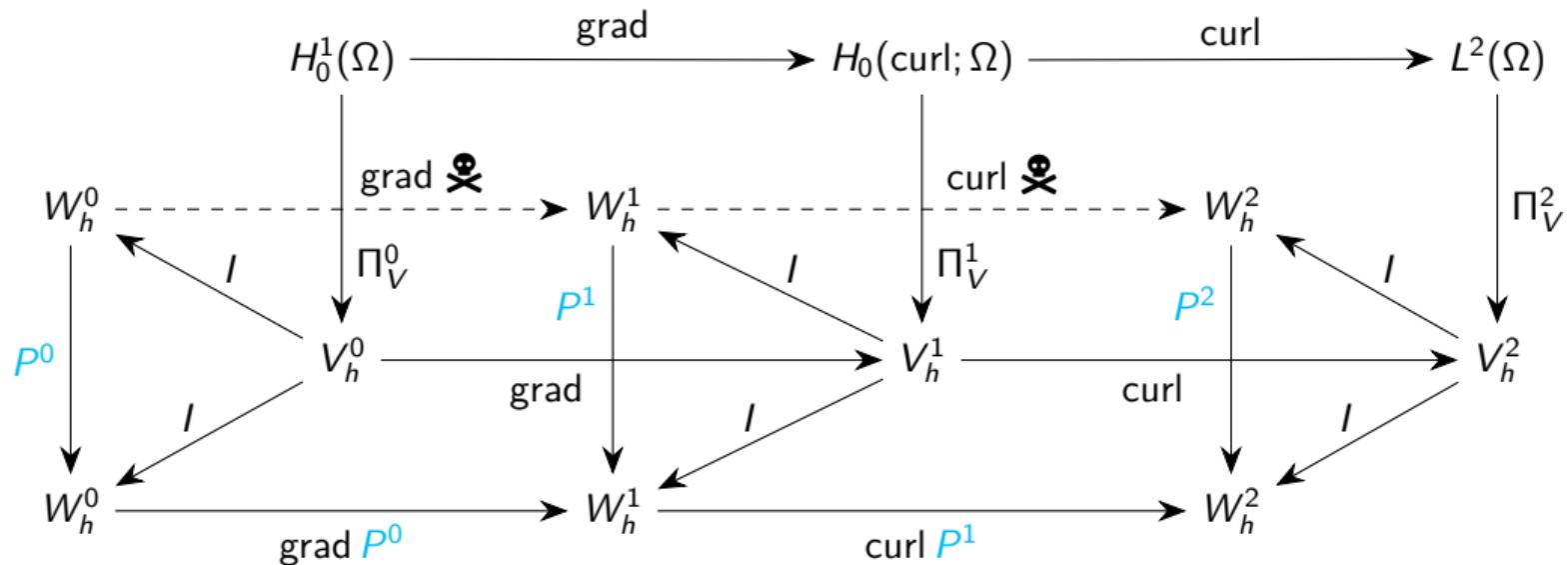
Projection-based approach: a different perspective



- Objective #1: commuting de Rham diagram of polar splines
- Objective #2: work with tensor-product splines
- Idea: use **conforming projections**, not conforming bases



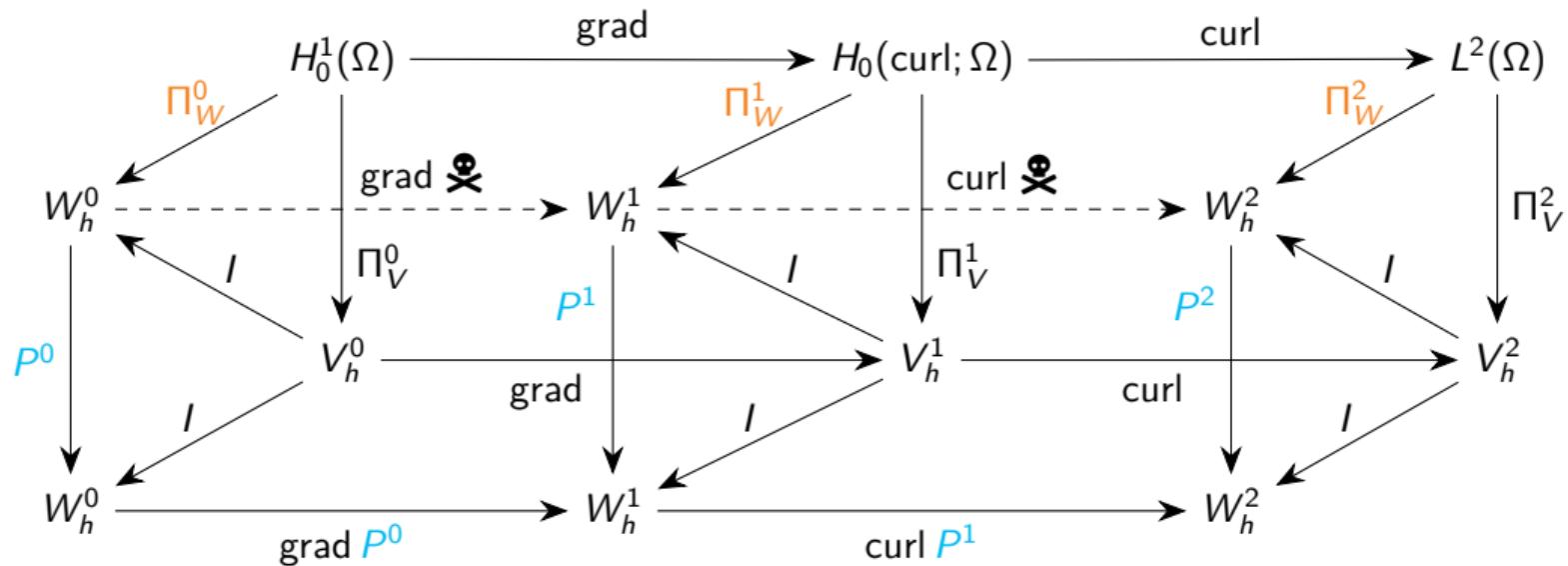
Projection-based approach: a different perspective



- **Advantage #1:** allows re-use of full tensor-product splines spaces and operators
- **Advantage #2:** similar treatment of multi-patch domains (broken-FEBC)



Projection-based approach: a different perspective



- **Advantage #1:** allows re-use of full tensor-product splines spaces and operators
- **Advantage #2:** similar treatment of multi-patch domains (broken-FEBC)
- **⚠ design of good conforming projections → careful design**



Conforming vs. projection-based (CONGA) approach: Poisson

- Model and conforming discretization:

$$\begin{cases} -\Delta \phi = f & \text{in } \Omega \\ \phi = 0 & \text{on } \partial\Omega, \end{cases} \rightsquigarrow \mathbb{S}_p \phi_p = \mathbf{f}_p$$

with $(\mathbb{S}_p)_{a,b} = \int_{\Omega} \nabla \Lambda_a^{0,p} \cdot \nabla \Lambda_b^{0,p} dx dy$ the stiffness matrix in the **polar spline basis**.

- CONGA discretization:

$$(\alpha(\mathbb{I} - \mathbb{P}^0)^T \mathbb{M} (\mathbb{I} - \mathbb{P}^0) + (\mathbb{P}^0)^T \mathbb{S} \mathbb{P}^0) \phi = (\mathbb{P}^0)^T \mathbf{f}$$

with $\alpha > 0$ and

$$\begin{cases} \mathbb{M}^0, \mathbb{S} : \text{the mass and stiffness matrices in the full spline basis.} \\ \mathbb{P}^0 : \text{the projection matrix onto the polar splines, in the full spline basis.} \end{cases}$$



Conforming vs. projection-based (CONGA) approach: Maxwell

- Model and conforming discretization:

$$\begin{cases} \partial_t B + \operatorname{curl} \mathbf{E} = 0, \\ \frac{1}{c^2} \partial_t \mathbf{E} - \operatorname{curl} B = 0, \end{cases} \rightsquigarrow \begin{cases} \partial_t \mathbf{B}_p + \mathbb{C}_p \mathbf{E}_p = 0 \\ \partial_t \tilde{\mathbb{M}}_p^1 \mathbf{E}_p - \mathbb{C}_p^T \tilde{\mathbb{M}}_p^2 \mathbf{B}_p = 0 \end{cases}$$

with curl and mass matrices in the [polar spline basis](#).

- CONGA discretization:

$$\begin{cases} \partial_t \mathbf{B} + \mathbb{C}\mathbb{P}^1 \mathbf{E} = 0 \\ \partial_t \tilde{\mathbb{M}}^1 \mathbf{E} - (\mathbb{C}\mathbb{P}^1)^T \tilde{\mathbb{M}}^2 \mathbf{B} = 0 \end{cases}$$

with curl and (regularized) mass matrices in the [full spline basis](#)

- Note: \triangleleft the mass matrices [must be regularized](#) because $W_h^1, W_h^2 \not\subset L^2(\Omega)$.

We set: $\tilde{\mathbb{M}}^\ell := \frac{1}{n_s n_\theta} (\mathbb{I} - \mathbb{P}^\ell)^T (\mathbb{I} - \mathbb{P}^\ell) + (\mathbb{P}^\ell)^T \mathbb{M}^\ell \mathbb{P}^\ell$



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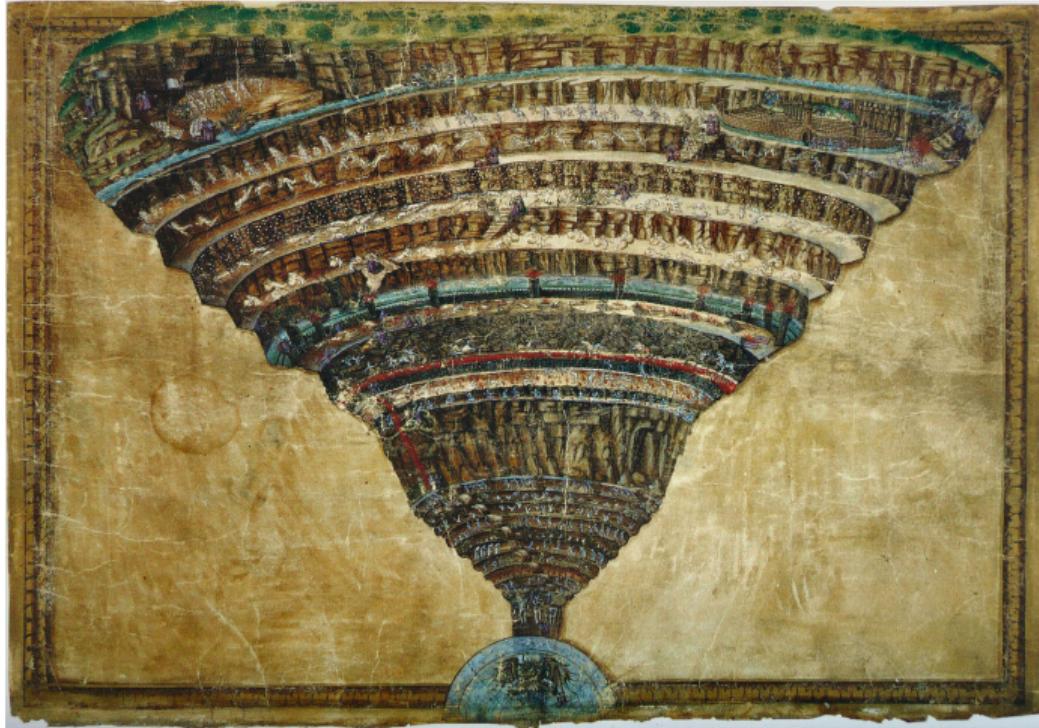
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Characterizing the pre-polar spline spaces



Sandro Botticelli, "Mappa dell' Inferno" (ca 1490)



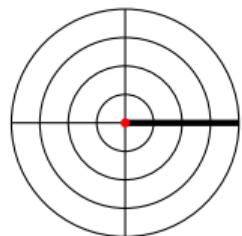
Characterizing the pre-polar spline spaces

$\hat{\Omega}$

θ

F

Ω



$$F : \begin{pmatrix} s \\ \theta \end{pmatrix} \rightarrow \sum_{i,j} \rho_i \begin{pmatrix} \cos \theta_j \\ \sin \theta_j \end{pmatrix} B_i(s) \mathring{B}_k(\theta) \quad \text{with} \quad \begin{cases} \rho_i := \frac{i}{n_s - 1} & 0 \leq i < n_s \\ \theta_j := \frac{2\pi k}{n_\theta} & 0 \leq j < n_\theta \end{cases}$$

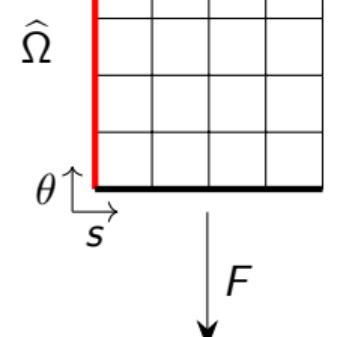
$$\begin{cases} \widehat{W}_h^0 = \mathbb{S}^{p_s, p_\theta} = \text{Span} \{ \widehat{\Lambda}_{ij}^0 := B_i(s) \mathring{B}_j(\theta) \} \\ \widehat{W}_h^1 = \begin{pmatrix} \mathbb{S}^{p_s-1, p_\theta} \\ \mathbb{S}^{p_s, p_\theta-1} \end{pmatrix} = \text{Span} \left\{ \widehat{\Lambda}_{ij}^{1,s} = \begin{pmatrix} M_i(s) \mathring{B}_j(\theta) \\ 0 \end{pmatrix}, \widehat{\Lambda}_{ij}^{1,\theta} = \begin{pmatrix} 0 \\ B_i(s) \mathring{M}_j(\theta) \end{pmatrix} \right\} \\ \widehat{W}_h^2 = \text{Span} \{ \widehat{\Lambda}_{ij}^2 = M_i(s) \mathring{M}_j(\theta) \} \end{cases}$$

- Pre-polar spline spaces:

(\triangle now $F \in (\mathbb{S}^{p_s, p_\theta})^2$)



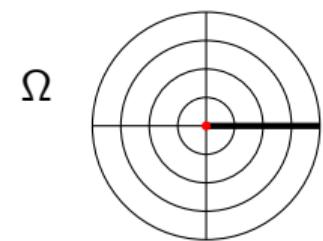
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$$F : \binom{s}{\theta} \rightarrow \sum_{i,j} \rho_i \begin{pmatrix} \cos \theta_j \\ \sin \theta_j \end{pmatrix} B_i(s) \mathring{B}_k(\theta) \quad \text{with} \quad \begin{cases} \rho_i := \frac{i}{n_s - 1} & 0 \leq i < n_s \\ \theta_j := \frac{2\pi k}{n_\theta} & 0 \leq j < n_\theta \end{cases}$$

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- Pre-polar spline spaces: C^0 sequence

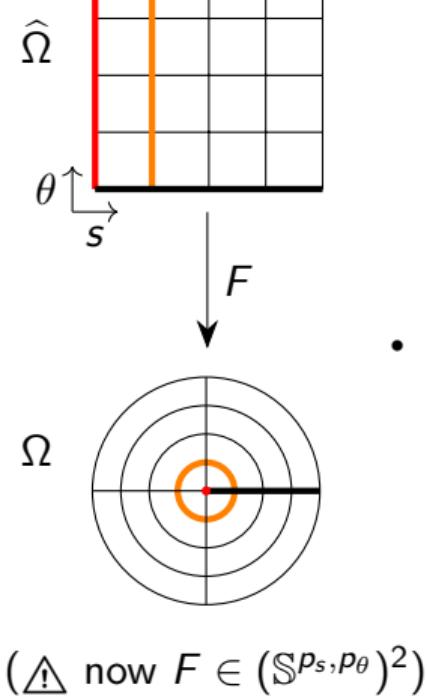


(⚠ now $F \in (\mathbb{S}^{p_s, p_\theta})^2$)

$$\begin{cases} \widehat{V}_h^0 = \{ \hat{\phi} \in \widehat{W}_h^0 : \mathcal{F}^0 \hat{\phi} \in C^0(\Omega) \} \\ \widehat{V}_h^1 = \{ \widehat{\mathbf{E}} \in \widehat{W}_h^1 : \mathcal{F}^1 \widehat{\mathbf{E}} \in H(\text{curl}; \Omega) \} \\ \widehat{V}_h^2 = \{ \hat{\beta} \in \widehat{W}_h^2 : \mathcal{F}^2 \hat{\beta} \in L^2(\Omega) \} \end{cases}$$



Characterizing the pre-polar spline spaces



$$F : \binom{s}{\theta} \rightarrow \sum_{i,j} \rho_i \begin{pmatrix} \cos \theta_j \\ \sin \theta_j \end{pmatrix} B_i(s) \mathring{B}_k(\theta) \quad \text{with} \quad \begin{cases} \rho_i := \frac{i}{n_s - 1} & 0 \leq i < n_s \\ \theta_j := \frac{2\pi k}{n_\theta} & 0 \leq j < n_\theta \end{cases}$$

$$\begin{cases} \widehat{W}_h^0 = \mathbb{S}^{p_s, p_\theta} = \text{Span} \{ \widehat{\Lambda}_{ij}^0 := B_i(s) \mathring{B}_j(\theta) \} \\ \widehat{W}_h^1 = \begin{pmatrix} \mathbb{S}^{p_s-1, p_\theta} \\ \mathbb{S}^{p_s, p_\theta-1} \end{pmatrix} = \text{Span} \left\{ \widehat{\Lambda}_{ij}^{1,s} = \begin{pmatrix} M_i(s) \mathring{B}_j(\theta) \\ 0 \end{pmatrix}, \widehat{\Lambda}_{ij}^{1,\theta} = \begin{pmatrix} 0 \\ B_i(s) \mathring{M}_j(\theta) \end{pmatrix} \right\} \\ \widehat{W}_h^2 = \text{Span} \{ \widehat{\Lambda}_{ij}^2 = M_i(s) \mathring{M}_j(\theta) \} \end{cases}$$

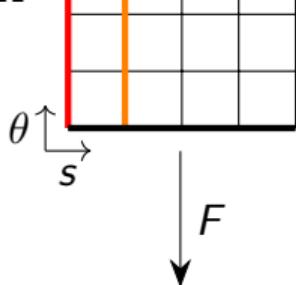
- Pre-polar spline spaces: C^0 sequence

$$\begin{cases} \widehat{V}_h^0 = \{ \widehat{\phi} \in \widehat{W}_h^0 : \mathcal{F}^0 \widehat{\phi} \in C^0(\Omega) \} & = \{ \widehat{\phi} = \sum_{ij} \phi_{ij} \widehat{\Lambda}_{ij}^0 : \phi_{0j} = \phi_{00} \forall j \} \\ \widehat{V}_h^1 = \{ \widehat{\mathbf{E}} \in \widehat{W}_h^1 : \mathcal{F}^1 \widehat{\mathbf{E}} \in H(\text{curl}; \Omega) \} & = \left\{ \widehat{\mathbf{E}} = \sum_{d,i,j} E_{i,j}^d \widehat{\Lambda}_{ij}^{1,d} : \begin{cases} E_{0j}^\theta = 0 \\ E_{1j}^\theta = E_{0(j+1)}^s - E_{0j}^s \end{cases} \forall j \right\} \\ \widehat{V}_h^2 = \{ \widehat{\beta} \in \widehat{W}_h^2 : \mathcal{F}^2 \widehat{\beta} \in L^2(\Omega) \} & = \{ \widehat{\beta} = \sum_{ij} \beta_{ij} \widehat{\Lambda}_{ij}^2 : \beta_{0j} = 0 \forall j \} \end{cases}$$



Characterizing the pre-polar spline spaces

$\hat{\Omega}$

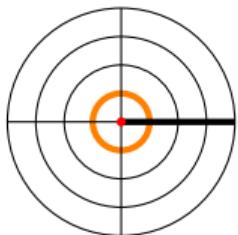


$$F : \binom{s}{\theta} \rightarrow \sum_{i,j} \rho_i \begin{pmatrix} \cos \theta_j \\ \sin \theta_j \end{pmatrix} B_i(s) \mathring{B}_k(\theta) \quad \text{with} \quad \begin{cases} \rho_i := \frac{i}{n_s - 1} & 0 \leq i < n_s \\ \theta_j := \frac{2\pi k}{n_\theta} & 0 \leq j < n_\theta \end{cases}$$

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- Pre-polar spline spaces: C^1 sequence

Ω

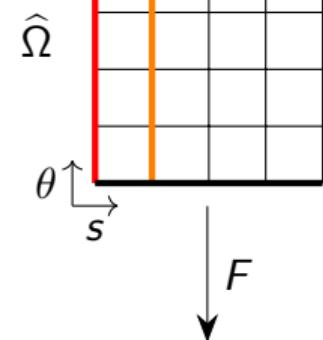


(\triangle now $F \in (\mathbb{S}^{p_s, p_\theta})^2$)

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Characterizing the pre-polar spline spaces



$$F : \binom{s}{\theta} \rightarrow \sum_{i,j} \rho_i \begin{pmatrix} \cos \theta_j \\ \sin \theta_j \end{pmatrix} B_i(s) \mathring{B}_k(\theta) \quad \text{with} \quad \begin{cases} \rho_i := \frac{i}{n_s - 1} & 0 \leq i < n_s \\ \theta_j := \frac{2\pi k}{n_\theta} & 0 \leq j < n_\theta \end{cases}$$

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- Pre-polar spline spaces: C^1 sequence

$$\begin{cases} \widehat{U}_h^0 = \{ \hat{\phi} \in \widehat{V}_h^0 : \mathcal{F}^0 \hat{\phi} \in C^1(\Omega) \} &= \left\{ \hat{\phi} \in \widehat{W}_h^0 : \begin{cases} \phi_{0j} = \phi_{00} \\ \phi_{1j} - \phi_{0j} = \lambda_1 \cos \theta_j + \lambda_2 \sin \theta_j \end{cases} \forall j \right\} \\ \widehat{U}_h^1 = \{ \widehat{\mathbf{E}} \in \widehat{V}_h^1 : \mathcal{F}^1 \widehat{\mathbf{E}} \in C^0(\Omega) \} &= \left\{ \widehat{\mathbf{E}} \in \widehat{W}_h^1 : \begin{cases} E_{0j}^\theta = 0 \\ E_{1j}^\theta = E_{0(j+1)}^s - E_{0j}^s \\ E_{0j}^s = \lambda_1 \cos \theta_j + \lambda_2 \sin \theta_j \end{cases} \forall j \right\} \\ \widehat{U}_h^2 = \{ \hat{\beta} \in \widehat{V}_h^2 : \mathcal{F}^2 \hat{\beta} \in L^2(\Omega) \} &= \widehat{V}_h^2 \end{cases}$$

(\triangle now $F \in (\mathbb{S}^{p_s, p_\theta})^2$)



Outline

Motivation

“logical” vs “physical” field spaces

Projection-based approach: a different perspective

Characterizing the pre-polar spline spaces

Computing the conforming projections

Numerical validation in Psydac

Summary



Computing the conforming projections



Cimbali, macchina M100 in Firenze (ca 2020)



Determination of the CONGA Projectors

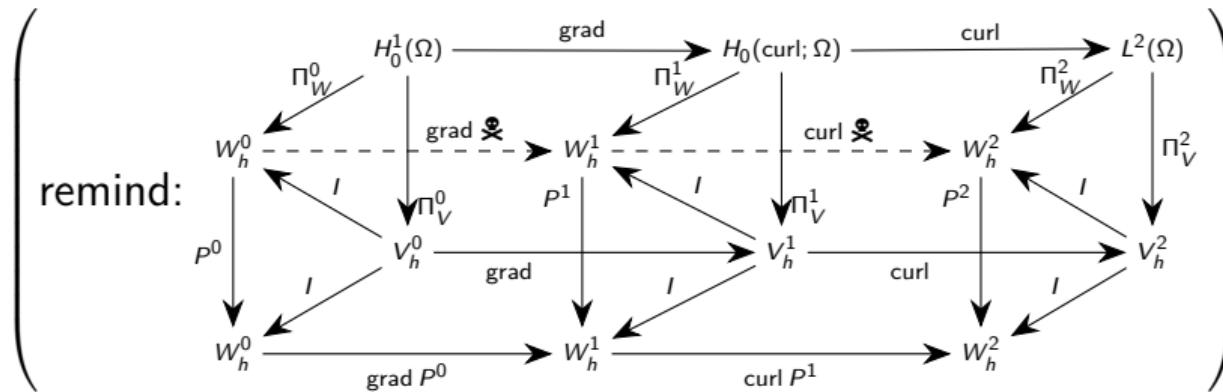
P^ℓ operators on W_h^ℓ , for $\ell = 0, 1, 2$, characterized by:



Determination of the CONGA Projectors

P^ℓ operators on W_h^ℓ , for $\ell = 0, 1, 2$, characterized by:

- Range property: $\text{Im}(P^\ell) \subseteq V_h^\ell$
- Projection property: $P^\ell u = u$ for $u \in V_h^\ell$
- Commuting property: $\begin{cases} \text{grad} \circ P^0 = P^1 \circ \text{grad} & \text{on } \text{Im}(\Pi_W^0) \subseteq W_h^0, \\ \text{curl} \circ P^1 = P^2 \circ \text{curl} & \text{on } \text{Im}(\Pi_W^1) \subseteq W_h^1. \end{cases}$





CONGA Projector P^0 for the C^0 sequence

$$V_h^0 = \left\{ \phi = \sum_{i,j} \phi_{ij} \Lambda_{ij}^0 \in W_h^0 : \phi_{0j} = \phi_{00} \quad \forall j \right\}$$



CONGA Projector P^0 for the C^0 sequence

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$\Rightarrow \Lambda_{ij}^0 \in V_h^0$ for $i \geq 1$

Projection property: $P^0 \phi = \phi$ for $\phi \in V_h^0 \Rightarrow P^0 \Lambda_{ij}^0 = \Lambda_{ij}^0 \quad \forall i \geq 1$



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Project Λ_{0j}^0 to any function in V_h^0

Symmetry in $j \Rightarrow$

$$P^0 \Lambda_{0j}^0 = \frac{1}{n_\theta} \sum_{k=0}^{n_\theta-1} \Lambda_{0k}^0$$



CONGA Projector P^0 for the C^1 sequence

$\phi \in W_h^0$, $\phi = \Lambda^{0,T} \phi$, we set

$$P^0 \phi = \Lambda^{0,T} (\mathbb{P}^0 \phi) \quad (\text{square matrix})$$

with $\mathbb{P}^0 = \mathbb{E}^{0,T} \mathbb{S}^0$, \mathbb{S}^0 to be defined.



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with $\mathbb{P}^0 = \mathbb{E}^{0,T} \mathbb{S}^0$, \mathbb{S}^0 to be defined. Range property verified for any \mathbb{S}^0 :

$$P^0 \phi = \Lambda^{0,T} (\mathbb{P}^0 \phi) = \Lambda^{0,T} (\mathbb{E}^{0,T} \mathbb{S}^0 \phi) = (\Lambda^{0,T} \mathbb{E}^{0,T}) \mathbb{S}^0 \phi = \mathcal{S}^{0,T} \varphi$$

with $\varphi = \mathbb{S}^0 \phi$.



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with $\varphi = \mathbb{S}^0 \phi$. In order for P^0 to have the Projection property we look for \mathbb{S}^0 such that $\mathbb{S}^0 \mathbb{E}^{0,T} = \mathbb{I}$ (i.e., \mathbb{S}^0 left-inverse $\mathbb{E}^{0,T}$).

Thereby, by recalling that $V_h^0 \ni \varphi = \mathcal{S}^{0,T} \varphi = \Lambda^{0,T} (\mathbb{E}^{0,T} \varphi)$, we get the Projection property

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Left-inverse of a rectangular matrix not unique.

$$\mathbb{E}^0 = \begin{bmatrix} \mathbb{X}^0 & 0 \\ 0 & \mathbb{I} \end{bmatrix} \Rightarrow \mathbb{S}^0 = \begin{bmatrix} \mathbf{s}^0 & 0 \\ 0 & \mathbb{I} \end{bmatrix}, \quad \text{with } \mathbf{s}^0 = \mathbf{s}_\gamma^0 \text{ determined from symmetry arguments}$$



CONGA Projectors P^1, P^2 for the C^0 sequence

$$V_h^1 = \left\{ \psi = \sum_{i,j} \psi_{i,j}^s \Lambda_{ij}^{1,s} + \sum_{i,j} \psi_{i,j}^\theta \Lambda_{ij}^{1,\theta} \in W_h^1 : \psi_{0j}^\theta = 0 \wedge \psi_{1j}^\theta = \psi_{0(j+1)}^s - \psi_{0j}^s \quad \forall j \right\}$$



CONGA Projectors P^1, P^2 for the C^0 sequence

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$\Rightarrow \Lambda_{ij}^{1,s}$ for $i \geq 1$ and $\Lambda_{ij}^{1,\theta}$ for $i \geq 2$ are in V_h^1

Projection property: $P^1 \psi = \psi$ for $\psi \in V_h^1 \Rightarrow$

$$P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \quad \forall i \geq 1 \wedge P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \quad \forall i \geq 2$$



CONGA Projectors P^1, P^2 for the C^0 sequence

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Projection property: $P^1 \psi = \psi$ for $\psi \in V_h^1 \Rightarrow P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \forall i \geq 1 \wedge P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \forall i \geq 2$

$\Lambda_{0j}^{1,s}, \Lambda_{0j}^{1,\theta}, \Lambda_{1j}^{1,\theta} \notin V_h^1$ BUT $\psi_j = \Lambda_{0j}^{1,s} + \Lambda_{1(j-1)}^{1,\theta} - \Lambda_{1j}^{1,\theta} \in V_h^1$

$$\Rightarrow P^1(\Lambda_{0j}^{1,s} + \Lambda_{1(j-1)}^{1,\theta} - \Lambda_{1j}^{1,\theta}) = \Lambda_{0j}^{1,s} + \Lambda_{1(j-1)}^{1,\theta} - \Lambda_{1j}^{1,\theta}.$$



CONGA Projectors P^1, P^2 for the C^0 sequence

$$\Rightarrow \begin{cases} P^1 \Lambda_{0j}^{1,\theta} = \mathbf{Q}_{0j} \\ P^1 \Lambda_{1j}^{1,\theta} = \mathbf{Q}_{1j} \\ P^1 \Lambda_{0j}^{1,s} = \Lambda_{0j}^{1,s} + \Lambda_{1(j-1)}^{1,\theta} - \Lambda_{1j}^{1,\theta} + \mathbf{Q}_{1j} - \mathbf{Q}_{1(j-1)} \end{cases}$$

with $\mathbf{Q}_{0j}, \mathbf{Q}_{1j} \in V_h^1$ to be determined by imposing commutation with P^2 .

Remark: Commutation with P^0 true for any choice of P^1 , as long as it is a projector, as one can show that $\text{Im} \Pi_W^0 \subseteq V_h^0$, so that $\text{grad } P^0 \phi = \text{grad } \phi = P^1 \text{ grad } \phi$.



CONGA Projectors P^1, P^2 for the C^0 sequence

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CONGA Projectors P^1, P^2 for the C^0 sequence

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CONGA Projectors P^1, P^2 for the C^0 sequence

Proposition: if $G_j = \operatorname{curl} \mathbf{Q}_{1j} + \Lambda_{1j}^2$ then $\operatorname{curl} P^1 \psi = P^2 \operatorname{curl} \psi \quad \forall \psi \in \operatorname{Im} \Pi_W^1$.

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CONGA Projectors P^1, P^2 for the C^0 sequence

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CONGA Projectors P^1, P^2 for the C^0 sequence

Proposition: if $G_j = \operatorname{curl} \mathbf{Q}_{1j} + \Lambda_{1j}^2$ then $\operatorname{curl} P^1 \psi = P^2 \operatorname{curl} \psi \quad \forall \psi \in \operatorname{Im} \Pi_W^1$.

$$\Rightarrow \begin{cases} P^1 \Lambda_{0j}^{1,\theta} = \mathbf{0} \\ P^1 \Lambda_{1j}^{1,\theta} = \mathbf{Q}_{1j} \\ P^1 \Lambda_{0j}^{1,s} = \Lambda_{0j}^{1,s} + \Lambda_{1(j-1)}^{1,\theta} - \Lambda_{1j}^{1,\theta} + \mathbf{Q}_{1j} - \mathbf{Q}_{1(j-1)} \\ P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \quad \forall i \geq 1 \\ P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \quad \forall i \geq 2 \end{cases} \quad \begin{cases} P^2 \Lambda_{0j}^2 = G_j \\ P^2 \Lambda_{ij}^2 = \Lambda_{ij}^2 \quad \forall i \geq 1. \end{cases}$$



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This choice is convenient as all the projections are local and invariant w.r.t. j .



CONGA Projectors P^1, P^2 for the C^1 sequence

$$V_h^1 = \left\{ \psi = \Lambda^{1,T} \psi = \begin{pmatrix} (\Lambda^{1,s})^T \psi^s \\ (\Lambda^{1,\theta})^T \psi^\theta \end{pmatrix} : \begin{array}{l} \psi_{0j}^s = \lambda_1 \cos \theta_j + \lambda_2 \sin \theta_j \\ \psi_{0j}^\theta = 0 \\ \psi_{1j}^\theta = \psi_{0(j+1)}^s - \psi_{0j}^s \end{array} \right\} \text{ with } \Lambda^1 = \begin{pmatrix} \Lambda^{1,s} \\ \Lambda^{1,\theta} \end{pmatrix}, \psi = \begin{pmatrix} \psi^s \\ \psi^\theta \end{pmatrix}$$



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Initial guess for P^1 by looking at V_h^1 **characterization** and **local exactness**



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$$\left\{ \begin{array}{ll} P^1 \Lambda_{0j}^{1,s} = \text{grad } P^0 \Lambda_{1j}^0 + R_j & P^1 \Lambda_{0j}^{1,\theta} = Q_{0j}, \\ P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \text{ for } i \geq 1 & P^1 \Lambda_{1j}^{1,\theta} = Q_{1j}, \\ P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \text{ for } i \geq 2. & \end{array} \right.$$



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CONGA Projectors P^1, P^2 for the C^1 sequence

$$V_h^2 = \{\boldsymbol{\eta} = \boldsymbol{\Lambda}^{2,T} \boldsymbol{\eta} : \eta_{0j} = 0\}$$



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CONGA Projectors P^1, P^2 for the C^1 sequence

We still have to determine $P^1 \dots$

Projector P^1

$$\left\{ \begin{array}{l} P^1 \Lambda_{0j}^{1,s} = \text{grad } P^0 \Lambda_{1j}^0 + \mathbf{R}_j \quad P^1 \Lambda_{0j}^{1,\theta} = \mathbf{Q}_{0j}, \\ P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \text{ for } i \geq 1 \quad P^1 \Lambda_{1j}^{1,\theta} = \mathbf{Q}_{1j}, \\ P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \text{ for } i \geq 2. \end{array} \right.$$

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$$\begin{cases} P^1 \Lambda_{0j}^{1,s} = \text{grad } P^0 \Lambda_{1j}^0 + \Lambda_{1j}^{1,s} & P^1 \Lambda_{0j}^{1,\theta} = \mathbf{0}, \\ P^1 \Lambda_{ij}^{1,s} = \Lambda_{ij}^{1,s} \text{ for } i \geq 1 & P^1 \Lambda_{1j}^{1,\theta} = \mathbf{0}, \\ P^1 \Lambda_{ij}^{1,\theta} = \Lambda_{ij}^{1,\theta} \text{ for } i \geq 2. \end{cases}$$

Constraints

$$\begin{cases} \text{curl } R_j = \text{curl } \Lambda_{1j}^{1,s} \\ \mathbf{0} = \Lambda_{1j}^{1,s} - R_j \\ \sum_{j=0}^{n_\theta-1} R_j = \sum_{j=0}^{n_\theta-1} \Lambda_{1j}^{1,s} \end{cases}$$



C^0 CONGA Projectors: Matrix Form

$\mathbb{P}^0, \mathbb{P}^1, \mathbb{P}^2$ sparse matrices
with the following structure:

$$\mathbb{P}^0 = \begin{bmatrix} \frac{1}{n_\theta} \mathbf{1} & \mathbf{0} \\ \mathbf{0} & I \end{bmatrix}$$

$$\mathbb{P}^1 = \begin{bmatrix} I & \mathbf{0} \\ \mathbf{0} & \begin{bmatrix} \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \mathbf{d} & 0 & 0 & 0 \\ \mathbf{0} & 0 & 0 & I \end{bmatrix} \end{bmatrix}$$

$$\mathbb{P}^2 = \begin{bmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{I} & \mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

$$\text{where } \mathbf{\ddot{d}} = \begin{bmatrix} -1 & 1 & & \\ & \ddots & \ddots & \\ & & -1 & 1 \\ 1 & & & -1 \end{bmatrix}$$

and $\mathbf{1}$ is the matrix full of 1's (both of size $n_\theta \times n_\theta$)



C^1 CONGA Projectors: Matrix Form

$\mathbb{P}^0, \mathbb{P}^1, \mathbb{P}^2$ sparse matrices
with the following structure:

$$\mathbb{P}^0 = \begin{array}{|c|c|c|} \hline \frac{1}{n_\theta} \mathbf{1} & \mathbf{0} & \\ \hline & & \mathbf{0} \\ \hline \frac{1}{n_\theta} \mathbf{1} & \mathbf{p} & \\ \hline & & \\ \hline \mathbf{0} & & \mathbf{I} \\ \hline \end{array}$$

$$\mathbb{P}^1 = \begin{array}{|c|c|c|c|} \hline p & \mathbf{0} & & \\ \hline I - p & & & \mathbf{0} \\ \hline \mathbf{0} & I & & \\ \hline \mathbf{0} & & & \\ \hline \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{0} \\ \hline \mathbf{0} & & & \\ \hline \end{array}$$

$$\mathbb{P}^2 = \begin{array}{|c|c|c|c|} \hline \mathbf{0} & \mathbf{0} & & \\ \hline & I & & \\ \hline & & & I \\ \hline \mathbf{0} & & & \\ \hline \end{array}$$

where \mathbf{p} is a Toeplitz matrix with $p_{\ell,k} = \frac{2}{n_\theta} \cos(\theta_\ell - \theta_k)$ for $\ell, k = 0, \dots, n_\theta - 1$



Outline

Motivation

“logical” vs “physical” field spaces

Projection-based approach: a different perspective

Characterizing the pre-polar spline spaces

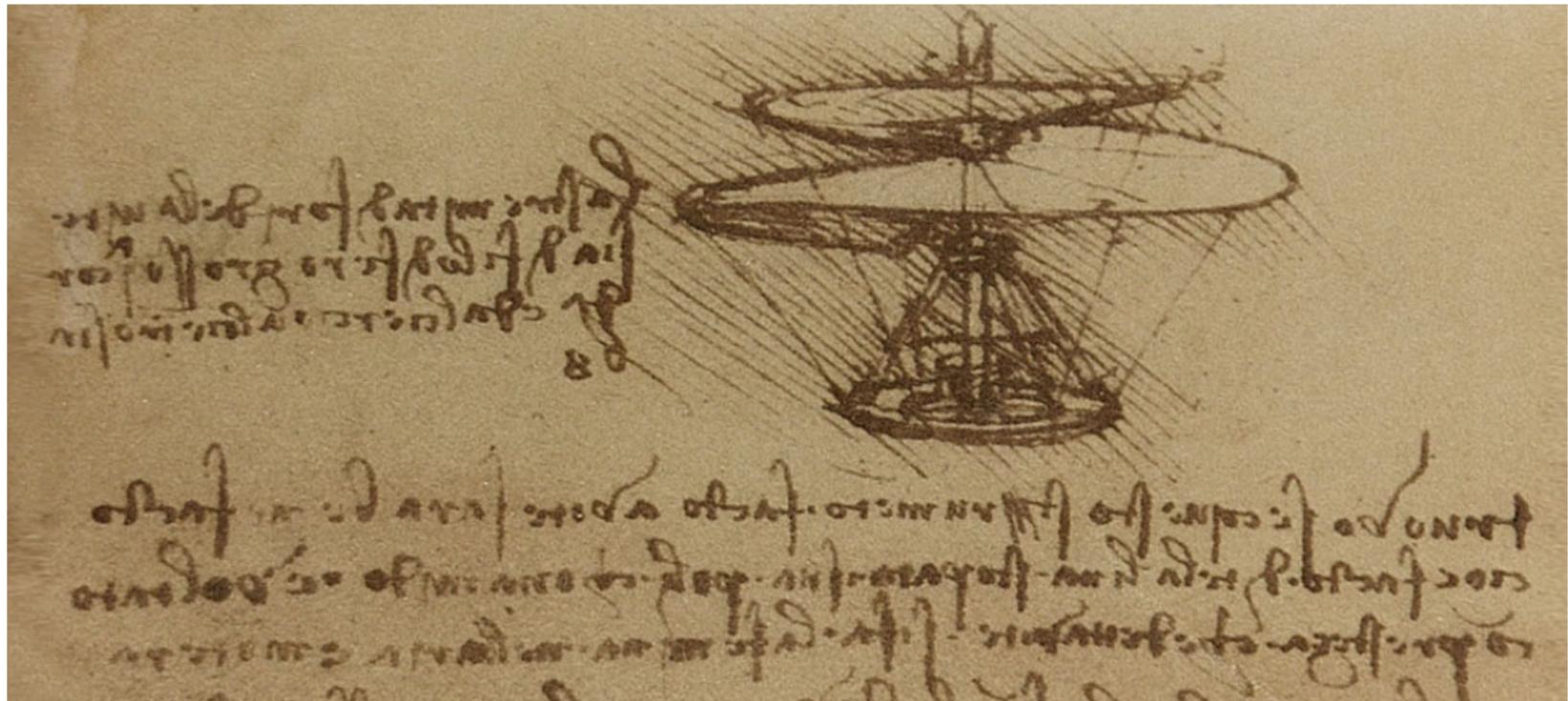
Computing the conforming projections

Numerical validation in Psydac

Summary



Numerical validation in Psydac



Leonardo da Vinci, prototype design (ca 1490)



Reminder: CONGA (projection-based) Poisson solver

- Model and conforming discretization:

$$\begin{cases} -\Delta \phi = f & \text{in } \Omega \\ \phi = 0 & \text{on } \partial\Omega, \end{cases} \rightsquigarrow \mathbb{S}_p \phi_p = \mathbf{f}_p$$

with $(\mathbb{S}_p)_{a,b} = \int_{\Omega} \nabla \Lambda_a^{0,p} \cdot \nabla \Lambda_b^{0,p} dx dy$ the stiffness matrix in the **polar spline basis**.

- CONGA discretization:

$$(\alpha(\mathbb{I} - \mathbb{P}^0)^T \mathbb{M} (\mathbb{I} - \mathbb{P}^0) + (\mathbb{P}^0)^T \mathbb{S} \mathbb{P}^0) \phi = (\mathbb{P}^0)^T \mathbf{f}$$

with $\alpha > 0$ and

$$\begin{cases} \mathbb{M}^0, \mathbb{S} : \text{the mass and stiffness matrices in the full spline basis.} \\ \mathbb{P}^0 : \text{the projection matrix onto the polar splines, in the full spline basis.} \end{cases}$$



Reminder: CONGA (projection-based) Maxwell solver

- Model and conforming discretization:

$$\begin{cases} \partial_t B + \operatorname{curl} \mathbf{E} = 0, \\ \frac{1}{c^2} \partial_t \mathbf{E} - \operatorname{curl} B = 0, \end{cases} \rightsquigarrow \begin{cases} \partial_t \mathbf{B}_p + \mathbb{C}_p \mathbf{E}_p = 0 \\ \partial_t \mathbb{M}_p^1 \mathbf{E}_p - \mathbb{C}_p^T \mathbb{M}_p^2 \mathbf{B}_p = 0 \end{cases}$$

with curl and mass matrices in the [polar spline basis](#).

- CONGA discretization:

$$\begin{cases} \partial_t \mathbf{B} + \mathbb{C}\mathbb{P}^1 \mathbf{E} = 0 \\ \partial_t \tilde{\mathbb{M}}^1 \mathbf{E} - (\mathbb{C}\mathbb{P}^1)^T \tilde{\mathbb{M}}^2 \mathbf{B} = 0 \end{cases}$$

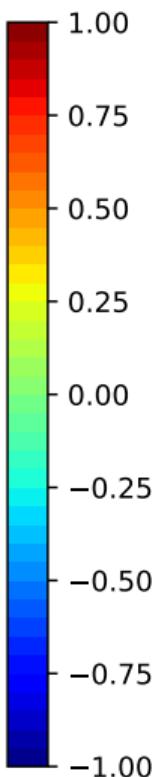
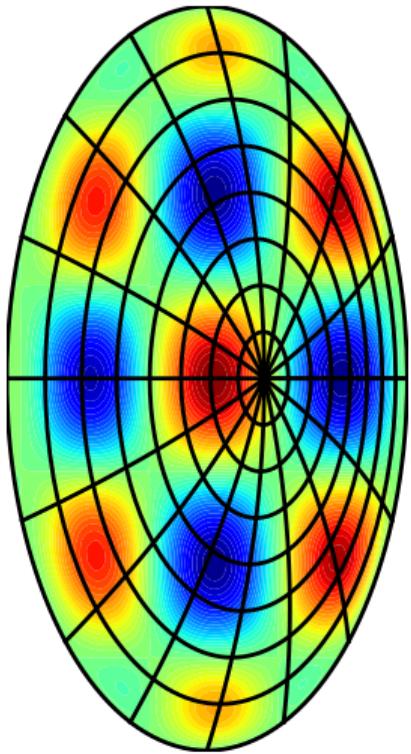
with curl and (regularized) mass matrices in the [full spline basis](#)

- Note: \triangleleft the mass matrices [must be regularized](#) because $W_h^1, W_h^2 \not\subset L^2(\Omega)$.

We set: $\tilde{\mathbb{M}}^\ell := \frac{1}{n_s n_\theta} (\mathbb{I} - \mathbb{P}^\ell)^T (\mathbb{I} - \mathbb{P}^\ell) + (\mathbb{P}^\ell)^T \mathbb{M}^\ell \mathbb{P}^\ell$



Poisson Problem on a Polar Domain



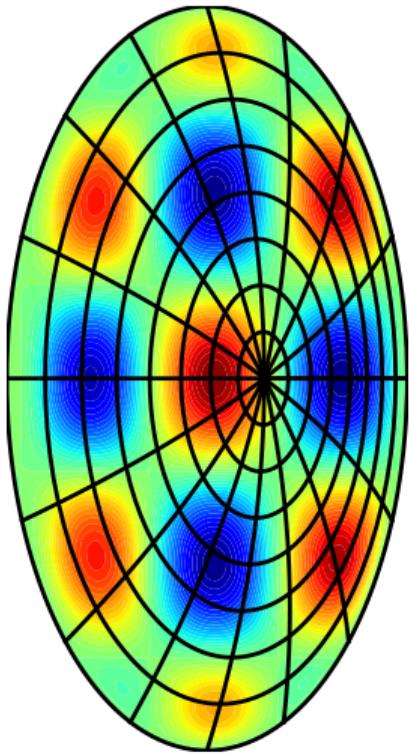
Homogeneous Poisson problem:

$$\begin{cases} -\Delta \phi = f & \Omega \\ \phi = 0 & \partial\Omega \end{cases}$$

ϕ manufactured solution shown on the left.



Poisson Problem on a Polar Domain



Homogeneous Poisson problem:

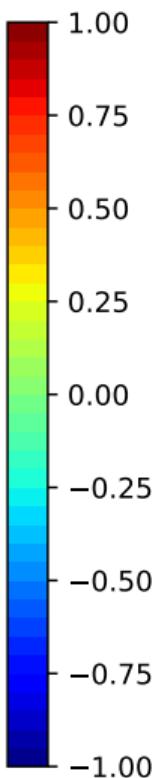
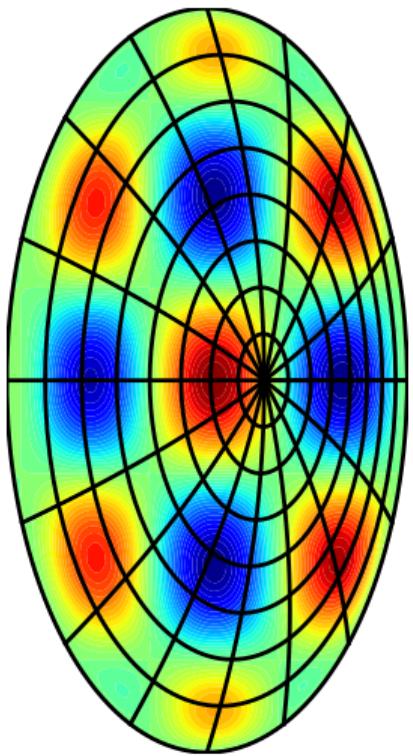
$$\begin{cases} -\Delta \phi = f & \Omega \\ \phi = 0 & \partial\Omega \end{cases}$$

ϕ manufactured solution shown on the left.

Discretization with degree $p^s, p^\theta = 2, 3, 4$



Poisson Problem on a Polar Domain

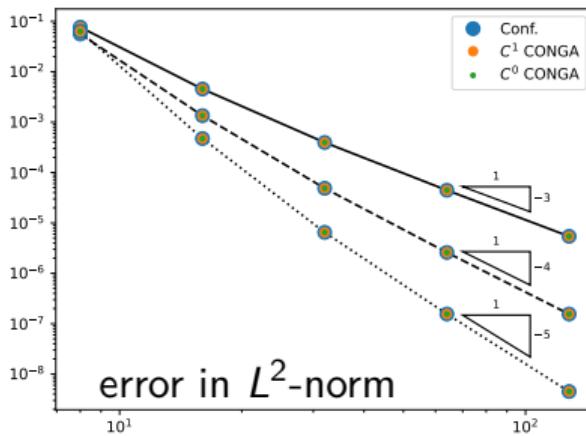


Homogeneous Poisson problem:

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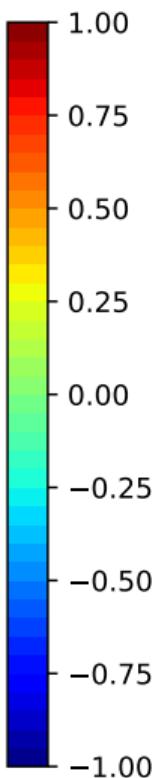
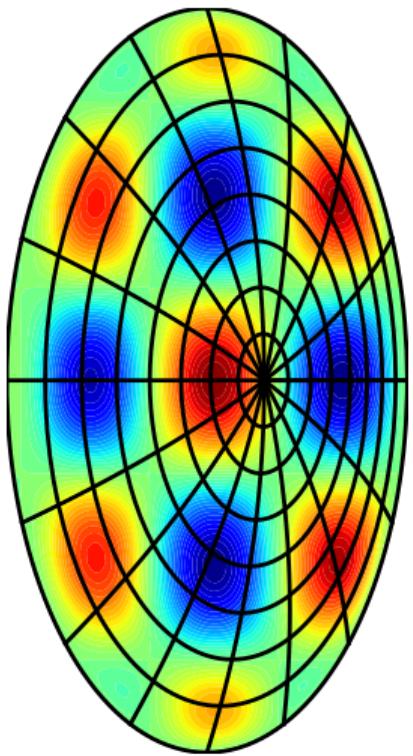
Discretization with degree $p^s, p^\theta = 2, 3, 4$



Same (optimal)
order of the
conforming
(polar)
discretization



Poisson Problem on a Polar Domain

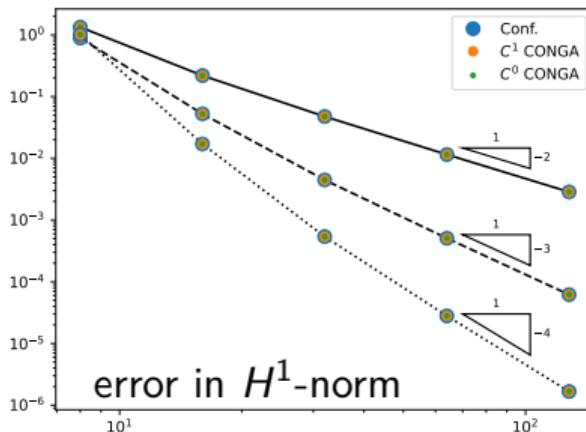


Homogeneous Poisson problem:

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ϕ manufactured solution shown on the left.

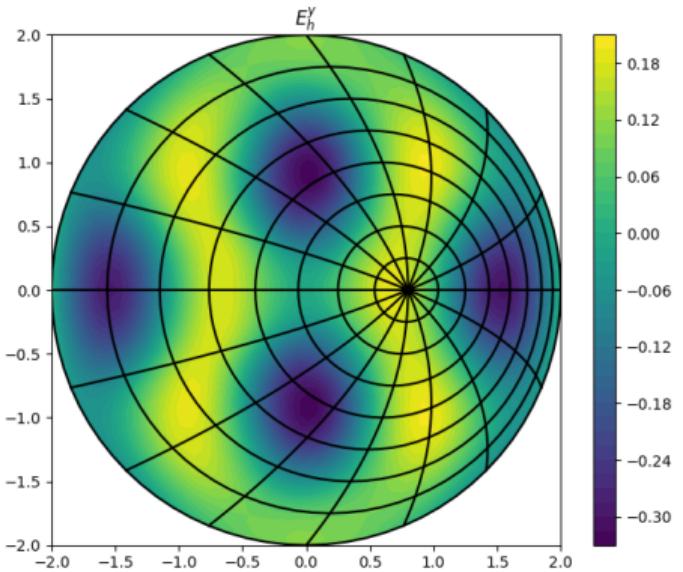
Discretization with degree $p^s, p^\theta = 2, 3, 4$



Same (optimal)
order of the
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(polar)
discretization



Maxwell Problem on a Polar Domain



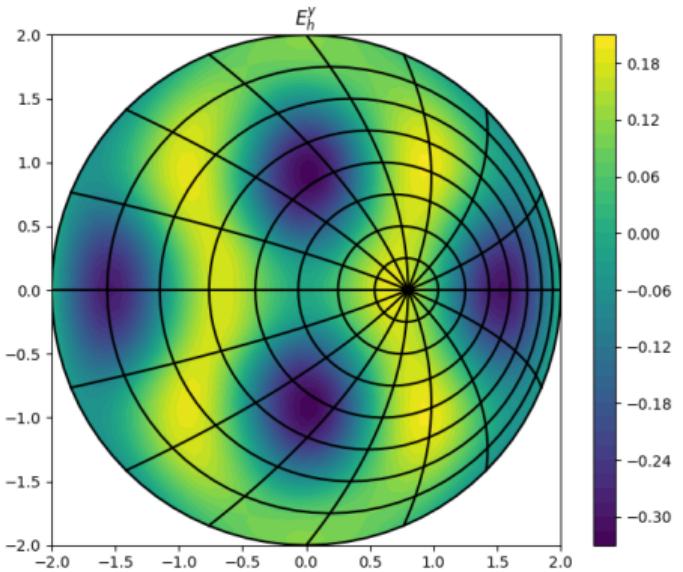
TD Maxwell problem:

$$\begin{cases} \partial_t B + \operatorname{curl} \mathbf{E} = 0, \\ \frac{1}{c^2} \partial_t \mathbf{E} - \operatorname{curl} B = 0, \end{cases}$$

\mathbf{E}, B : Fourier-Bessel eigenmode, shown on the left.



Maxwell Problem on a Polar Domain



TD Maxwell problem:

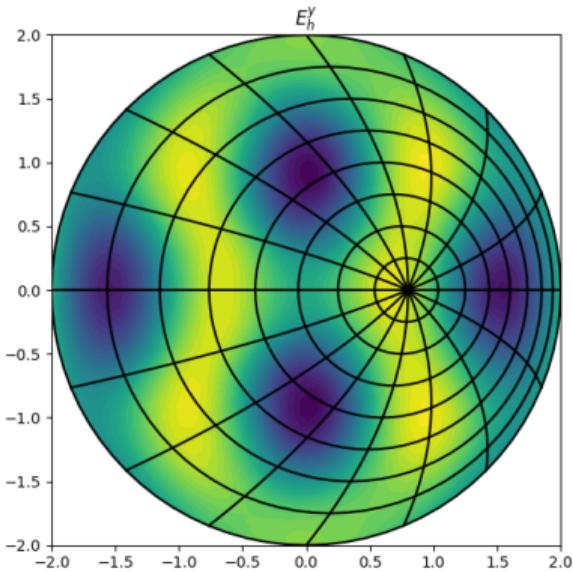
$$\begin{cases} \partial_t B + \operatorname{curl} \mathbf{E} = 0, \\ \frac{1}{c^2} \partial_t \mathbf{E} - \operatorname{curl} B = 0, \end{cases}$$

\mathbf{E}, B : Fourier-Bessel eigenmode, shown on the left.

Discretization with degree $p^s, p^\theta = 2, 3, 4$



Maxwell Problem on a Polar Domain

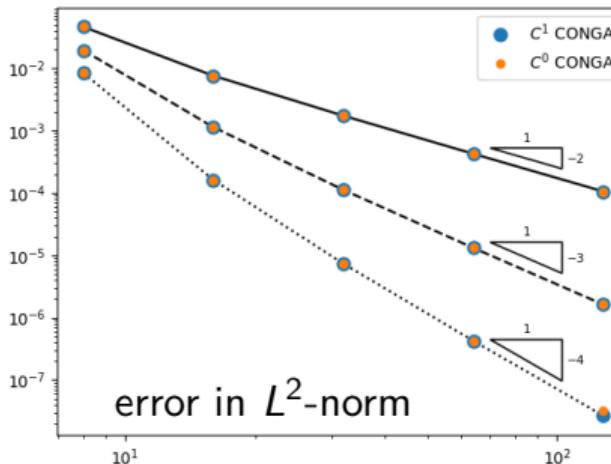


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Discretization with degree $p^s, p^\theta = 2, 3, 4$

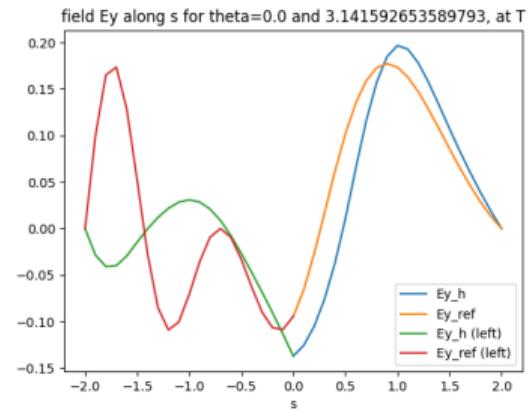
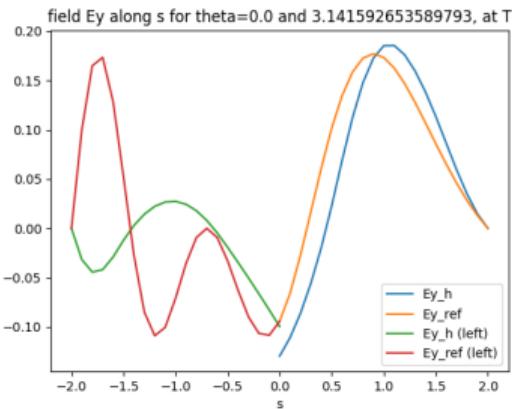
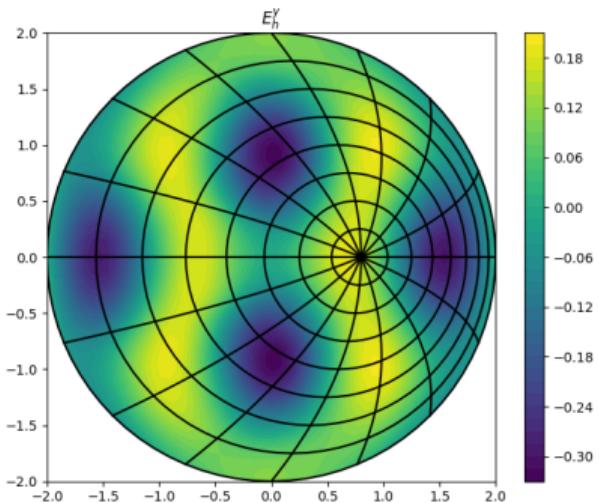


Optimal order
of convergence
is observed



Maxwell Problem on a Polar Domain

Cuts along $\theta = 0$ (with C^0 vs. C^1 projections)





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Summary

- Poisson equation: $(\alpha(\mathbb{I} - \mathbb{P}^0)^T \mathbb{M}^0 (\mathbb{I} - \mathbb{P}^0) + (\mathbb{P}^0)^T \mathbb{S} \mathbb{P}^0) \phi = (\mathbb{P}^0)^T \mathbf{f}$
- Maxwell equations: $\partial_t \mathbf{B} + \mathbb{C} \mathbb{P}^1 \mathbf{E} = 0, \partial_t \tilde{\mathbb{M}}^1 \mathbf{E} - (\mathbb{C} \mathbb{P}^1)^T \tilde{\mathbb{M}}^2 \mathbf{B} = 0$
- \mathbb{C}, \mathbb{S} : usual curl and stiffness matrices, $\mathbb{M}^0, \tilde{\mathbb{M}}^1, \tilde{\mathbb{M}}^2$: (regularized) mass matrices
- projection matrices:

$$\mathbb{P}^0 = \begin{bmatrix} \frac{1}{n_\theta} \mathbf{1} & \mathbf{0} & \\ \hline \mathbf{0} & \mathbf{p} & \\ \hline & & \mathbf{0} \end{bmatrix}$$

$$\mathbb{P}^1 = \begin{bmatrix} \mathbf{p} & \mathbf{0} & & \\ \hline \mathbf{I} - \mathbf{p} & & \mathbf{0} & \\ \hline \mathbf{0} & \mathbf{I} & & \\ \hline \mathbf{0} & & \mathbf{0} & \\ \hline \dot{\mathbf{d}}\mathbf{p} & & & \\ \hline \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{I} \end{bmatrix}$$

$$\mathbb{P}^2 = \begin{bmatrix} \mathbf{0} & \mathbf{0} & \\ \hline \mathbf{I} & & \\ \hline \mathbf{0} & & \mathbf{I} \end{bmatrix}$$

with $\dot{\mathbf{d}} = \begin{bmatrix} -1 & 1 & \\ & \ddots & \\ & & \ddots \end{bmatrix}$, $\mathbf{1}_{\ell,k} = 1$ and $\mathbf{p}_{\ell,k} = \frac{2}{n_\theta} \cos(\theta_\ell - \theta_k)$ for $0 \leq \ell, k < n_\theta$