

New properties of the collisional sheath

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BIT1 related projects ran under IFERC-CSC

- SOL modelling; studying kinetic effects in the SOL, divertor power and particle loads, impurity erosion, ets
- plasma sheath \succ Collisional plasma sheath modelling T [eV] 600 55 550 50 ITER 500 10²¹ 45 450 40 400 JET n_e [m⁻³] 35 350 10²⁰ t [µs] 30 300 25 250 20 200 COMPASS 10¹⁹ 15 150 10 100 5 50 10¹⁸ 10⁻³ 10⁻² 10⁰ 10^{-1} 10¹ 10 20 30 40 50 60 70 x [m] s [m]

Density and temperature profiles in the stationary and ELM-ing SOLs.





✓ Motivation

- ✓ Discussion of obtained results
- \checkmark Short description of the BIT1 (3) codes

✓ Conclusions

✓ On our experiance of running jobs under IFREC-CSC



What can be fundamentally new in plasma sheath model?



Plasma velocity and density profiles in the sheath obtained from PIC similations [Chodura PF 1982, Tskhakaya CPP 2012]



The scaling of the plasma sheath

classical plasma sheath

$$h \sim 10\mu \ll \lambda_D \sim \sqrt{T_e / n_e} \ll \rho_i \sim \sqrt{T_i m_i} / B \ll l_{mfp} \sim T^2 / n_e$$



What happens when this scaling is not valid?



Sheath collisionality





Motivation



Simulation parameters: R= 0 - 1, Z_{eff} = 1 - 1.5, θ = 1.5° - 6°

Modelling of divertor plasmas

- $\checkmark\,$ Different densities, with and without neutrals and molecules
- ✓ Number of simulated cells: 3x10⁵ 10⁶
- ✓ CPU time: 10⁵ 5x10⁶

Mach number

De-magnetization of plasma

Main results

[Tskhakaya EPS 2021]

Electron VDF at the JET ID

[Tskhakaya JNM 2017]

Numerical "experiments"

BIT1: electrostatic PIC MC code

Physics

- ✓ Electrons, main and impurity ions, neutrals (1D3V)
- ✓ Nonlinear particle interactions: $m \rightarrow n$ collisions
- ✓ Plasma-surface interaction, linear model

Numerics

- ✓ Massively parallel
- ✓ Unique Field solvers
- ✓ Optimized memory management

"Natural sorting" used in BIT1

Particles curry the cell index

- Neighboring particles in real space are neighbors in the computer memory: cache-hit increases. Parallelization is straightforward.
- ✓ Particle trajectories are calculated with the same accuracy at each point:

$$X_n = i \times \Delta x + x_n, \quad x_n < \Delta x$$
 all operations are performed on x_n

✓ Cells are statistically independent: all collision probabilities are calculated separately. Collision partners easy to find.

- ➤ Large set of divertor plasma simulations has been performed (~20 M CH)
- New features of the high density, high collisional plasma sheath have been identified
 - i. **subsonic** plasma flow, **position** of the SE has to be **re-defined**

ii. Heat to the wall (divertor plates) curried by **neutrals** (and non-Maxwellian **hot electrons**)

- These properties are the consequence of the common action of Coulomb collisions and ion-neutral friction
- Future plans: DEMO relevant plasma sheath modelling higher plasma density and simulation complexity (10⁷ grid cell in 1D)

- \checkmark One of the **most stable** supercomputers we accessed
- ✓ Very **responsive user support** service
- ✓ **Our wish**: to have debugging tools **simpler than Totalview**

Totalview – professional software requiring significant learning time, easy to forget if you use it once per >6 months (stable codes), requires graphical interface

90% of possible "bugs" for particle codes are related to improper memory allocation, which is not easy to fix.

E.g. in BIT3: > 2x26x(6+8) + 8x2 + 2 = 746 routines related to particle array reallocation (Particle send/receive, inelastic collisions, volumetric particle sources)