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TSVV5 – Neutral gas dynamics in the edge Intermediate progress report KUL

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Outline

- Status advanced fluid and hybrid neutral models for fast simulations
- Highlights inclusion n-n collisions
 - Theoretical derivation (Hilbert expansion)
 - Practical extension to SOLPS-ITER
 - Application to AUG and ITER modeling, incl. extended grids
 - Error analysis for DEMO modeling
- Summary and next steps

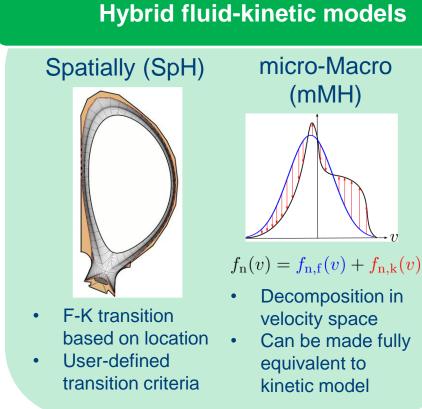


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A hierarchy of neutral models

Advanced fluid neutral models (AFN)

- Efficient (direct) coupling to plasma equations, no MC noise
- Basis for hybrid methods
- Good accuracy in highly collisional regimes



Kinetic model

- Most complete physical description
- Flexibility w.r.t. geometry, collisional processes, sources, boundary conditions,...
- Very expensive in highly collisional regimes

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Model accuracy

Computational efficiency

CPU × 1/10?

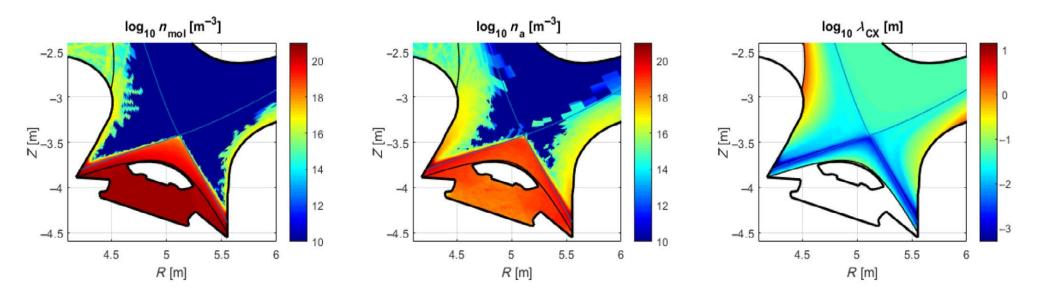
Summary achievements AFN: mature models!

- Significant model improvements compared to 'standard' fluid neutral models
 - Transport coefficients consistent with collisional processes used by EIRENE (AMJUEL/HYDHEL)
 [N. Horsten et al., NF, 2017], including neutral-neutral collision effects [W. Dekeyser et al, PSI, 2024.]
 - Boundary conditions consistent with kinetic EIRENE treatment [N. Horsten et al., NF 57, 2017], incl. fast/thermal reflection (approximate effect of molecules) and TRIM data (effect of wall materials)
 - Separate neutral energy equation to extend validity range of fluid (and SpH) model towards lower recycling conditions [W. Van Uytven et al., CPP 60, 2020]
 - o Inclusion of plasma drift effects [W. Van Uytven et al. NME 2022]
- Made widely available to users through implementation in new extended grids version of SOLPS-ITER
 - Correct treatment of grid non-orthogonality [W. Dekeyser et al, NME 18, 2019]
 - Simulations up-to-the-wall [W. Dekeyser et al, NME 27, 2021]
- Already successfully applied to various machines, incl. AUG, JET [N. Horsten et al., NME 2022], ITER [W. Van Uytven et al, NF 62, 2022] and DEMO (link WP-DES) [W. Van Uytven et al, CPP, 2024]
- Support provided for implementation of AFN models in European turbulence codes (TOKAM3X, GRILLIX link TSVV3).

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Achievements spatially hybrid modeling (SpH)

- Combine AFN model in high-collisional regions with kinetic treatment in low collisional regions [W. Van Uytven, CPP, 2022]
 - Improved accuracy compared to pure fluid
 - Improved speed compared to kinetic (factor 5-20 depending on regime)
- Accurate treatment of molecular and (kinetic) impurity effects
- Fully integrated in extended grids version of SOLPS-ITER for simulations up-to-the-wall



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Status of two-phases hybrid method and boundary conditions

- Overview of practical boundary condition implementation strategies for fluid neutral models
 - Matching moments and fluxes (Marshak, most used in practise)
 - Adjoint source iteration method (Golse, Klar)
 - Moment model approach (Kainz, Titulaer, Borsche, Klar)
- Comparison of the different strategies is WIP
- Two-phases hybrid method with particle tracing phase and fluid phase
- For a given error tolerance, the most cost-effective two-phases hybrid method is a domain decomposition (spatial hybrid) method
- Implementation of an adaptive spatial hybrid method with error-based interface position is WIP

Status of hybrid method based on KDMC

- Aim: investigate alternative, fully particle-based, hybrid method
- Basic particle tracing scheme implemented in EIRON
- Eiron updated to use BGK operator
 - KDMC depends on certain assumptions of the physics to work
 - EIRON used simple rotation after collision, which violated those assumptions
 - Initial results look ok, but more tests needed
- Estimation of QoIs through fluid model based on particle positions
 - Error analysis of 1D homogeneous background is now more rigorous.

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Introducing neutral-neutral collisions

Nonlinear kinetic equation:

$$\partial_t f(x,v,t) + v \partial_x f(x,v,t) = R_{cx}(x) \left(M_{cx}(v|x) \int f(x,v',t) dv' - f(x,v,t) \right) + R_{nn}(x) \left(M_{nn}(v|x) \int f(x,v',t) dv' - f(x,v,t) \right)$$

With

$$M_{cx}(v|x) = \frac{1}{\sqrt{2\pi T_p(x)}} e^{-\frac{1(v-u_p(x))^2}{2}} \qquad \qquad M_{nn}(v|x) = \frac{1}{\sqrt{2\pi T_n(x)}} e^{-\frac{1(v-u_n(x))^2}{2}}$$

 $\rightarrow M_{nn}(v|x)$ depends on the neutral particle distribution itself!

Make a fluid model in a systematic way?

- \rightarrow Explicit in time: $M_{nn}(v|x)$ is known from previous time step
- \rightarrow Hilbert expansion

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Hilbert expansion

Hilbert expansion ansatz¹: Introducing a scaling parameter $\varepsilon \ll 1$

 $f(x,v,t) \approx f_0(x,v,t) + \varepsilon f_1(x,v,t) + \varepsilon^2 f_2(x,v,t) + \dots$

 \rightarrow The particle distribution is an equilibrium f_0 plus higher order perturbations

Rank terms by importance by scaling them with $\varepsilon^k \ll 1$ (larger $k \rightarrow$ less important term) and equate per order in ε

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Results

[E. Andoni, MSc thesis, KU Leuven]

$$\partial_t(\rho(x,t)) + \partial_x(u_A(x,t)\rho) - \partial_x(D(x,t)\partial_x[\rho \operatorname{Var}_B(x,t)]) = 0$$

Hydrodynamic scaling:

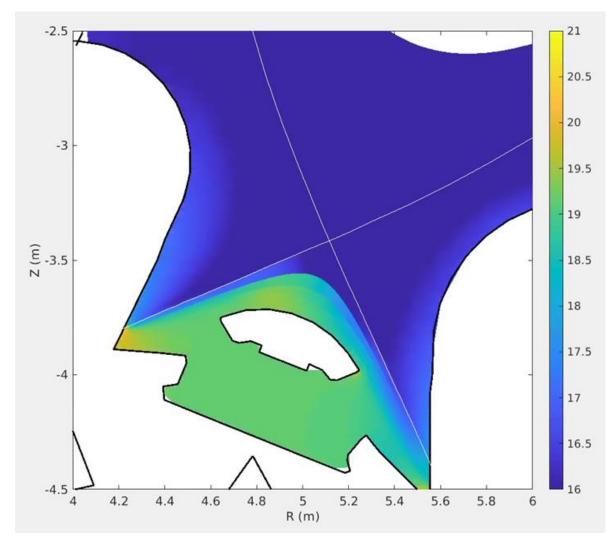
$R_{nn} = \epsilon^k R_{cx}$	$u_A(x,t)$	D(x,t)	$\operatorname{Var}_B(x,t)$
k = 0	u_R	0	0
k > 0	u_p	0	0

Diffusive scaling:

$R_{nn} = \epsilon^k R_{cx}$	$u_A(x,t)$	D(x,t)	$\operatorname{Var}_B(x,t)$
k = 0	u_R	$\frac{1}{R_{nn}(x,t) + R_{cx}(x,t)}$	$\operatorname{Var}_{M_R}(x,t)$
k = 1	$u_p + \frac{R_{nn}}{R_{cx}} \left(u_n - u_p \right)$	$\frac{1}{R_{cx}(x,t)}$	σ_p^2
k > 1	u_p	$\frac{1}{R_{cx}(x,t)}$	σ_p^2

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AFN model including n-n collisions in SOLPS-ITER



- 'Standard' AFN model assumes dominant CX collisions for transport of atoms, but:
 - n-n collisions may be as frequent as CX in case $n_i \approx n_n$
 - No plasma below dome, far-SOL,...

 Add n-n collision contribution to diffusion coefficient (and viscosity/conductivity) (rate based on Kotov 2007 (thesis))

$$D_0^n = \frac{T_n}{m_n(\nu_{ion} + \nu_{CX} + \nu_{n-n})}$$

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• Split into (perpendicular) pressure diffusion and (isotropic) density diffusion based on relative collision frequencies

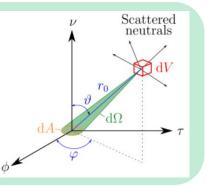
 $D_{p}^{n} = \frac{(\nu_{ion} + \nu_{CX})D_{0}^{n}}{\nu_{ion} + \nu_{CX} + \nu_{n-n}}, \qquad D_{n}^{n} = \frac{\nu_{n-n}D_{0}^{n}}{\nu_{ion} + \nu_{CX} + \nu_{n-n}}$

AFN boundary conditions including n-n collisions

Speed- and angular-dependent particle flux density

Reflected/recycled neutrals

 $\Gamma^{n}_{\nu-}(v,\vartheta,\varphi) \quad \begin{array}{l} \text{Incident neutrals: diffusion approx.} \\ \text{or Maxwellian approx.} \\ \Gamma^{i}_{\nu-}(v,\vartheta,\varphi) \quad \begin{array}{l} \text{Incident ions: truncated Maxwellian} \\ \text{+ sheath acceleration} \end{array}$



Diffusion approx.:

- Original BCs:
 consider neutrals from
 CX-collisions only
- Modified: neutrals from both CX and n-n collisions

Maxwellian approx.:

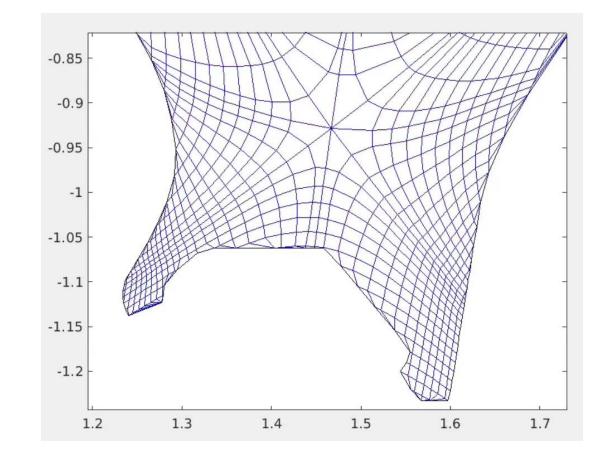
Assume (drifting) Maxwellian based on T_n and $u_{||n}$

$\Gamma_{\nu+}^{n}(v_{R},\vartheta_{R},\varphi_{R}) = \int_{\nu=0}^{\infty} \int_{\vartheta=0}^{\pi/2} \int_{\varphi=0}^{2\pi} \underbrace{R(v,\vartheta,\varphi \to v_{R},\vartheta_{R},\varphi_{R})}_{(\Gamma_{\nu-}^{n}(v,\vartheta,\varphi) + \Gamma_{\nu-}^{i}(v,\vartheta,\varphi)) dv d\vartheta d\varphi} IR$ $TRIM \ database$ $Moments \ total \ distribution: \ particle, \ momentum \ and$

energy flux densities [N. Horsten et al., NF 57 (2017)]

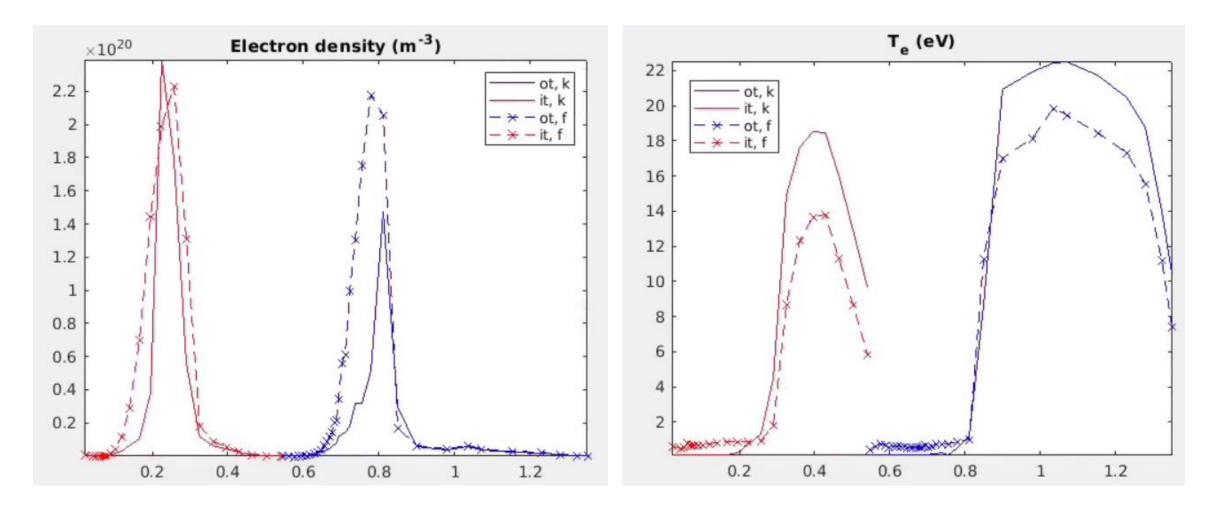
AUG 16151

- A standard SOLPS-ITER equilibrium/geometry, but full W wall
- Grid created with carreMode=3 and GOAT
- BCs:
 - Core: $T_i = T_e = 300 \text{ eV}$, $n_i = 2.8 \text{ e19 m}^{-3}$
 - Walls: sheath BCs
 - Recycling 1.0; no puff/pump
- Setup:
 - D only, no drifts, but with parallel currents
 - AFN model, incl. n-n collisions, with and w/o separate neutral energy equation
 - Ref.: full kinetic neutrals (atoms, molecules, n-n collisions)



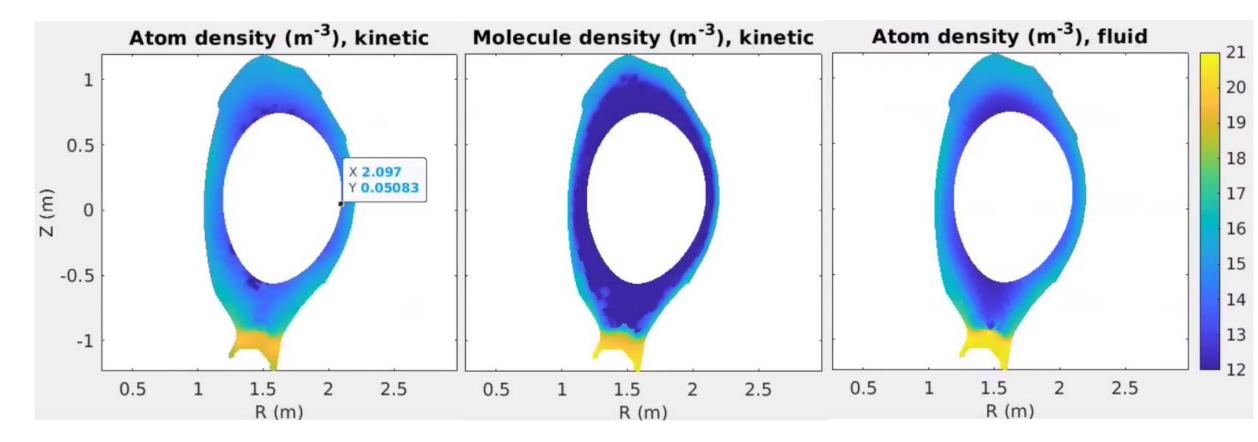
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Target profiles



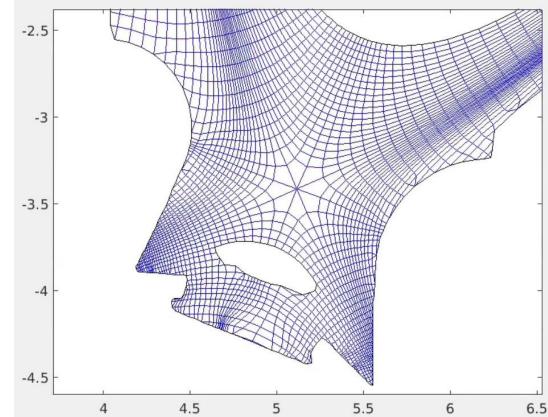
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Neutral density



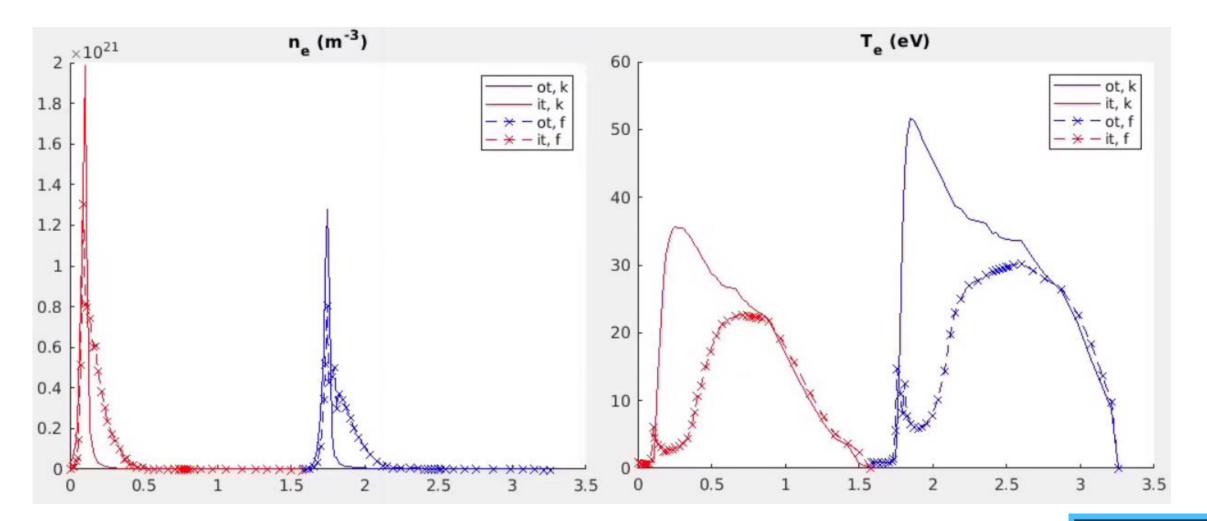
ITER

- Case based on ITER 2275, but full W wall
- Grid created with carreMode=3 and GOAT
- BCs:
 - Core: $T_i = T_e = 300 \text{ eV}$, $n_i = 2.8 \text{ e19 m}^{-3}$
 - Walls: sheath BCs
 - Recycling 1.0; puff 1e22 s⁻¹;pump beneath dome
- Setup:
 - D only, no drifts, no parallel currents
 - AFN model, incl. n-n collisions, with and w/o separate neutral energy equation
 - Ref.: full kinetic neutrals (atoms, molecules, n-n collisions)



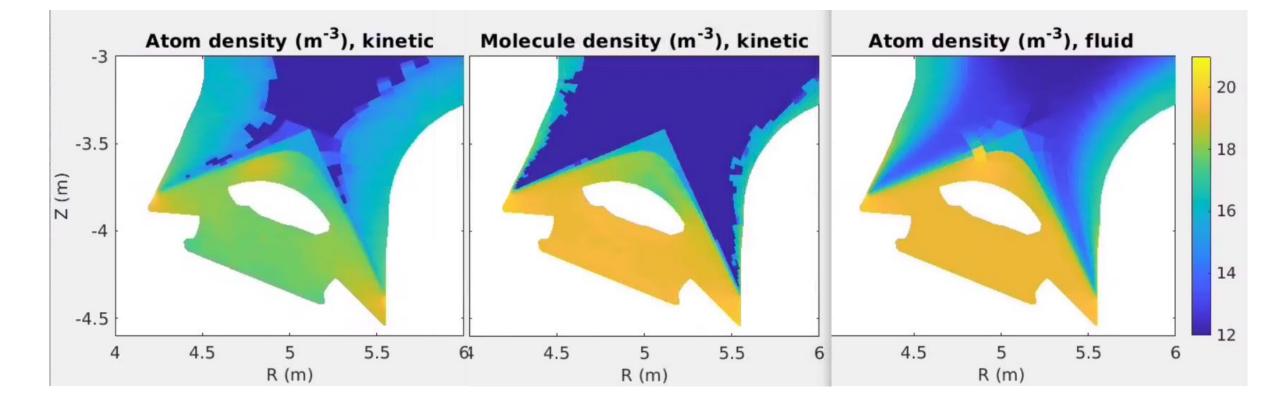
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Target profiles



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Neutral density

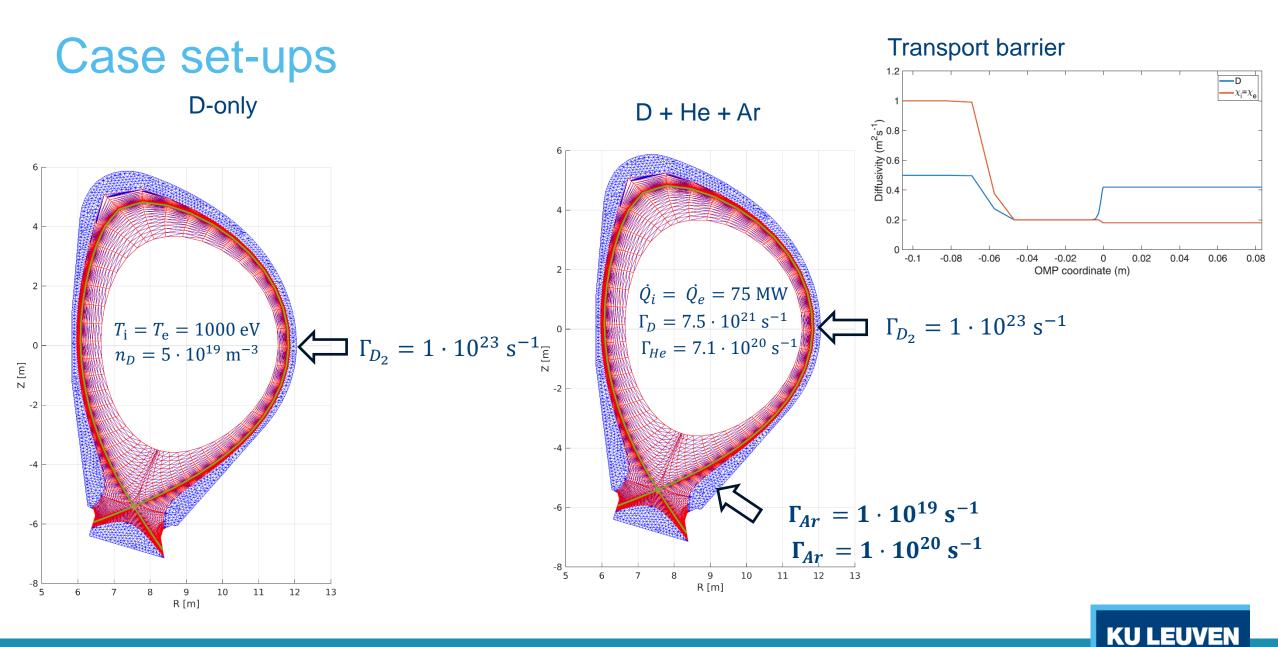


Towards accurate and efficient DEMO simulations in SOLPS

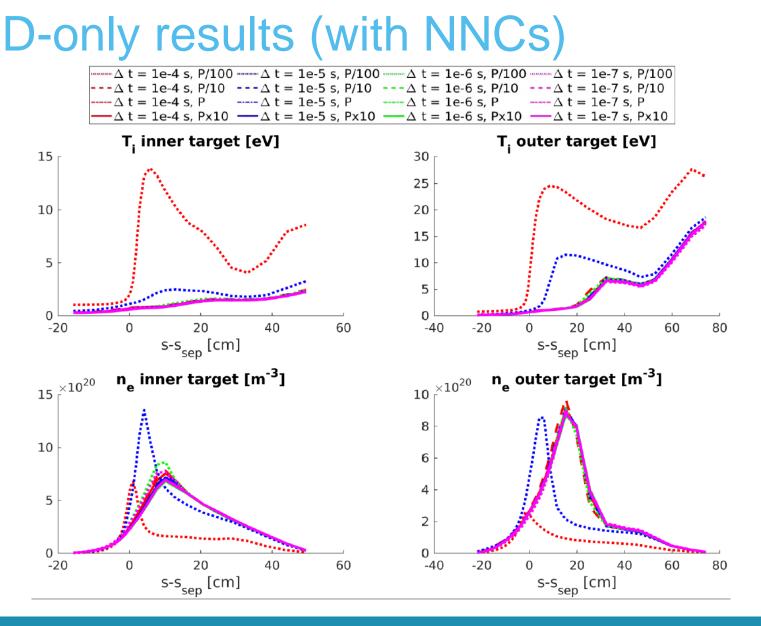
- Goal: acceptable numerical errors for DEMO SOLPS cases (e.g. < 10%) as cheaply as possible
- Start from error analysis framework of PhD K. Ghoos



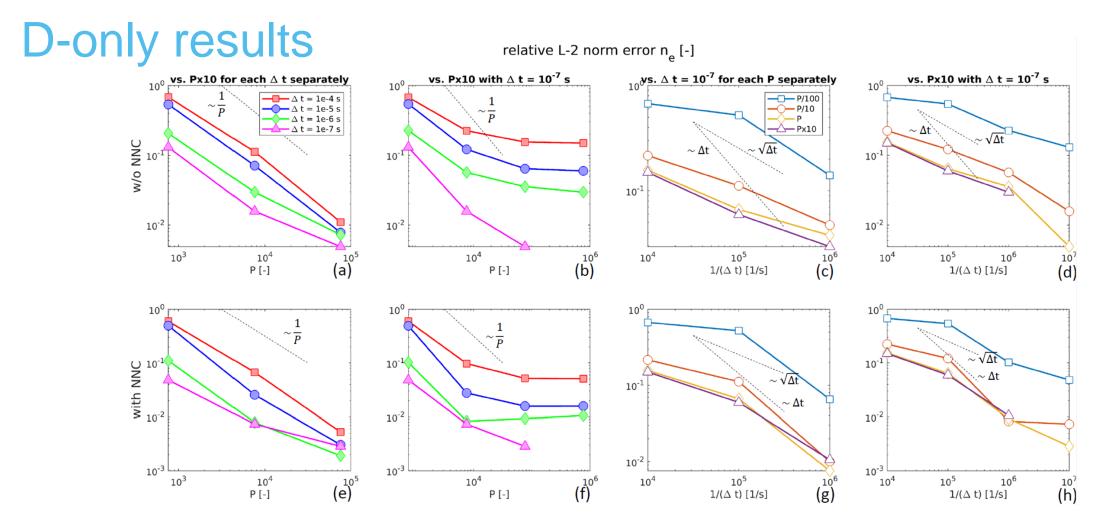
- But, some unanswered questions:
 - Q1: effect of Δt on bias? ([M. Baeten et al., CtPP, 2018]: statistical error ~ $\sqrt{\Delta t}$ (0D+1D cases))
 - Q2: effect of n-n collisions (NNC) on error scaling?
 - Q3: effect of impurities?



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Only 1^e-4s and 1^e-5s for P/100 lead to a qualitatively wrong solution



 \rightarrow no noticeable effect of NNCs on convergence behavior

 \rightarrow bias decreases monotinically with Δt

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Prelim. conclusions D + He + Ar cases

- Multi-species cases appear to have <u>much larger bias</u> than D-only case
- Why?
 - Purely case dependent? E.g. much higher core power? higher T's OT?
 - Bad statistics from impurity neutrals themselves?
 - Combination of both?

Conclusions error analysis

- Error reduction w.r.t. P and Δt does not change significantly with NNCs
- Decrease of bias for smaller Δt demonstrated in SOLPS-ITER
 - \circ useful knowledge if Δt is limited by plasma side (e.g. drifts)
- Bias error seems to be much higher for (high-power?) multi-species cases
 - Similar observations in literature
 - Need to better understand why
 - Optimal strategies for D-only may no longer be optimal



 \rightarrow back to 1D or slab cases? DEMO cases much too slow for efficient research



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FHK modeling based on AFN

- AFN models and hybrid methods (in particular, SpH) reached high level of maturity
 - Including effects of drifts, molecules, n-n collisions,...
 - Coupling with impurity models
- Integration in various codes
 - Default models in SOLPS-ITER extended grids version. Relevant input files automatically generated.
 - Basic AFN models implemented in various European turbulence codes (link TSVV3), incl. SOLEDGE3X, GRILLIX

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- Already applied to simulate multiple machines, incl. TCV, AUG, JET, ITER, DEMO (link WP TE, WP DES)
- Next steps
 - Validation n-n collision effects with kinetic simulations
 - Extension to 'hydrodynamic' closure model for void regions w/o plasma
 - Fluid model for molecules?

FHK modeling based on KDMC

- Basic particle tracing scheme implemented in EIRON
- Eiron updated to use BKG operator
 - KDMC depends on certain assumptions of the physics to work
 - EIRON used simple rotation after collision, which violated those assumptions
 - Initial results look ok, but more tests needed
- Estimation of QoIs through fluid model based on particle positions
 - Error analysis of 1D homogeneous background is now more rigorous.
- Next steps
 - Extension to heterogeneous background
 - Validation source estimators
 - Integration with multi-level scheme

AD, UQ

- Derivatives based on AD (TAPENADE) in forward mode available
 - EIRENE standalone
- UQ demonstration: applied to study sensitivity of QoIs to uncertainty in reaction rate coefficients
 - Accurate in low/medium recycling regimes
 - Problem of diverging derivatives in high recycling regimes
- Next steps
 - Analysis of derivative problems in high recycling
 - Analysis of impact estimators on accuracy of derivatives
 - Implementation adjoint AD with TAPENADE
 - Adjoint differentiation of couple B2.5-EIRENE solver
- Potential for building implicit coupling to plasma codes (B2.5, SOLEDGE3X) and providing sensitivities (ERO2.0)

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